

SIBGRAPI'18

31st Conference on Graphics, Patterns and Images

Synthesizing Periodic Tilings of Regular Polygons

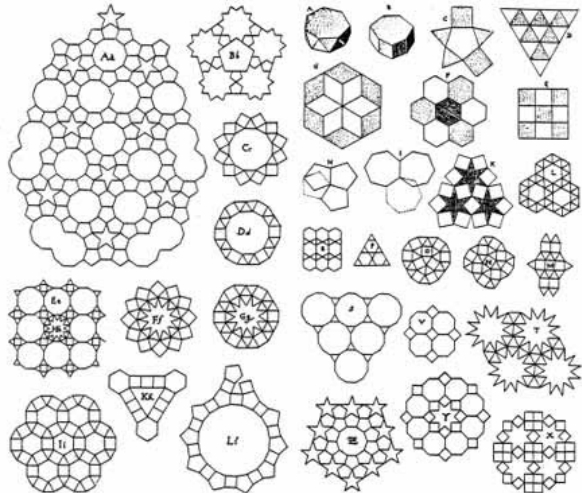
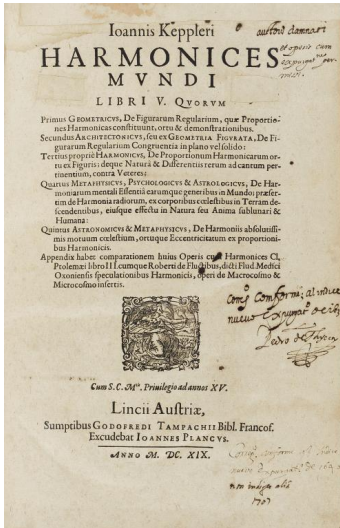
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Luiz Henrique de Figueiredo · IMPA

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Motivation: tile the plane with regular polygons

Kepler (1619)



Rigidity: only 15 vertex neighborhoods



G $3-12-12$

H $4-6-12$

J $4-8-8$



K $6-6-6$



L $3-3-4-12$



M $3-4-3-12$



N $3-4-4-6$



P $3-4-6-4$



Q $3-3-6-6$



R $3-6-3-6$



S $4-4-4-4$



T $3-3-3-4-4$



U $3-3-4-3-4$

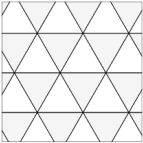


V $3-3-3-3-6$

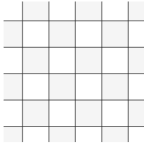


W $3-3-3-3-3-3$

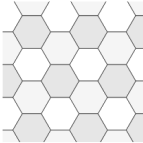
Rigidity: only 11 tilings are 1-regular



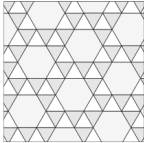
(3⁶)



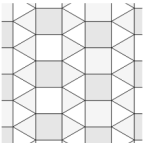
(4⁴)



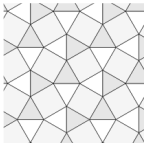
(6³)



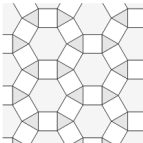
(3⁴.6)



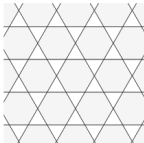
(3³.4²)



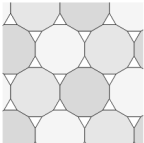
(3².4.3.4)



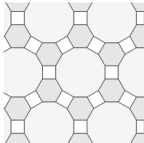
(3.4.6.4)



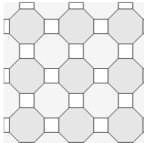
(3.6.3.6)



(3.12²)

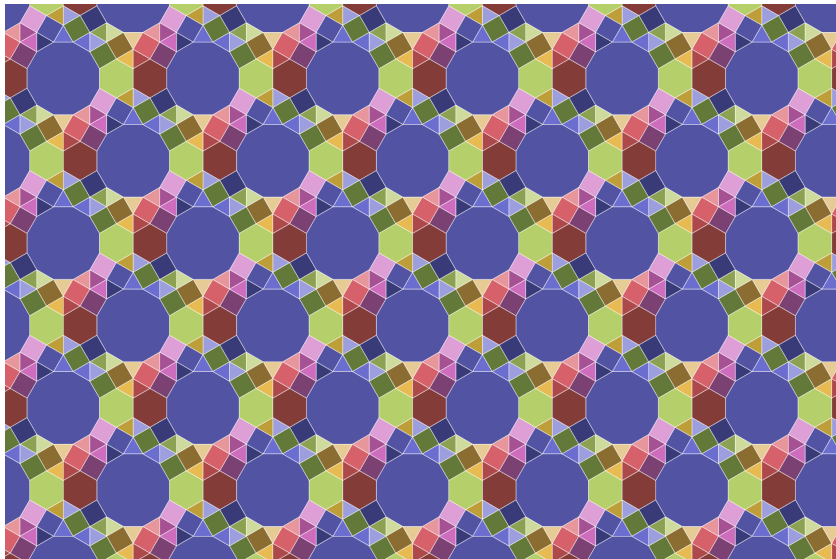


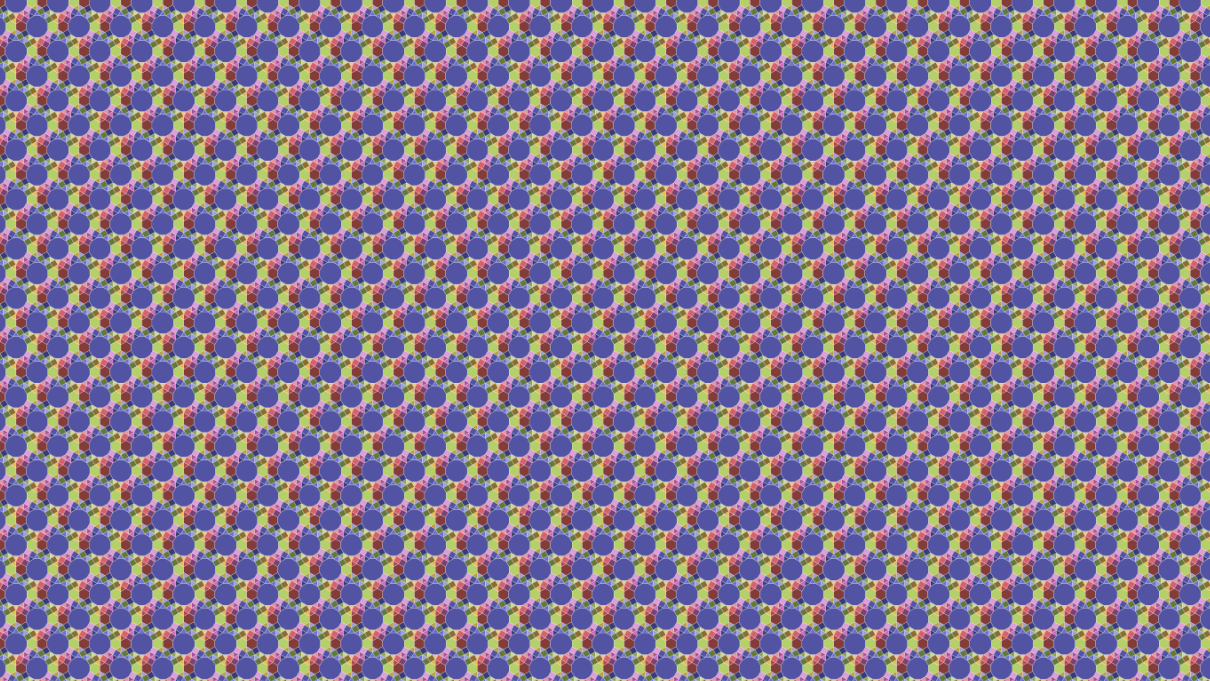
(4.6.12)



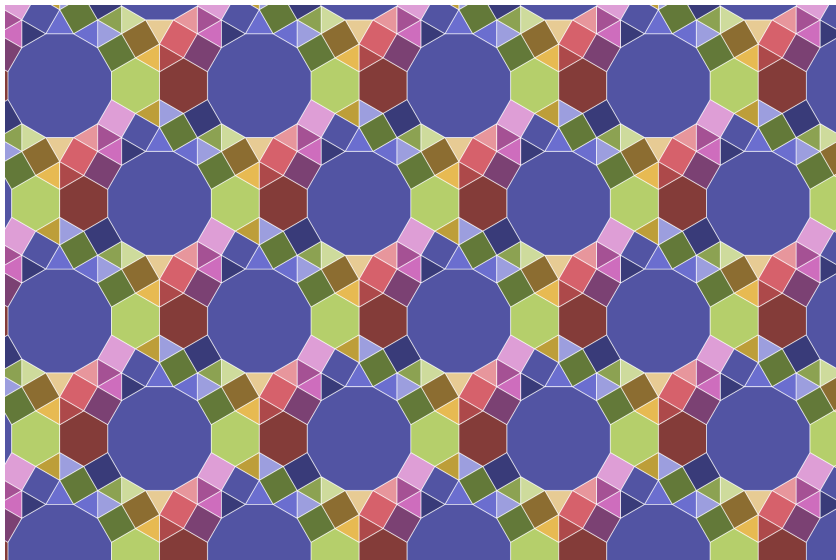
(4.8.8)

Goal: represent and synthesize complex k -regular tilings



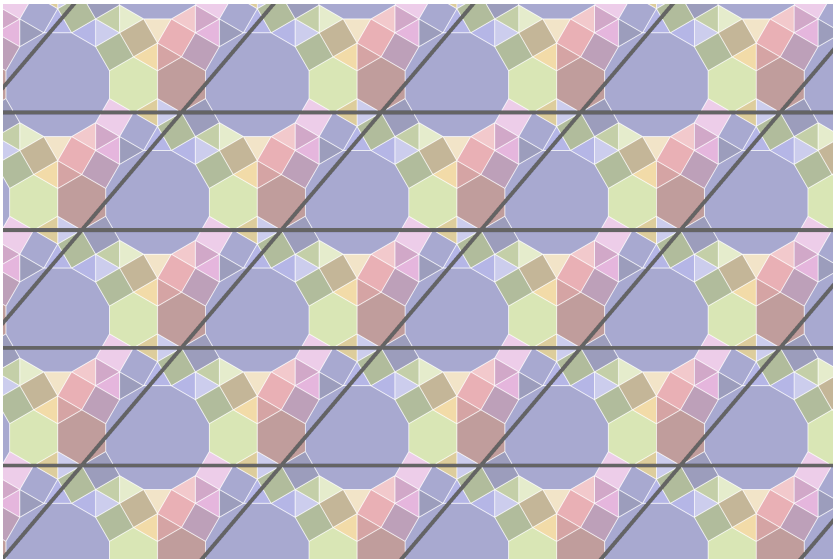


Understanding tilings: many symmetries

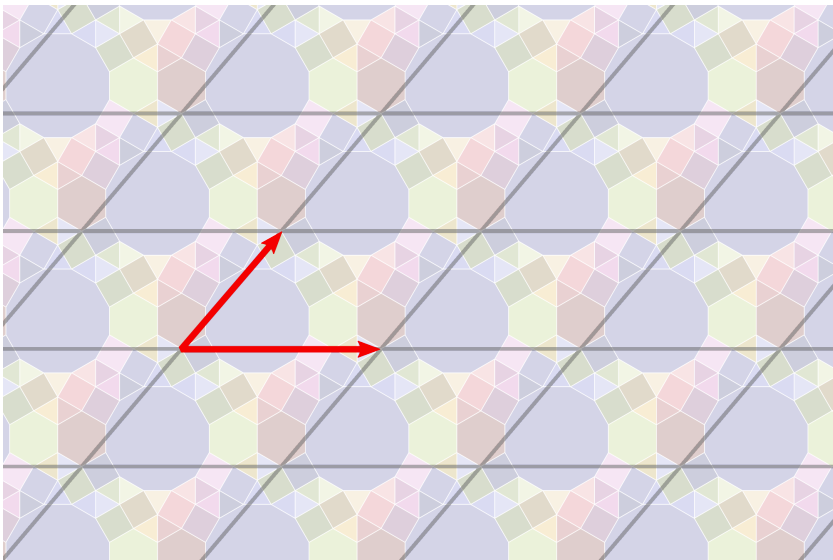


Understanding tilings: translation symmetries

(group $p1$)

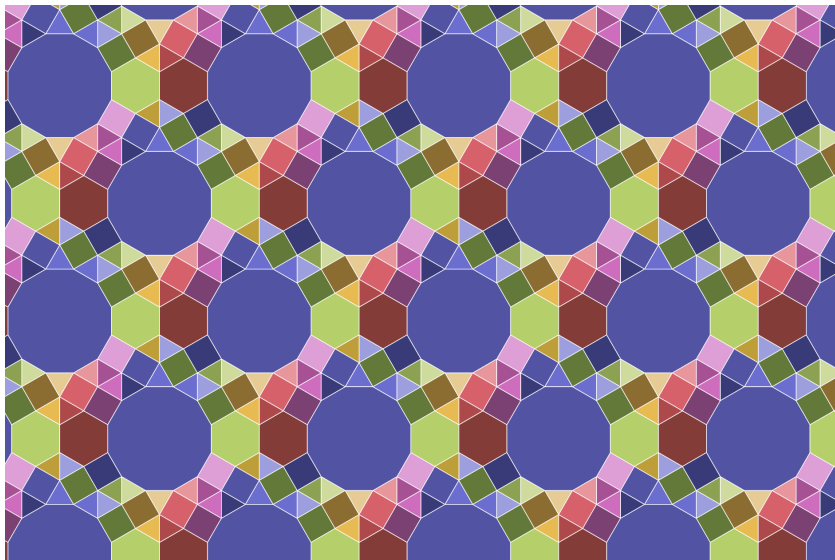


Understanding tilings: fundamental domain



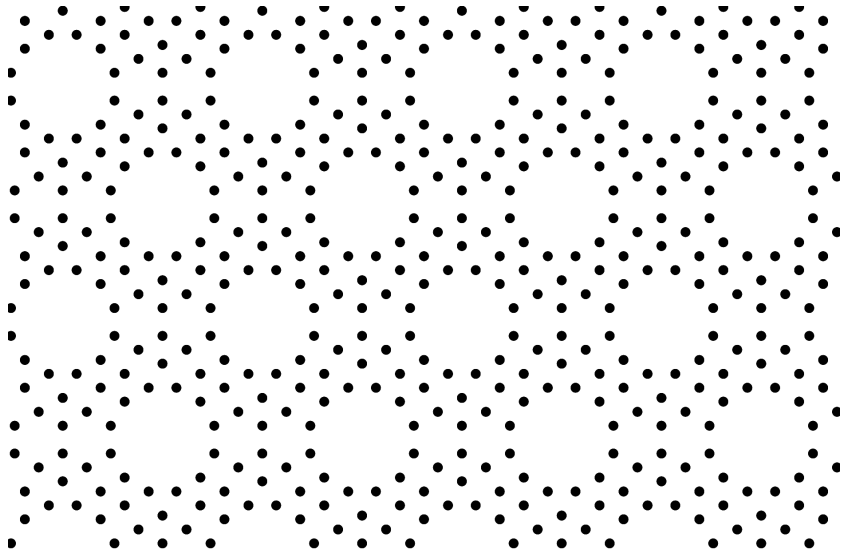
Regular systems of points

Hilbert & Cohn-Vossen (1952)

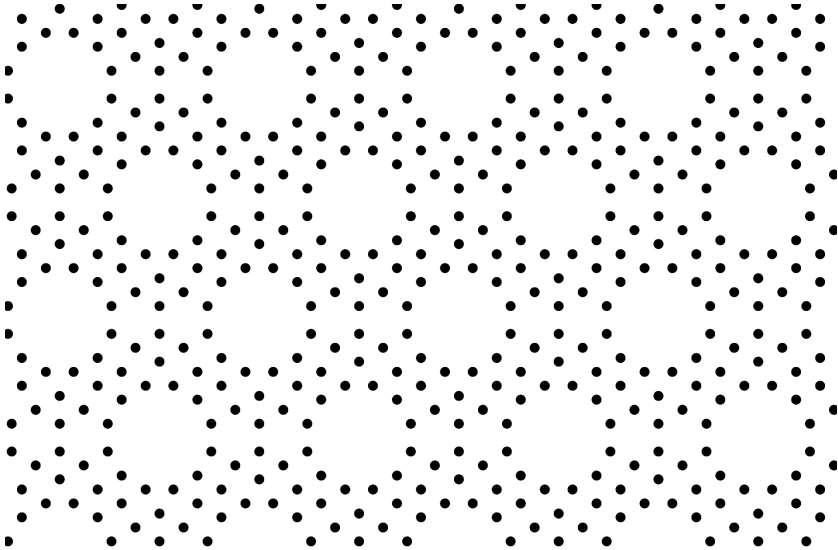


Regular systems of points

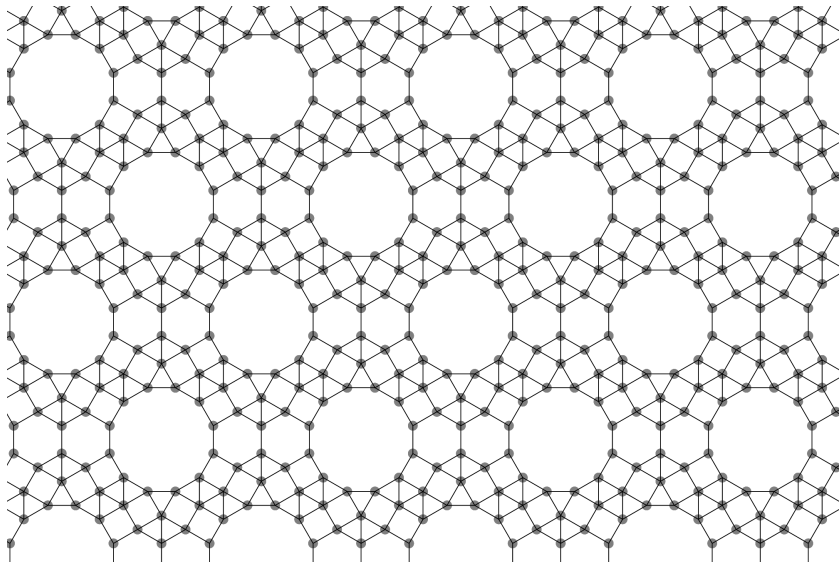
Hilbert & Cohn-Vossen (1952)



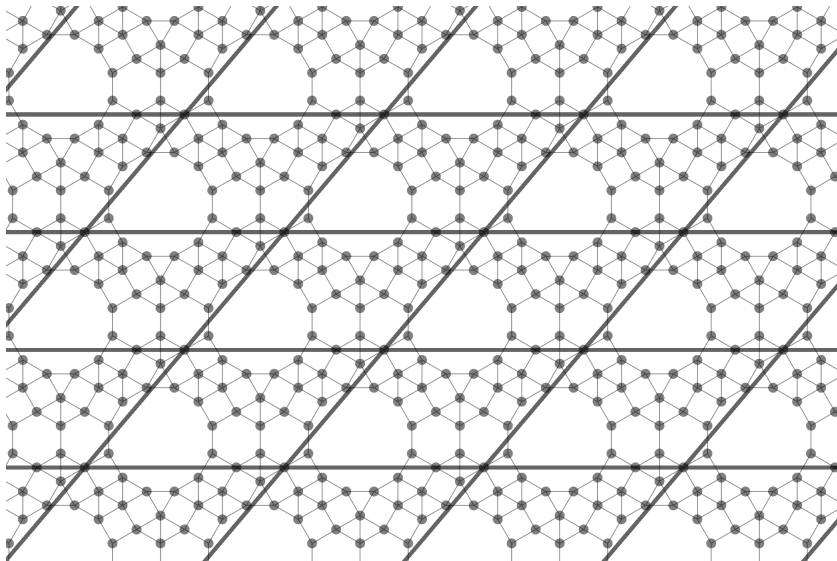
Reconstruct tiling from vertices



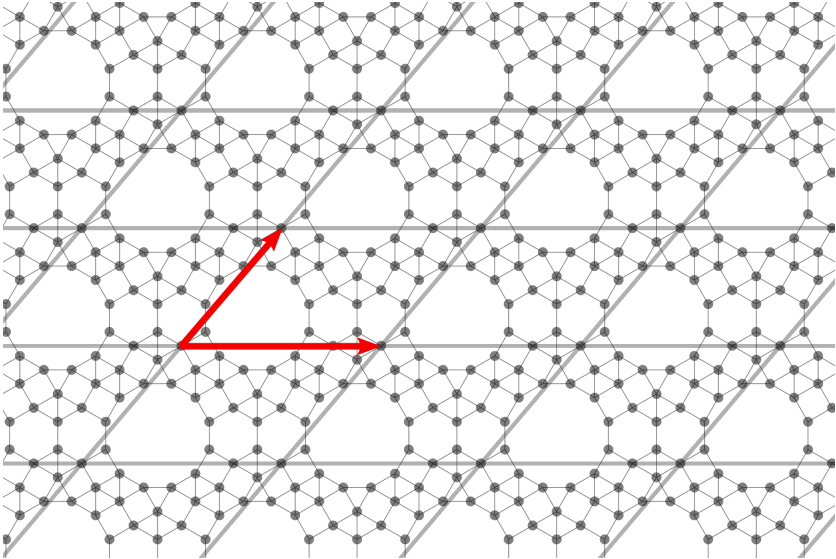
Reconstruct tiling from vertices: edges



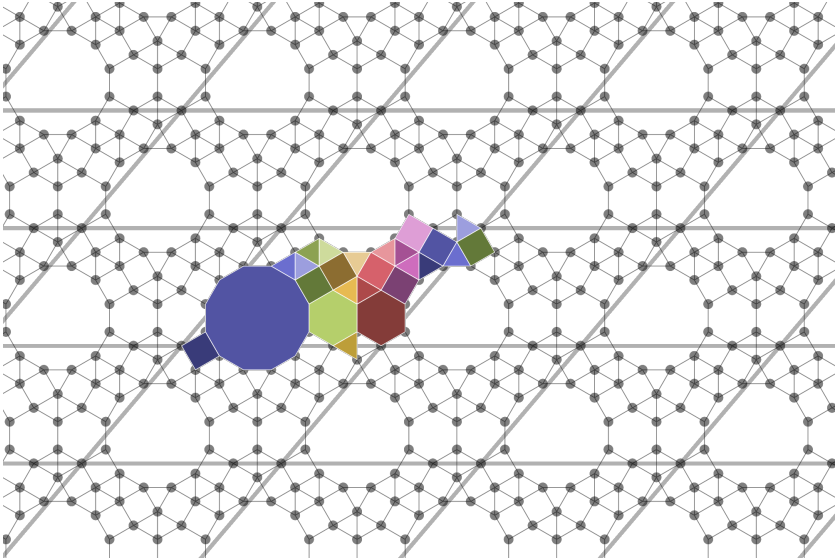
Reconstruct tiling from vertices: translation grid



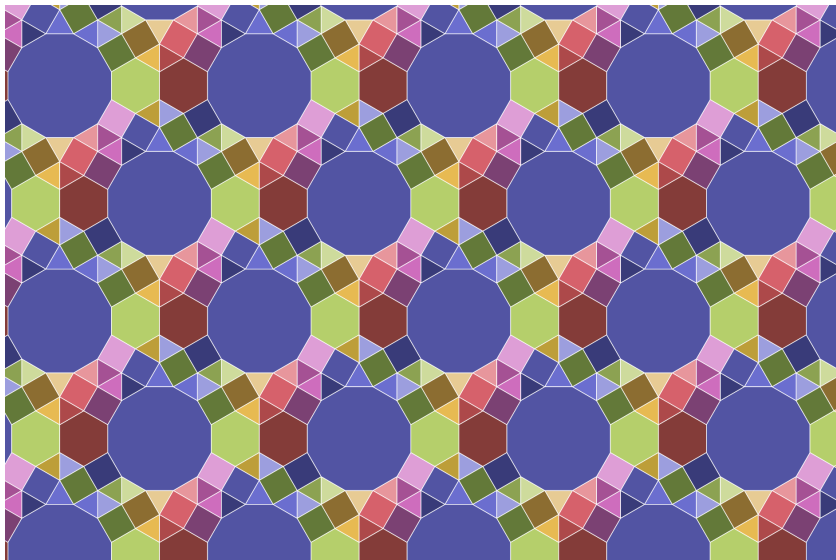
Reconstruct tiling from vertices: fundamental domain



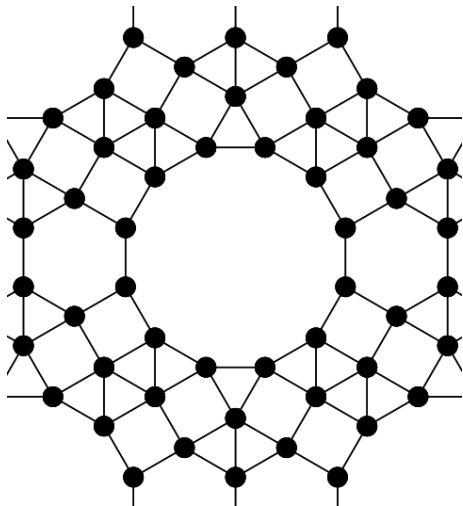
Reconstruct tiling from vertices: patch



Reconstruct tiling from vertices: full tiling



Edges aligned to a few basic directions

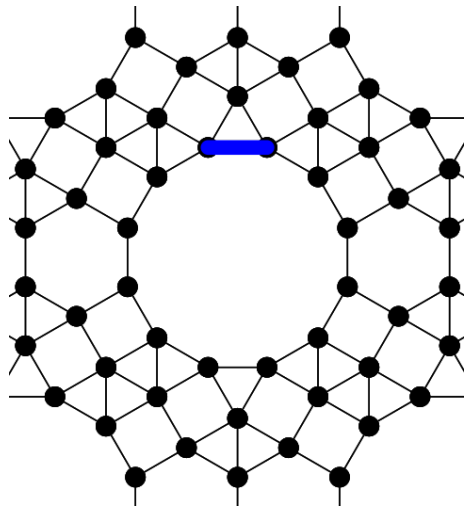


roots of unity

$$\pm\omega_n, \pm\bar{\omega}_n \quad \omega_n = e^{\frac{2\pi i}{n}}$$

$$n \in \{1, 2, 3, 4, 6, 8, 12\}$$

Edges aligned to a few basic directions



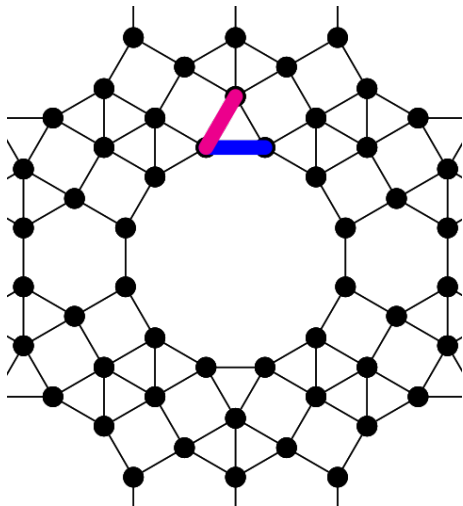
roots of unity

$$\pm\omega_n, \pm\bar{\omega}_n \quad \omega_n = e^{\frac{2\pi i}{n}}$$

$$n \in \{1, 2, 3, 4, 6, 8, 12\}$$

● $+\omega_1$

Edges aligned to a few basic directions



roots of unity

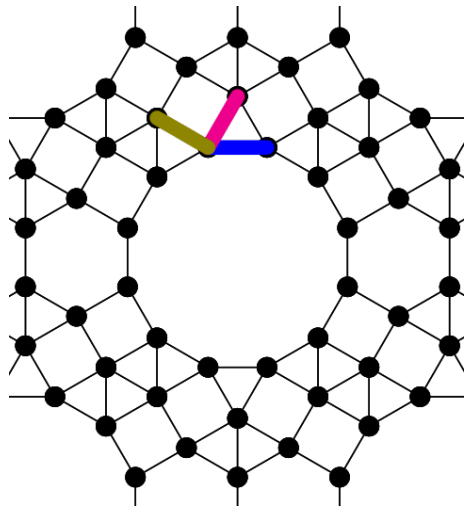
$$\pm\omega_n, \pm\bar{\omega}_n \quad \omega_n = e^{\frac{2\pi i}{n}}$$

$$n \in \{1, 2, 3, 4, 6, 8, 12\}$$

● $+\omega_1$

● $+\omega_6$

Edges aligned to a few basic directions



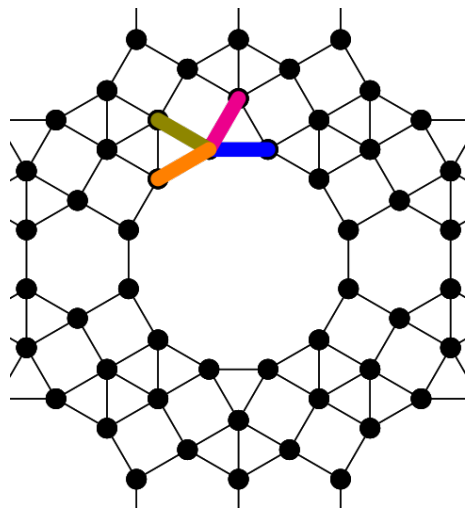
roots of unity

$$\pm\omega_n, \pm\bar{\omega}_n \quad \omega_n = e^{\frac{2\pi i}{n}}$$

$$n \in \{1, 2, 3, 4, 6, 8, 12\}$$

- $+\omega_1$
- $+\omega_6$
- $-\bar{\omega}_{12}$

Edges aligned to a few basic directions



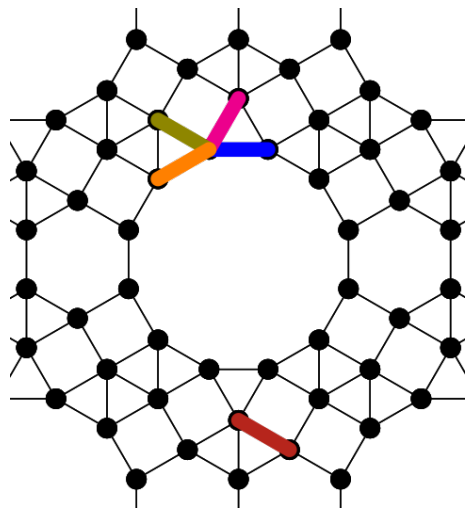
roots of unity

$$\pm\omega_n, \pm\bar{\omega}_n \quad \omega_n = e^{\frac{2\pi i}{n}}$$

$$n \in \{1, 2, 3, 4, 6, 8, 12\}$$

- $+\omega_1$
- $+\omega_6$
- $-\bar{\omega}_{12}$
- $-\omega_{12}$

Edges aligned to a few basic directions



roots of unity

$$\pm\omega_n, \pm\bar{\omega}_n \quad \omega_n = e^{\frac{2\pi i}{n}}$$

$$n \in \{1, 2, 3, 4, 6, 8, 12\}$$

● $+\omega_1$

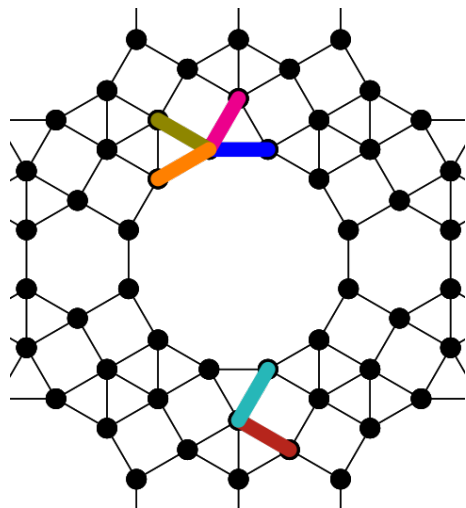
● $+\bar{\omega}_{12}$

● $+\omega_6$

● $-\bar{\omega}_{12}$

● $-\omega_{12}$

Edges aligned to a few basic directions



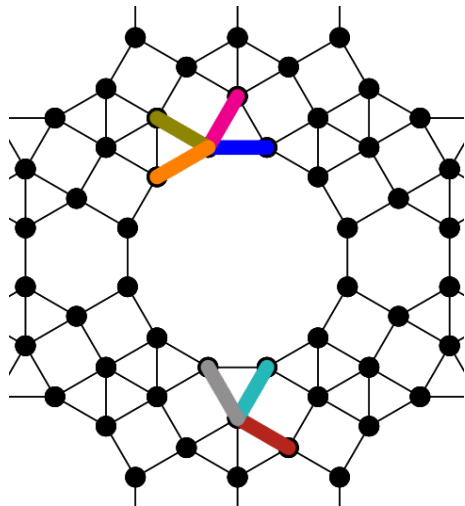
roots of unity

$$\pm\omega_n, \pm\bar{\omega}_n \quad \omega_n = e^{\frac{2\pi i}{n}}$$

$$n \in \{1, 2, 3, 4, 6, 8, 12\}$$

- | | | | |
|--|----------------------|---|----------------------|
|  | $+\omega_1$ |  | $+\bar{\omega}_{12}$ |
|  | $+\omega_6$ |  | $+\omega_6$ |
|  | $-\bar{\omega}_{12}$ | | |
|  | $-\omega_{12}$ | | |

Edges aligned to a few basic directions



roots of unity

$$\pm\omega_n, \pm\bar{\omega}_n \quad \omega_n = e^{\frac{2\pi i}{n}}$$

$$n \in \{1, 2, 3, 4, 6, 8, 12\}$$

● $+\omega_1$

● $+\omega_6$

● $-\bar{\omega}_{12}$

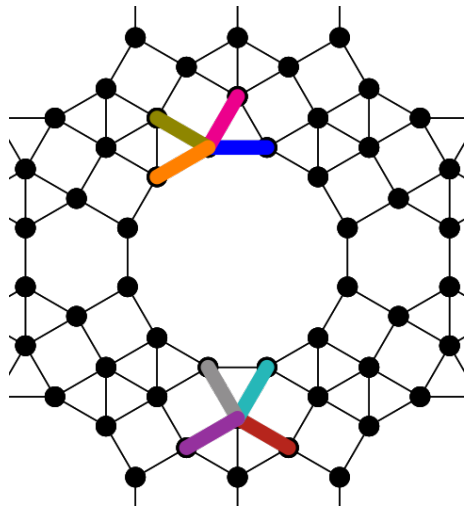
● $-\omega_{12}$

● $+\bar{\omega}_{12}$

● $+\omega_6$

● $-\bar{\omega}_6$

Edges aligned to a few basic directions



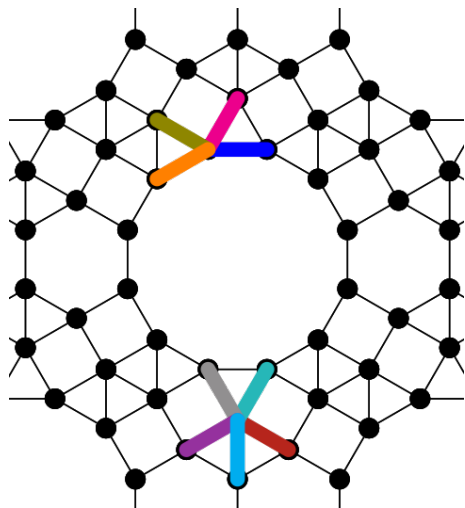
roots of unity

$$\pm\omega_n, \pm\bar{\omega}_n \quad \omega_n = e^{\frac{2\pi i}{n}}$$

$$n \in \{1, 2, 3, 4, 6, 8, 12\}$$

	$+\omega_1$		$+\bar{\omega}_{12}$
	$+\omega_6$		$+\omega_6$
	$-\bar{\omega}_{12}$		$-\bar{\omega}_6$
	$-\omega_{12}$		$-\omega_{12}$

Edges aligned to a few basic directions



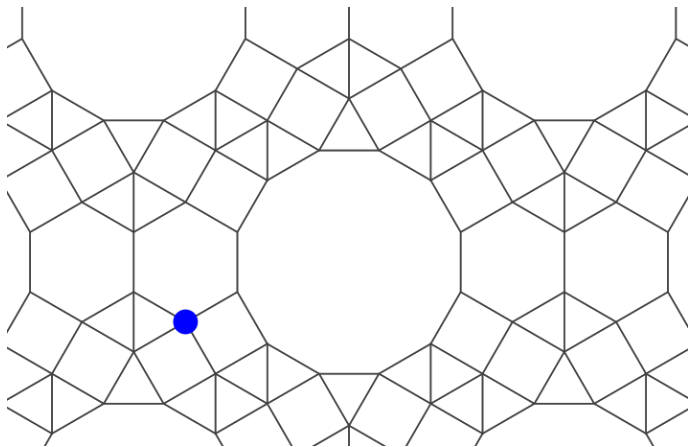
roots of unity

$$\pm\omega_n, \pm\bar{\omega}_n \quad \omega_n = e^{\frac{2\pi i}{n}}$$

$$n \in \{1, 2, 3, 4, 6, 8, 12\}$$

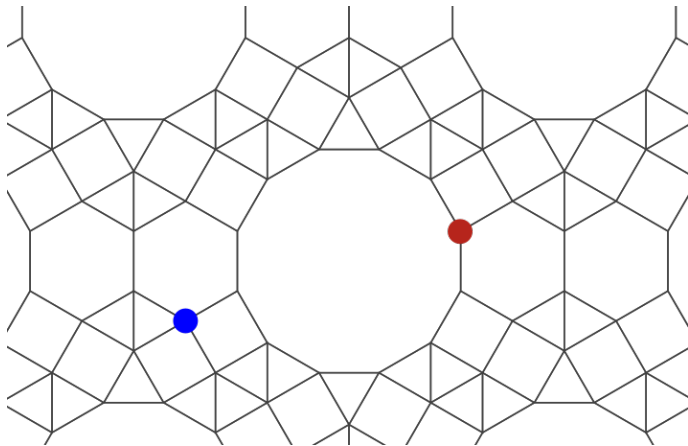
- | | |
|---|--|
|  $+\omega_1$ |  $+\bar{\omega}_{12}$ |
|  $+\omega_6$ |  $+\omega_6$ |
|  $-\bar{\omega}_{12}$ |  $-\bar{\omega}_6$ |
|  $-\omega_{12}$ |  $-\omega_{12}$ |
| |  $-\omega_4$ |

Vertices as integer linear combinations of basic directions



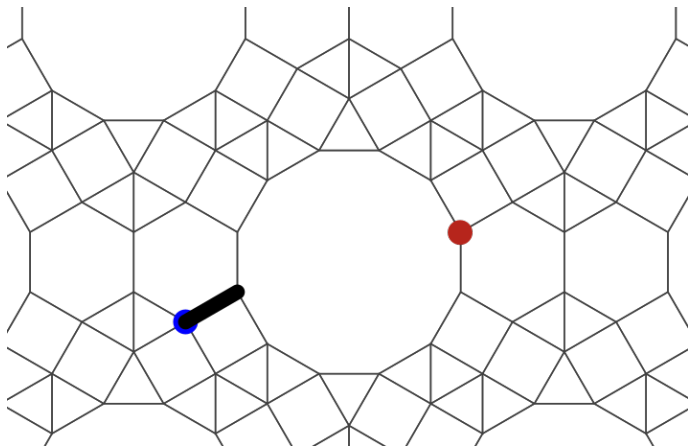
O

Vertices as integer linear combinations of basic directions



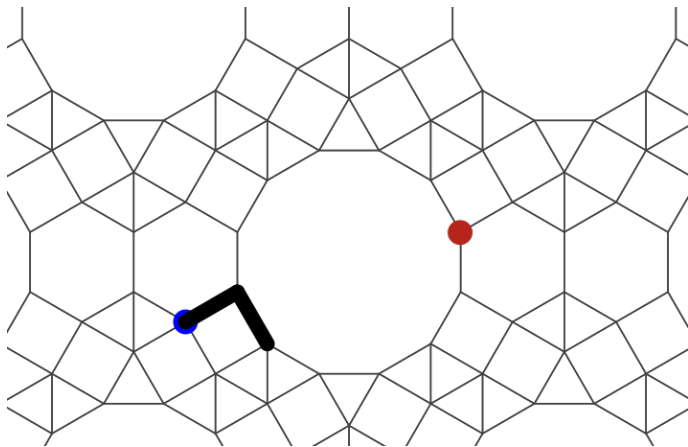
O

Vertices as integer linear combinations of basic directions



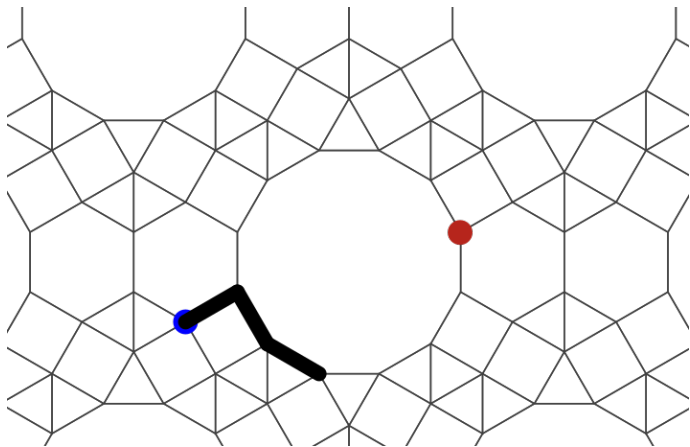
$$O + \omega_{12}$$

Vertices as integer linear combinations of basic directions



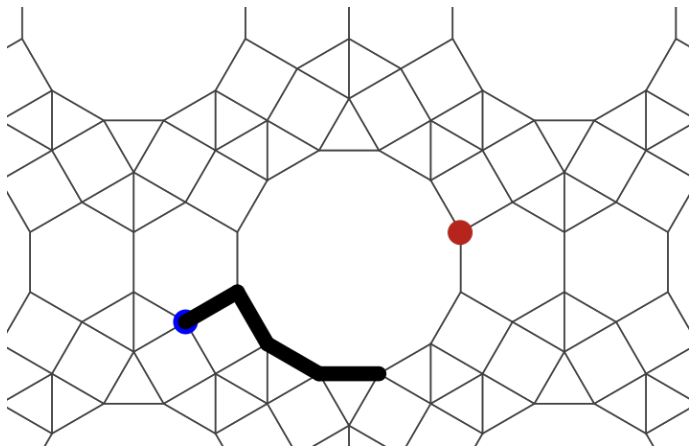
$$O + \omega_{12} + \bar{\omega}_6$$

Vertices as integer linear combinations of basic directions



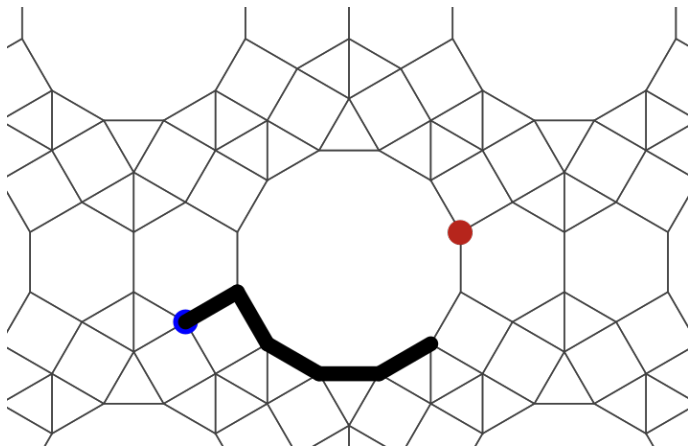
$$O + \omega_{12} + \bar{\omega}_6 + \bar{\omega}_{12}$$

Vertices as integer linear combinations of basic directions



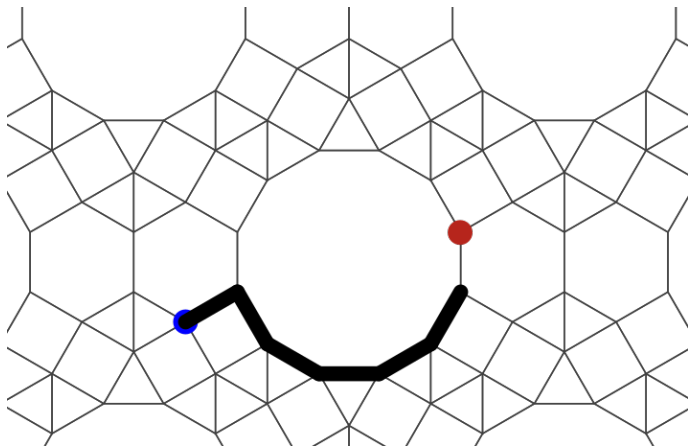
$$O + \omega_{12} + \bar{\omega}_6 + \bar{\omega}_{12} + \omega_1$$

Vertices as integer linear combinations of basic directions



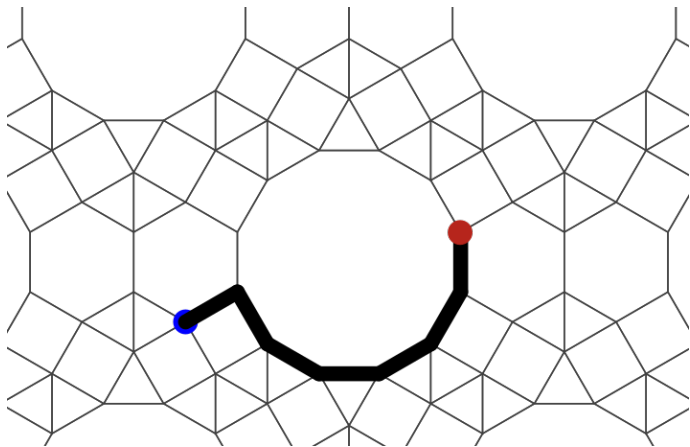
$$O + \omega_{12} + \bar{\omega}_6 + \bar{\omega}_{12} + \omega_1 + \omega_{12}$$

Vertices as integer linear combinations of basic directions



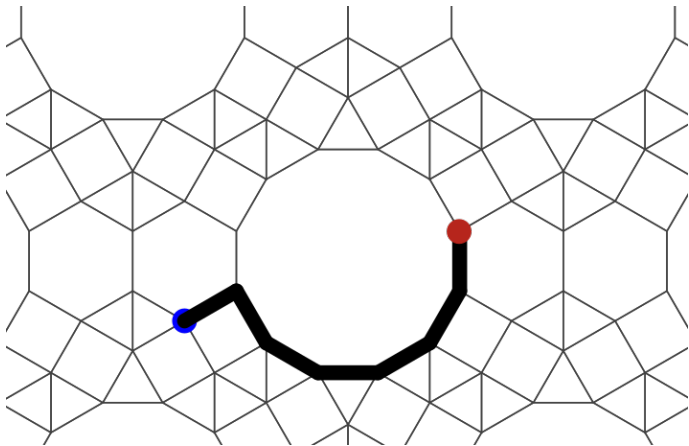
$$O + \omega_{12} + \bar{\omega}_6 + \bar{\omega}_{12} + \omega_1 + \omega_{12} + \omega_6$$

Vertices as integer linear combinations of basic directions



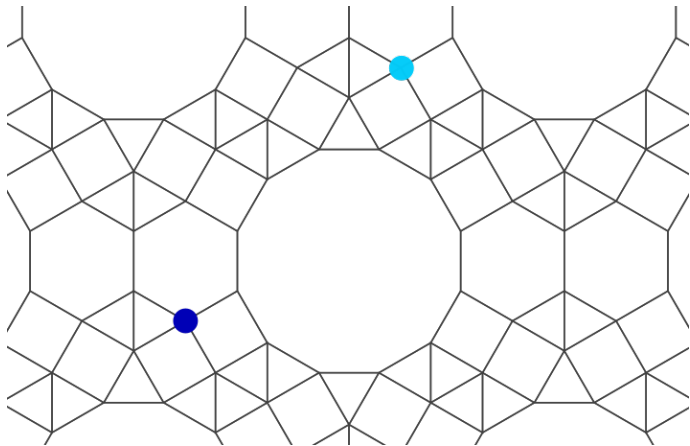
$$O + \omega_{12} + \bar{\omega}_6 + \bar{\omega}_{12} + \omega_1 + \omega_{12} + \omega_6 + \omega_4$$

Vertices as integer linear combinations of basic directions



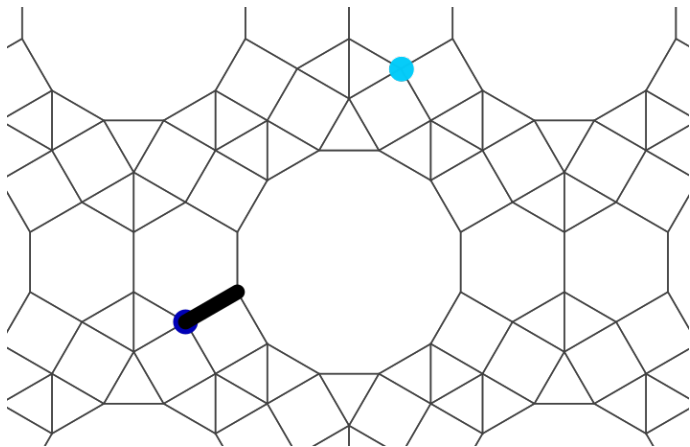
$$O + \omega_{12} + \bar{\omega}_6 + \bar{\omega}_{12} + \omega_1 + \omega_{12} + \omega_6 + \omega_4 = v$$

Translations as integer linear combinations of basic directions



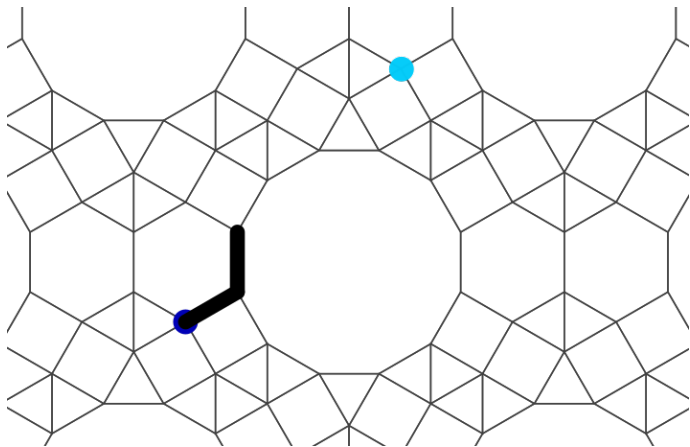
O

Translations as integer linear combinations of basic directions



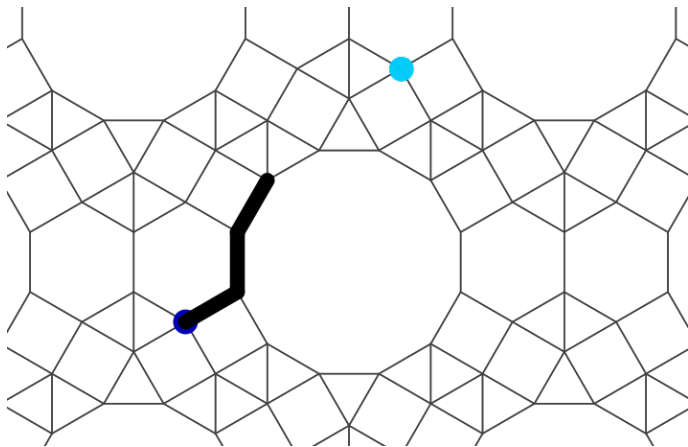
$$O + \omega_{12}$$

Translations as integer linear combinations of basic directions



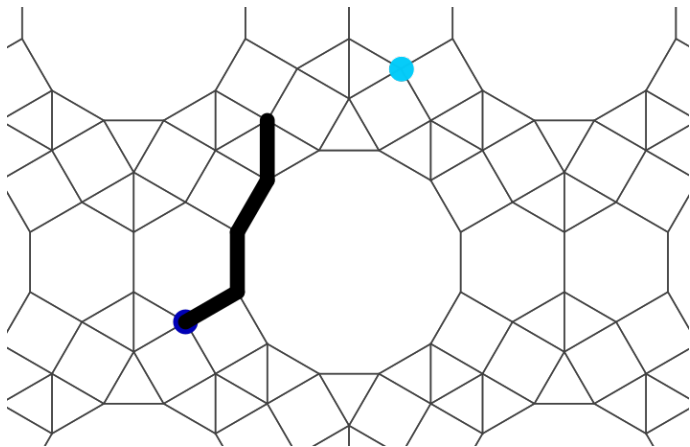
$$O + \omega_{12} + \omega_4$$

Translations as integer linear combinations of basic directions



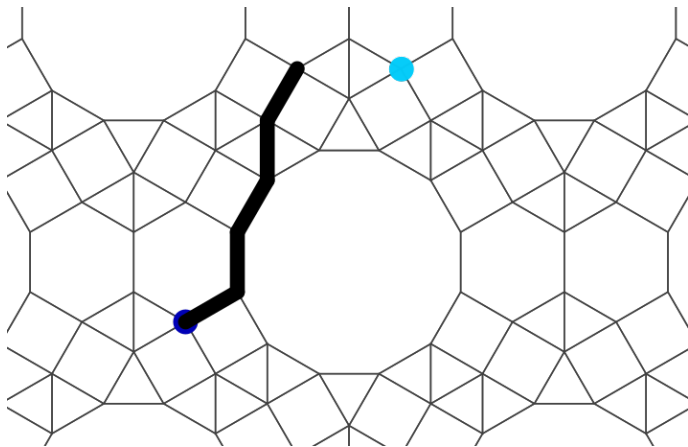
$$O + \omega_{12} + \omega_4 + \omega_6$$

Translations as integer linear combinations of basic directions



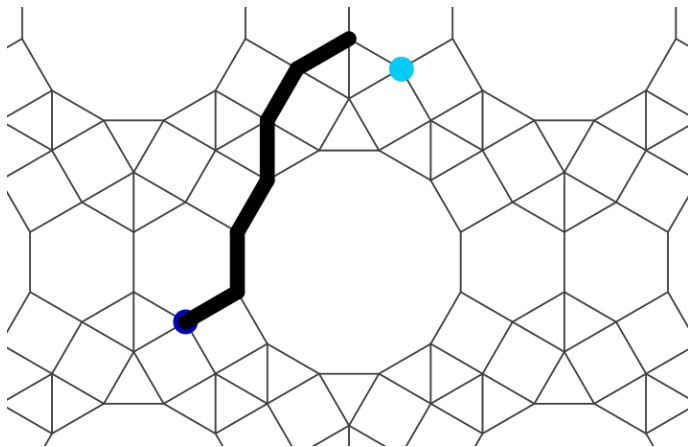
$$O + \omega_{12} + \omega_4 + \omega_6 + \omega_4$$

Translations as integer linear combinations of basic directions



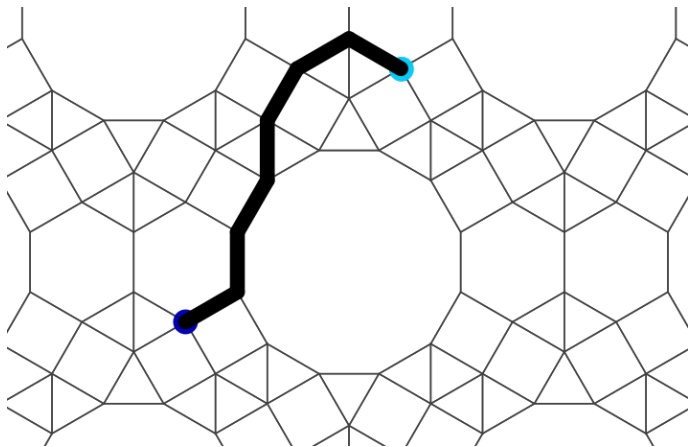
$$O + \omega_{12} + \omega_4 + \omega_6 + \omega_4 + \omega_6$$

Translations as integer linear combinations of basic directions



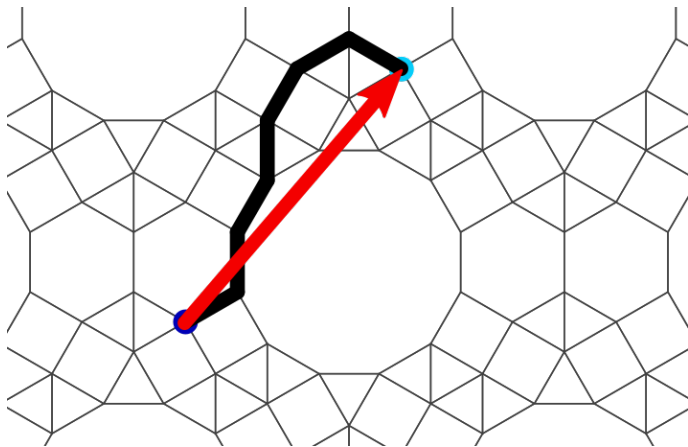
$$O + \omega_{12} + \omega_4 + \omega_6 + \omega_4 + \omega_6 + \omega_{12}$$

Translations as integer linear combinations of basic directions



$$O + \omega_{12} + \omega_4 + \omega_6 + \omega_4 + \omega_6 + \omega_{12} + \bar{\omega}_{12}$$

Translations as integer linear combinations of basic directions



$$O + \omega_{12} + \omega_4 + \omega_6 + \omega_4 + \omega_6 + \omega_{12} + \bar{\omega}_{12} = t$$

Tiling symbols

Each tiling is represented by:

- ▶ **two translation vectors**
define the fundamental region
- ▶ **set of seeds**
vertices inside fundamental region
- ▶ translation vectors and seeds expressed as **integer linear combinations** of **basic directions**

Basic directions can be simplified:

$$\omega_2 + \omega_1 = 0$$

$$\omega_3 + \bar{\omega}_6 = 0$$

$$\omega_2 + \omega_6 + \bar{\omega}_6 = 0$$

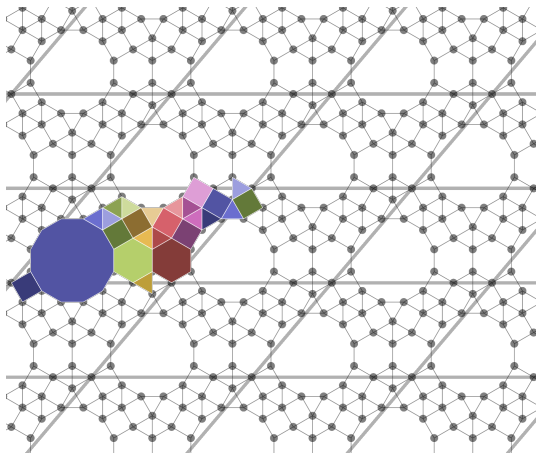
$$\omega_4 - \omega_{12} + \bar{\omega}_{12} = 0$$

$$\omega_1 = 1, \quad \omega_2 = -1, \quad \omega_4 = i$$

At most four basic directions needed

Unique representation

Tiling symbols



basic
directions

$$\Omega = \{\omega_1, \omega_4, \omega_6, \omega_{12}\}$$

translation
vectors

$$t_1 = [0, 1, 2, 3]$$

$$t_2 = [2, -3, 0, 6]$$

seeds

$$S_1 = [0, 0, 1, 2]$$

$$S_2 = [0, 0, 1, 3]$$

$$S_3 = [1, 0, 0, 1]$$

...

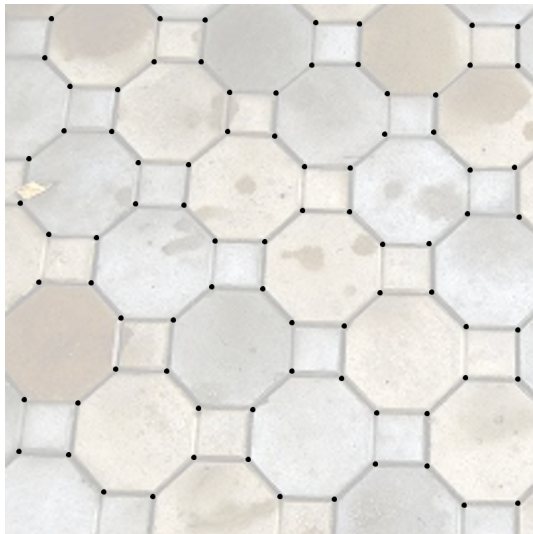
$$S_{24} = [2, 3, 1, 1]$$

Assisted acquisition from photographs



Assisted acquisition from photographs:

user selects vertices



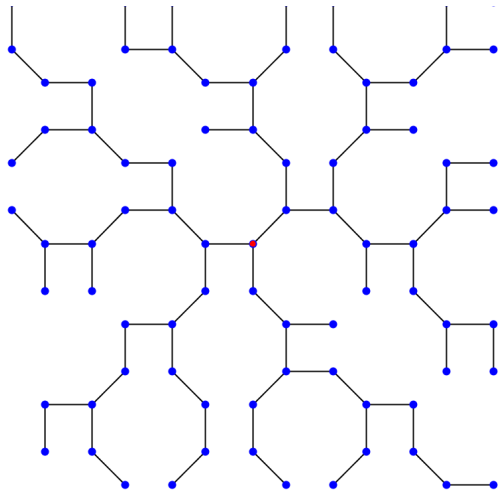
Assisted acquisition from photographs:

user selects vertices



Assisted acquisition from photographs:

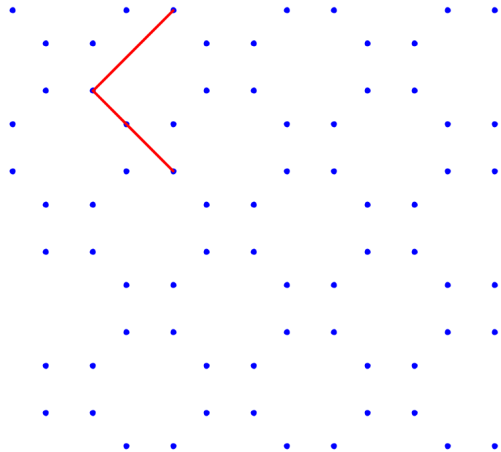
connect vertices with basic directions



$$\Omega = \{\omega_1, \omega_4, \omega_8, \bar{\omega}_8\}$$

Assisted acquisition from photographs:

find translations by maximizing overlap



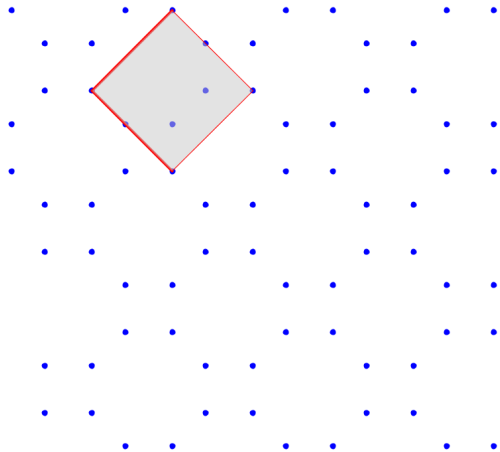
$$\Omega = \{\omega_1, \omega_4, \omega_8, \bar{\omega}_8\}$$

$$t_1 = [1, 1, 1, 0]$$

$$t_2 = [1, -1, 0, 1]$$

Assisted acquisition from photographs:

fundamental region



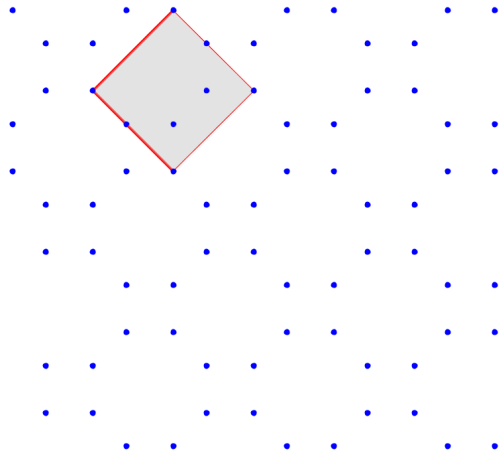
$$\Omega = \{\omega_1, \omega_4, \omega_8, \bar{\omega}_8\}$$

$$t_1 = [1, 1, 1, 0]$$

$$t_2 = [1, -1, 0, 1]$$

Assisted acquisition from photographs:

fundamental region



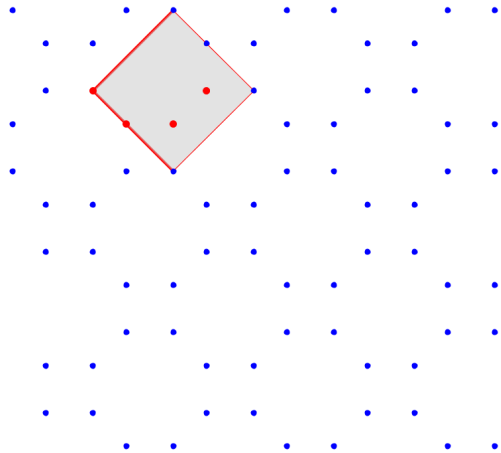
$$\Omega = \{\omega_1, \omega_4, \omega_8, \bar{\omega}_8\}$$

$$t_1 = [1, 1, 1, 0]$$

$$t_2 = [1, -1, 0, 1]$$

Assisted acquisition from photographs:

seeds



$$\Omega = \{\omega_1, \omega_4, \omega_8, \bar{\omega}_8\}$$

$$t_1 = [1, 1, 1, 0]$$

$$t_2 = [1, -1, 0, 1]$$

$$S_1 = [0, 0, 0, 0]$$

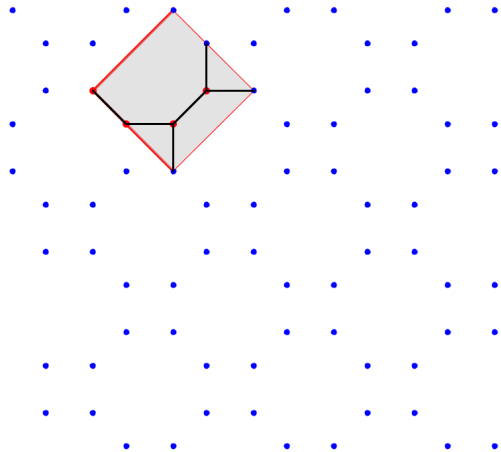
$$S_2 = [0, 0, 0, 1]$$

$$S_3 = [1, 0, 0, 1]$$

$$S_4 = [1, 0, 1, 1]$$

Assisted acquisition from photographs:

patch



$$\Omega = \{\omega_1, \omega_4, \omega_8, \bar{\omega}_8\}$$

$$t_1 = [1, 1, 1, 0]$$

$$t_2 = [1, -1, 0, 1]$$

$$S_1 = [0, 0, 0, 0]$$

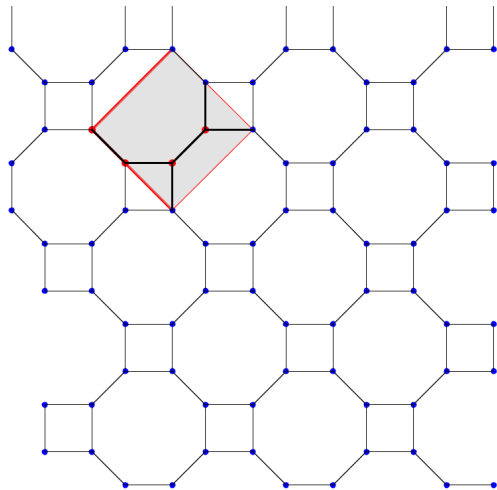
$$S_2 = [0, 0, 0, 1]$$

$$S_3 = [1, 0, 0, 1]$$

$$S_4 = [1, 0, 1, 1]$$

Assisted acquisition from photographs:

tiling



$$\Omega = \{\omega_1, \omega_4, \omega_8, \bar{\omega}_8\}$$

$$t_1 = [1, 1, 1, 0]$$

$$t_2 = [1, -1, 0, 1]$$

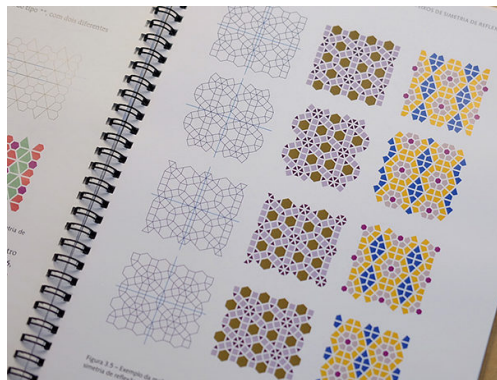
$$S_1 = [0, 0, 0, 0]$$

$$S_2 = [0, 0, 0, 1]$$

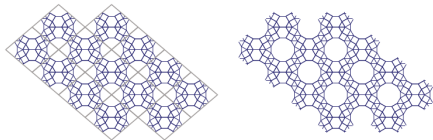
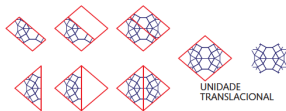
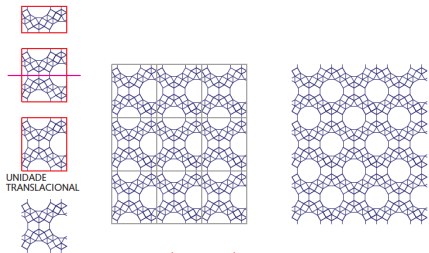
$$S_3 = [1, 0, 0, 1]$$

$$S_4 = [1, 0, 1, 1]$$

Book & catalogue: 200+ Arquimedean tilings



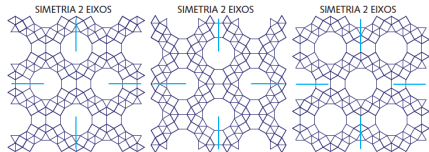
“Sobre malhas arquimedianas”, Ricardo Sá e Asla Medeiros e Sá, 2017



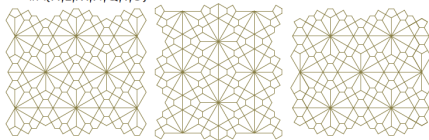
#A_{H,L,M,N,Q,T,U}



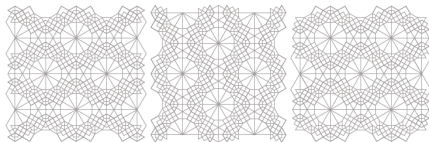
- H = 4-6-12
- L = 3-3-4-12
- M = 3-4-3-12
- N = 3-4-46
- Q = 3-3-6-6
- T = 3-3-3-4-4
- U = 3-3-4-3-4



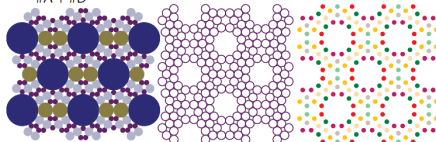
#A_{H,L,M,N,Q,T,U}



#D_{H,L,M,N,Q,T,U}



#A + #D



CÍRCULOS INSCRITOS

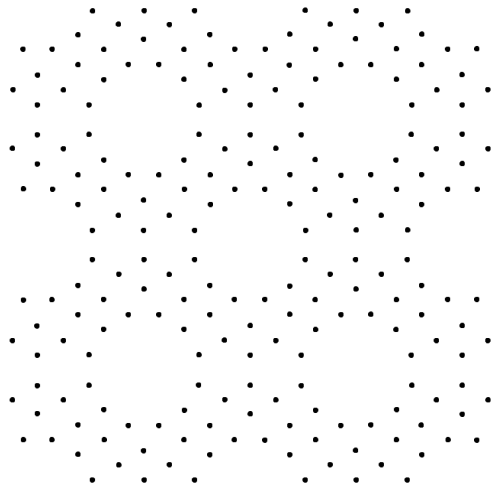
CÍRCULOS IGUAIS TANGENTES

CONSTELAÇÃO DE NÓS

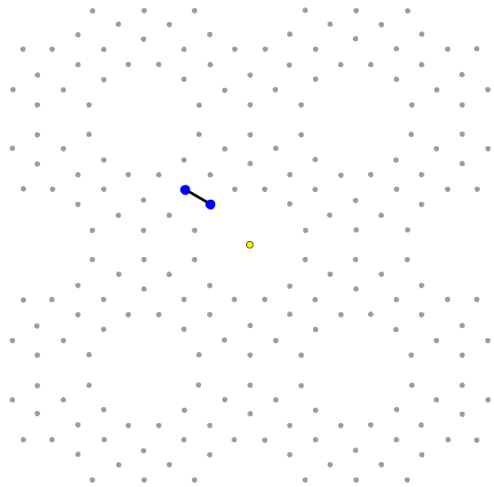
Automatic acquisition from tiny point cloud images



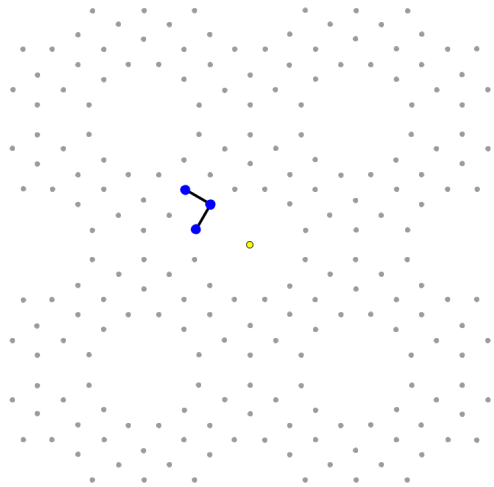
Automatic acquisition from tiny point cloud images



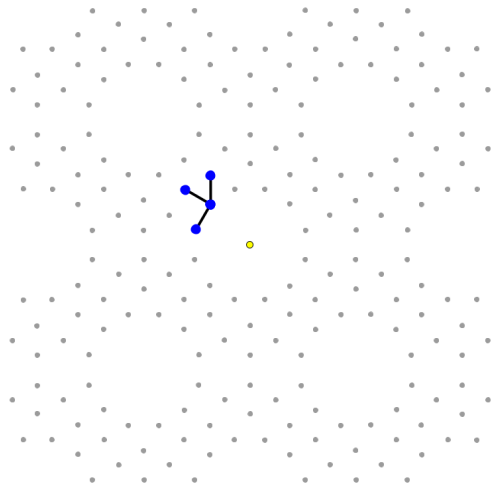
Automatic acquisition from tiny point cloud images



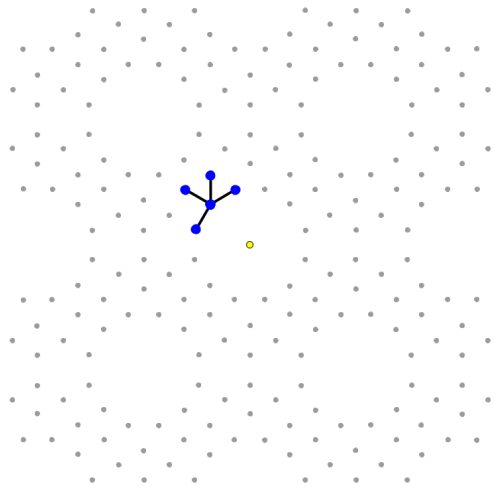
Automatic acquisition from tiny point cloud images



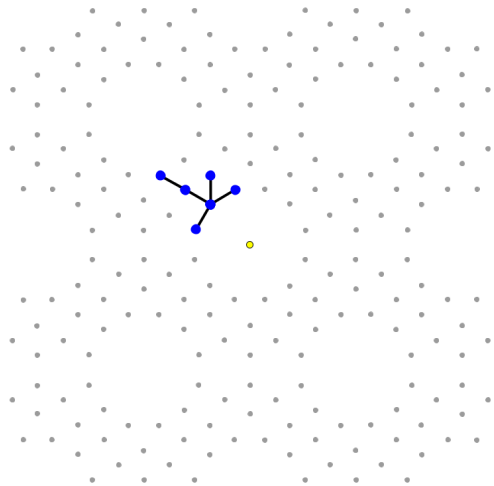
Automatic acquisition from tiny point cloud images



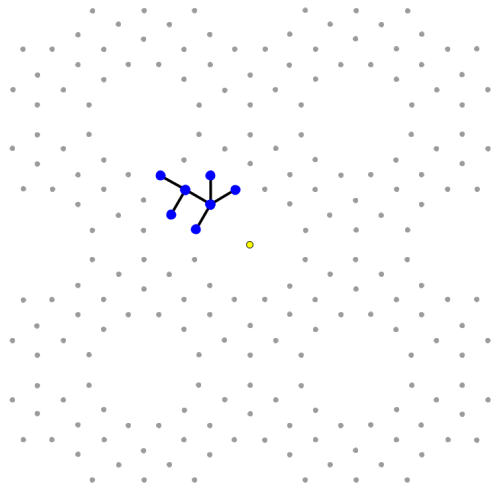
Automatic acquisition from tiny point cloud images



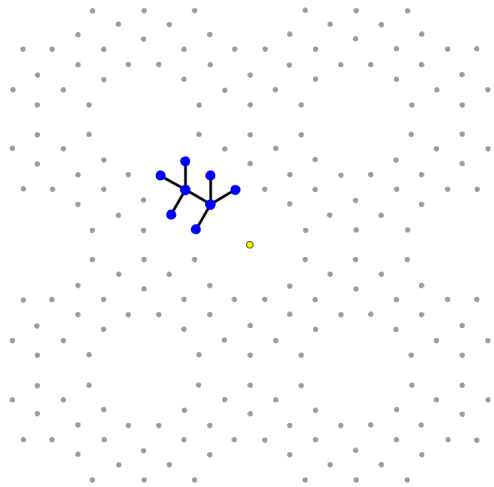
Automatic acquisition from tiny point cloud images



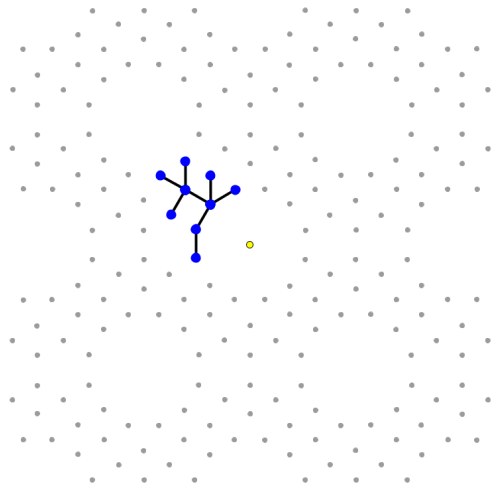
Automatic acquisition from tiny point cloud images



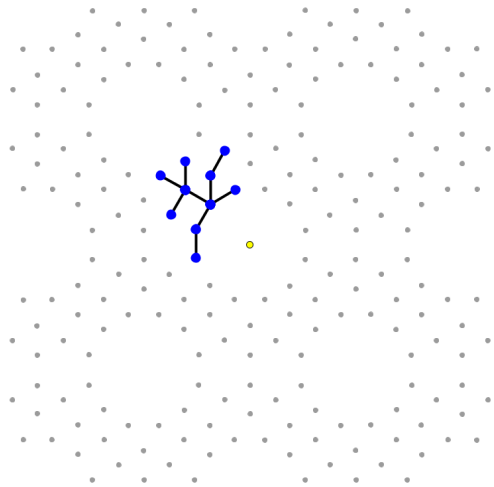
Automatic acquisition from tiny point cloud images



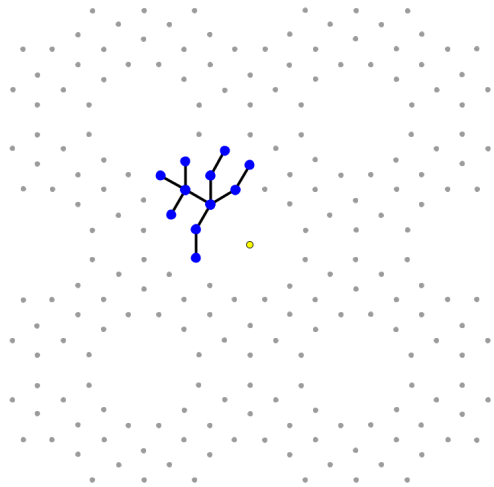
Automatic acquisition from tiny point cloud images



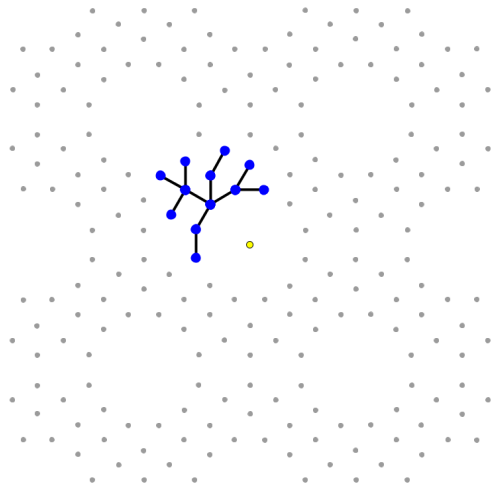
Automatic acquisition from tiny point cloud images



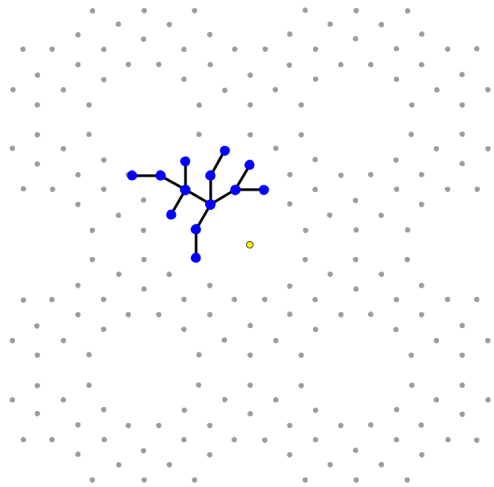
Automatic acquisition from tiny point cloud images



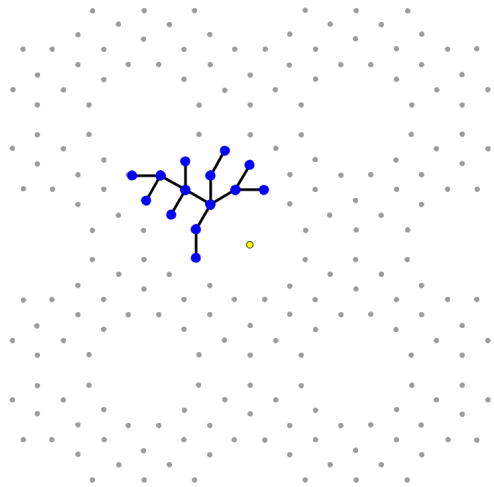
Automatic acquisition from tiny point cloud images



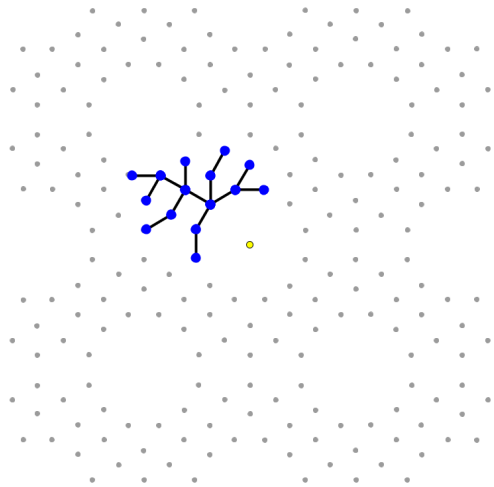
Automatic acquisition from tiny point cloud images



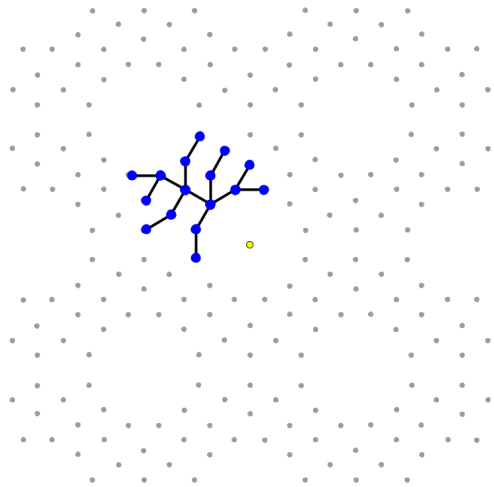
Automatic acquisition from tiny point cloud images



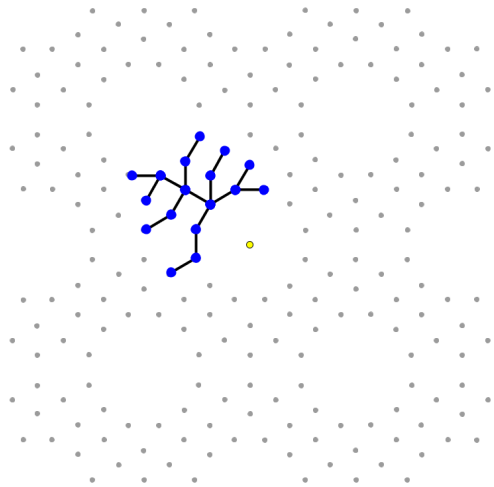
Automatic acquisition from tiny point cloud images



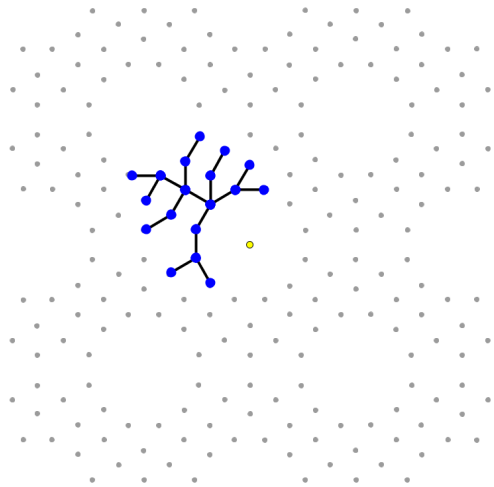
Automatic acquisition from tiny point cloud images



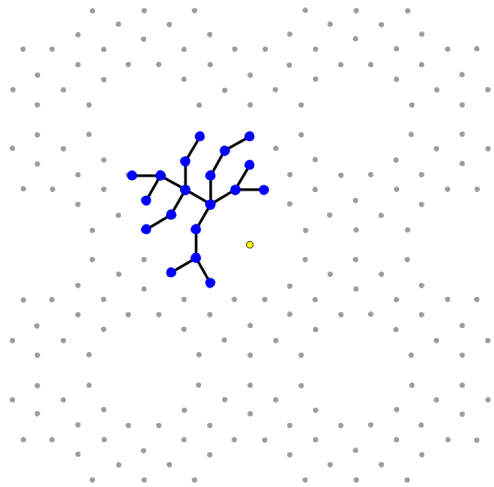
Automatic acquisition from tiny point cloud images



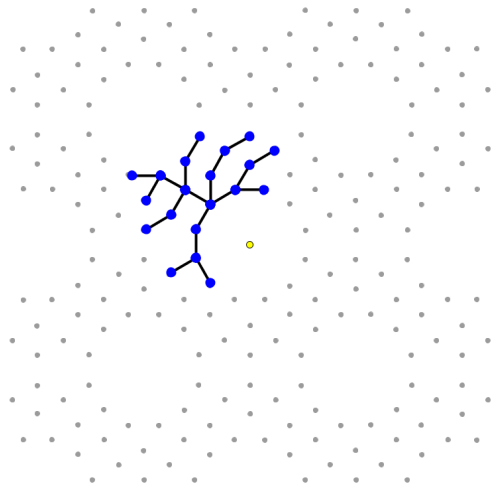
Automatic acquisition from tiny point cloud images



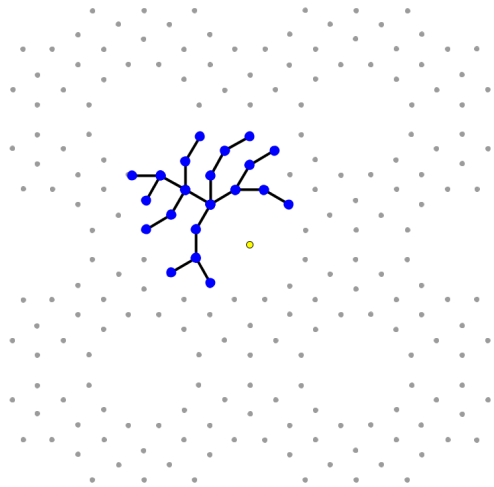
Automatic acquisition from tiny point cloud images



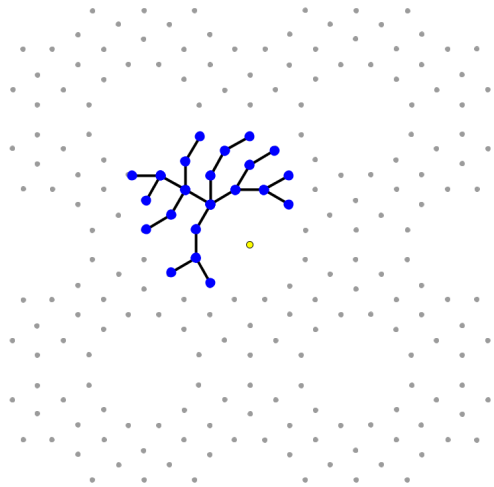
Automatic acquisition from tiny point cloud images



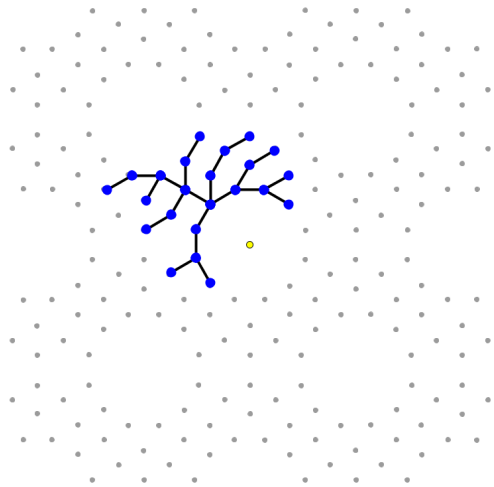
Automatic acquisition from tiny point cloud images



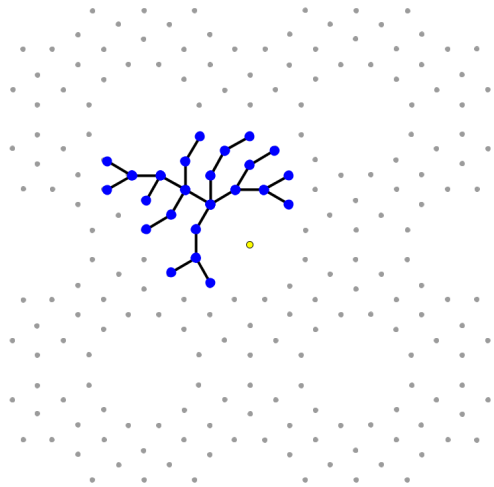
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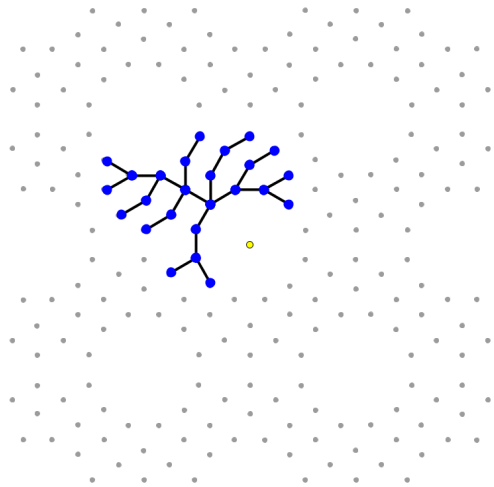
Automatic acquisition from tiny point cloud images



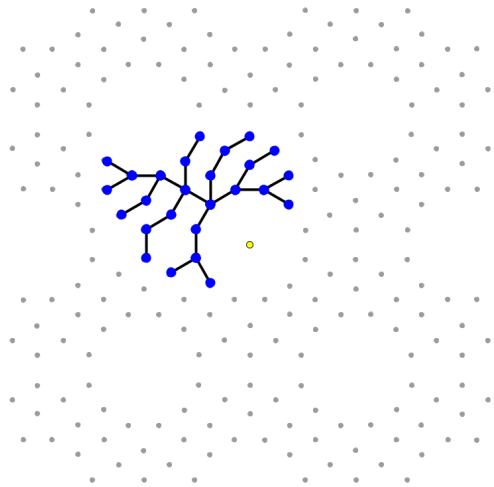
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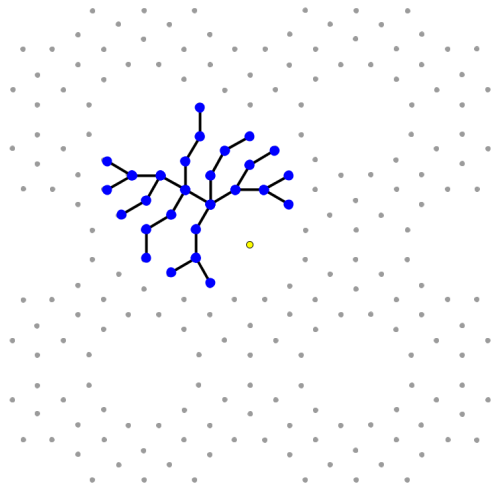
Automatic acquisition from tiny point cloud images



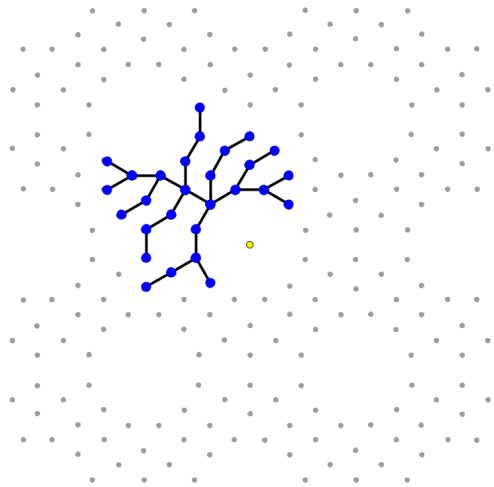
Automatic acquisition from tiny point cloud images



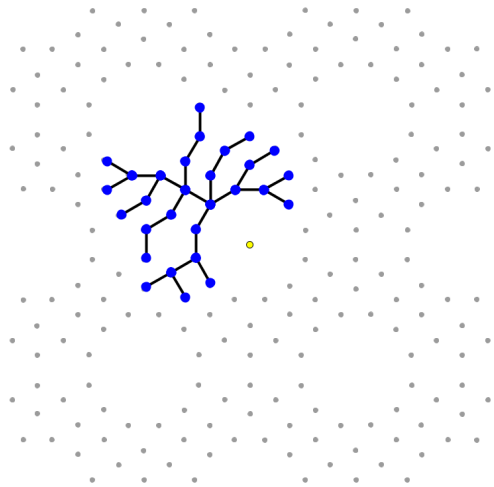
Automatic acquisition from tiny point cloud images



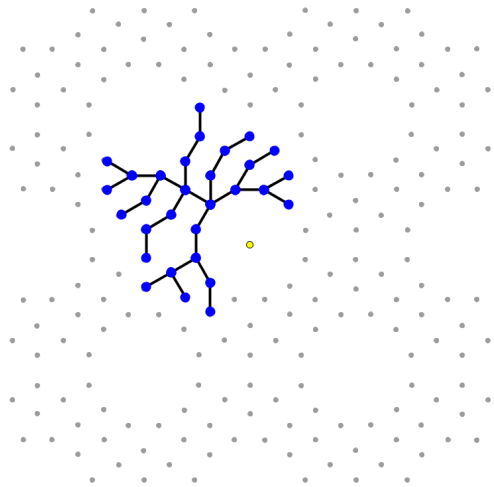
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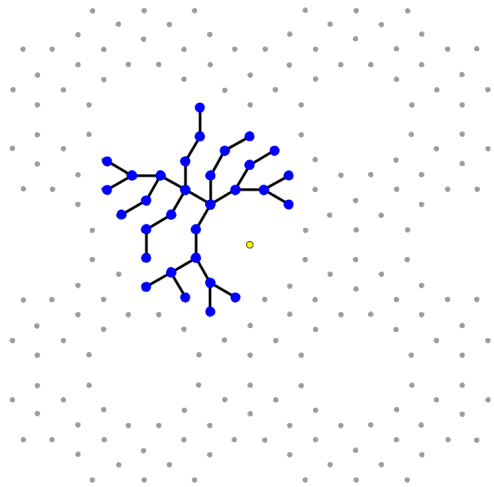
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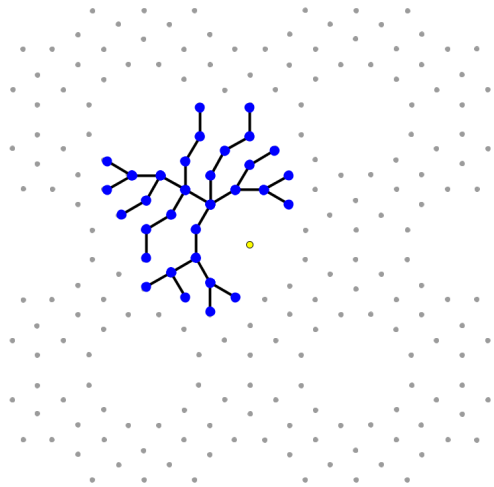
Automatic acquisition from tiny point cloud images



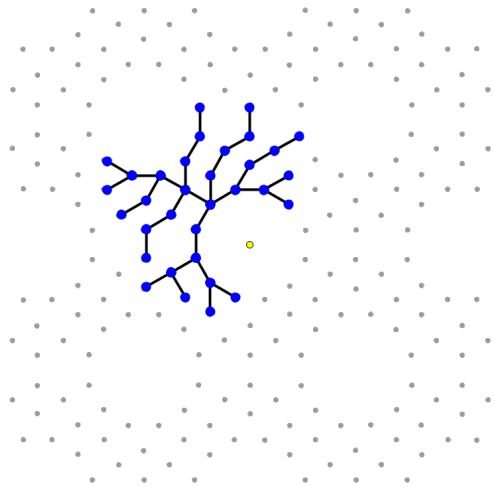
Automatic acquisition from tiny point cloud images



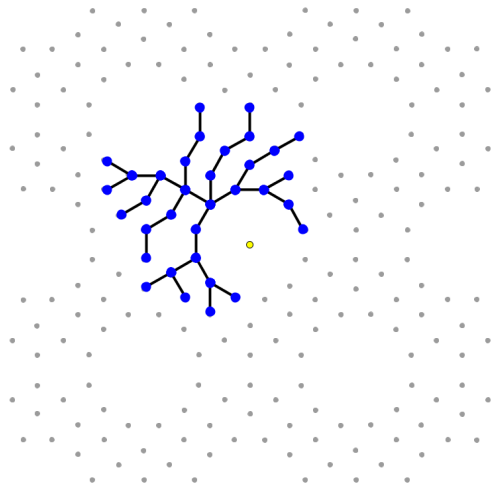
Automatic acquisition from tiny point cloud images



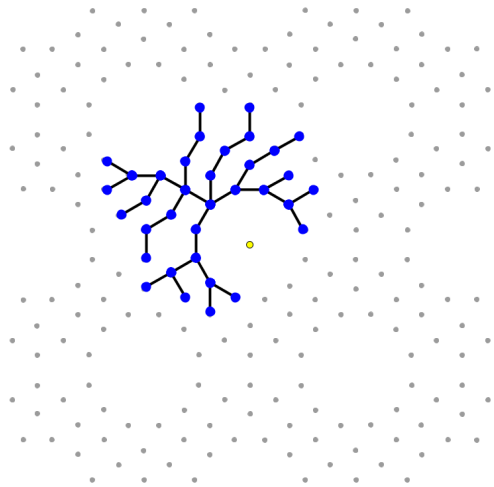
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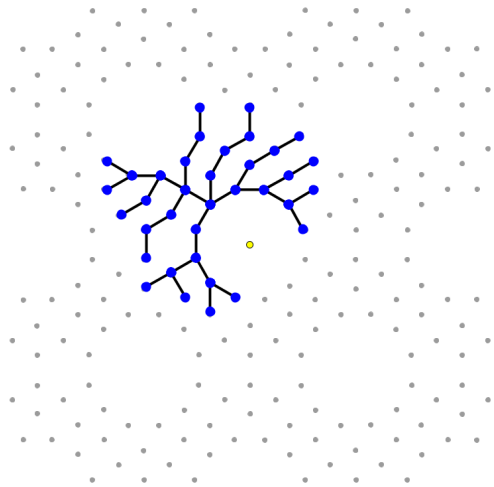
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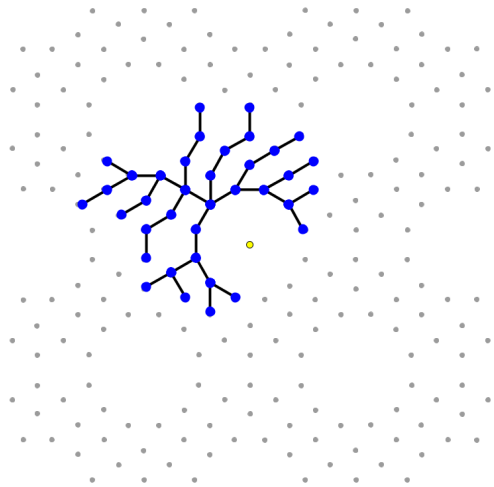
Automatic acquisition from tiny point cloud images



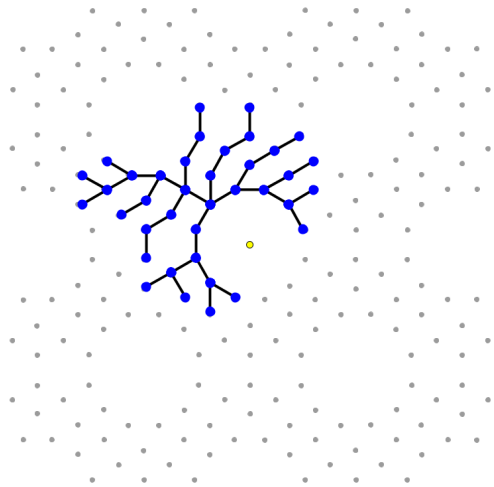
Automatic acquisition from tiny point cloud images



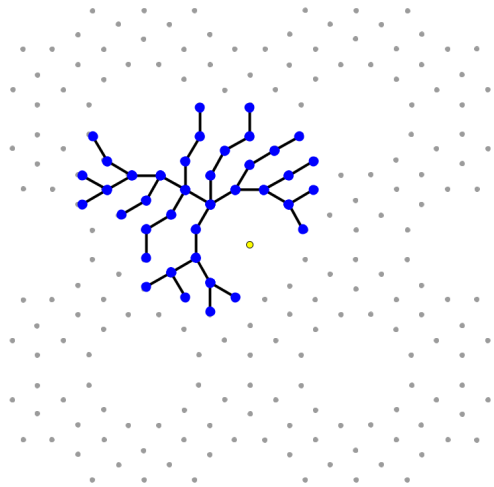
Automatic acquisition from tiny point cloud images



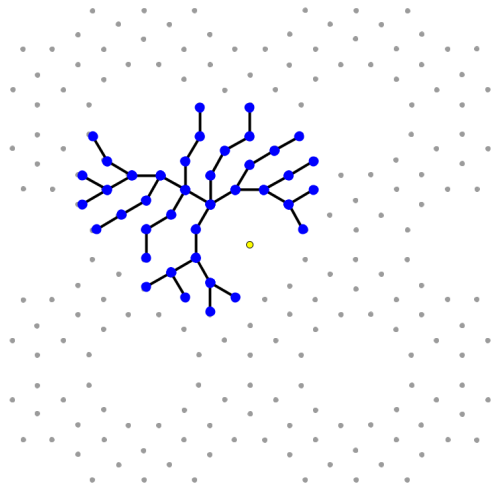
Automatic acquisition from tiny point cloud images



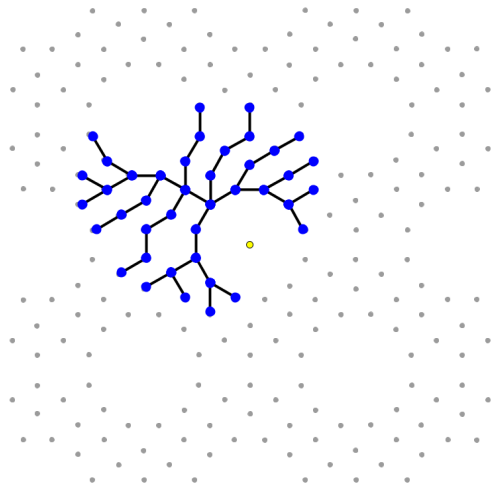
Automatic acquisition from tiny point cloud images



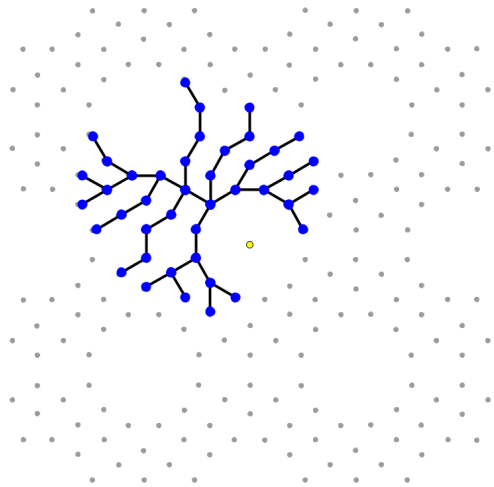
Automatic acquisition from tiny point cloud images



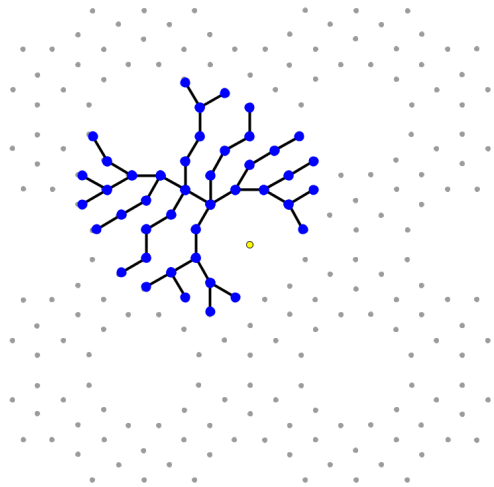
Automatic acquisition from tiny point cloud images



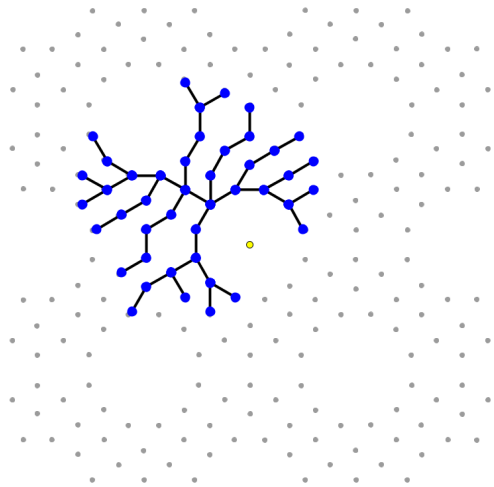
Automatic acquisition from tiny point cloud images



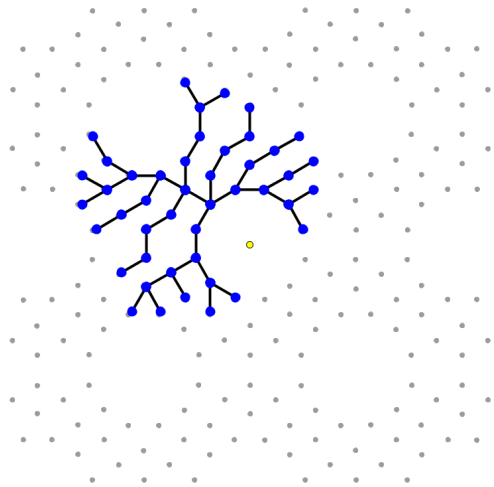
Automatic acquisition from tiny point cloud images



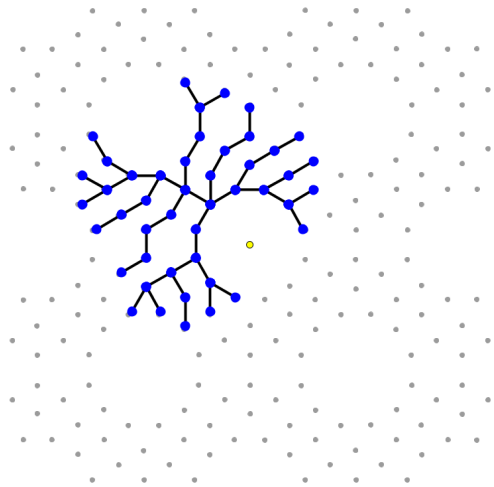
Automatic acquisition from tiny point cloud images



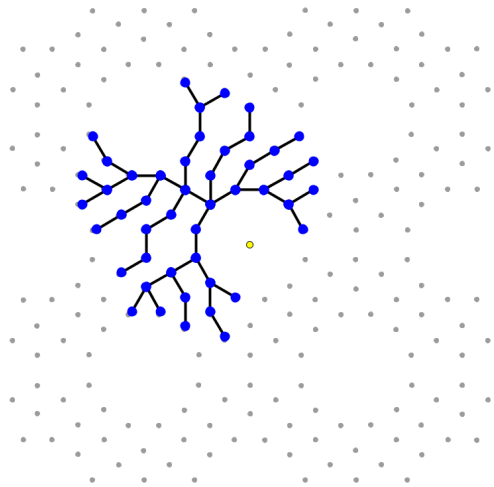
Automatic acquisition from tiny point cloud images



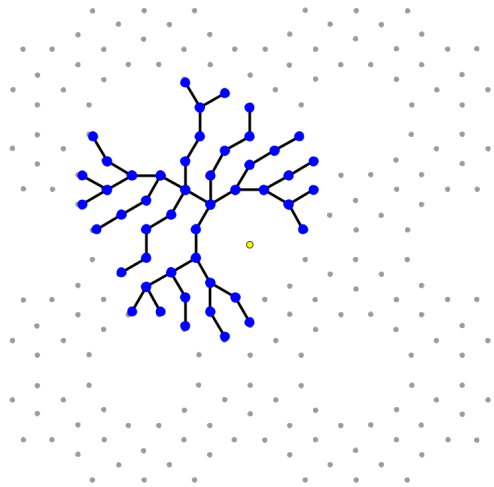
Automatic acquisition from tiny point cloud images



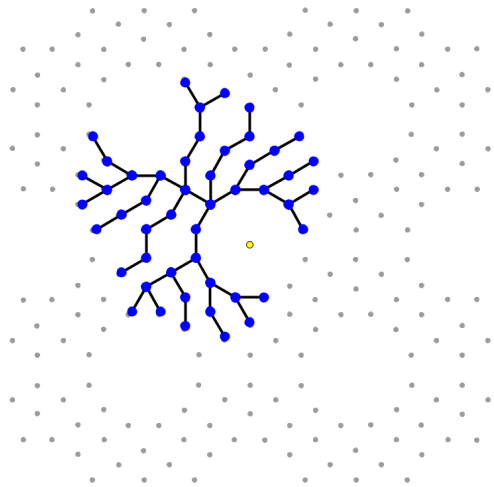
Automatic acquisition from tiny point cloud images



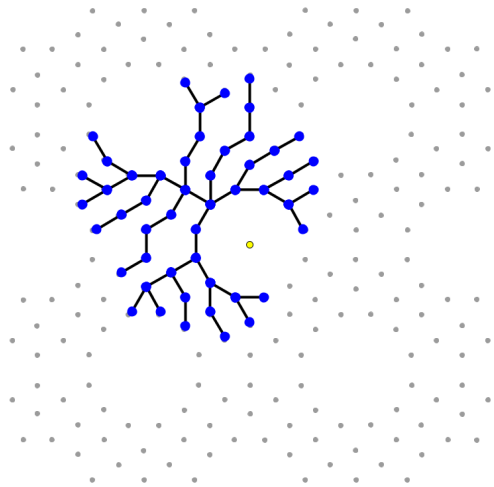
Automatic acquisition from tiny point cloud images



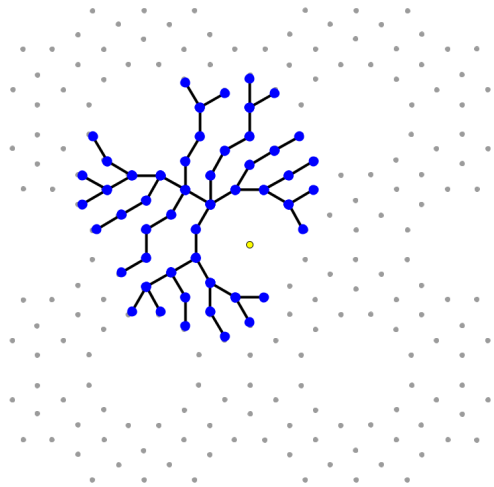
Automatic acquisition from tiny point cloud images



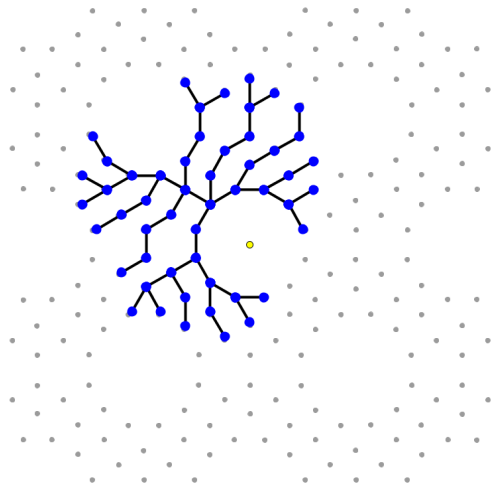
Automatic acquisition from tiny point cloud images



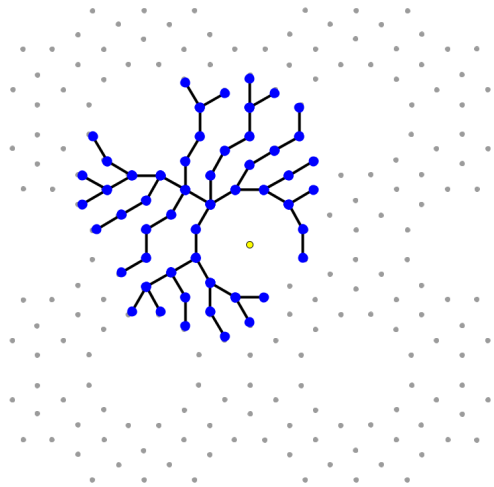
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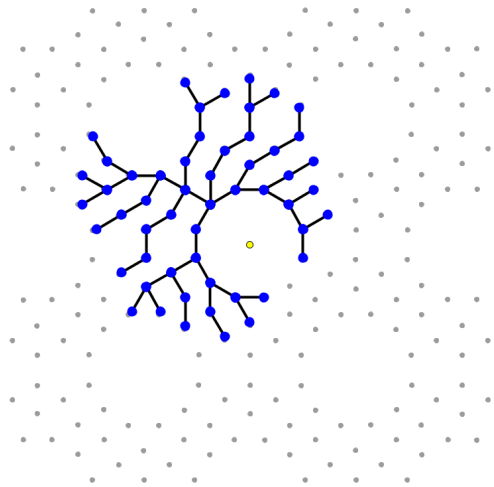
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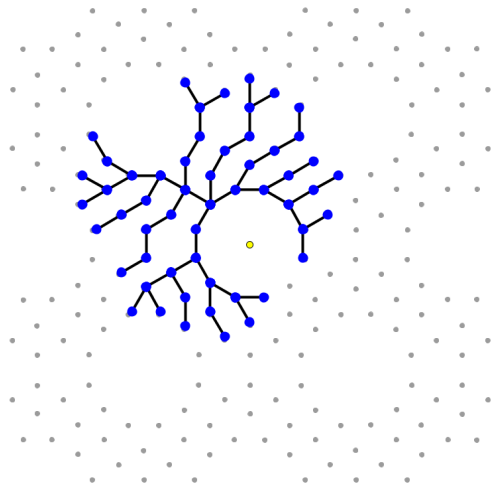
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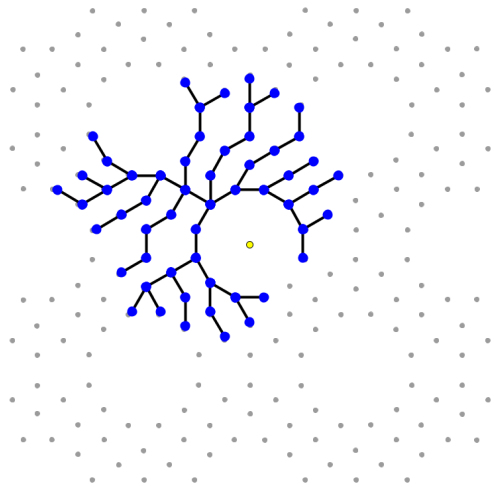
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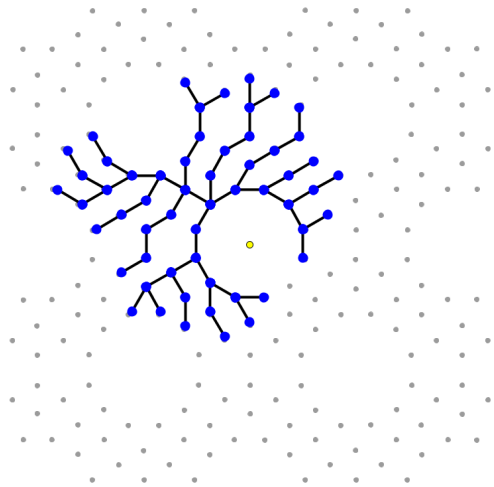
Automatic acquisition from tiny point cloud images



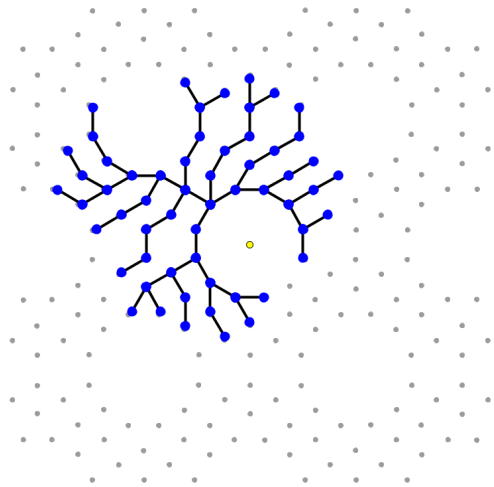
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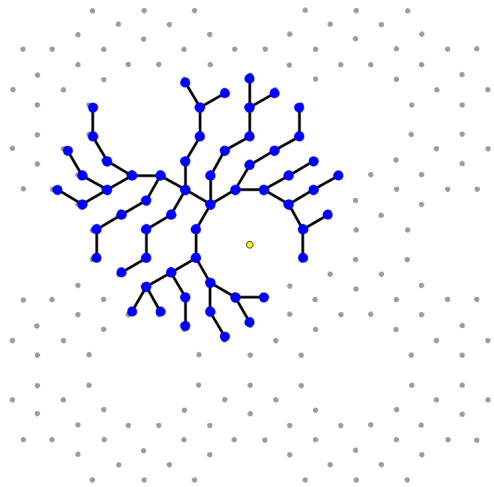
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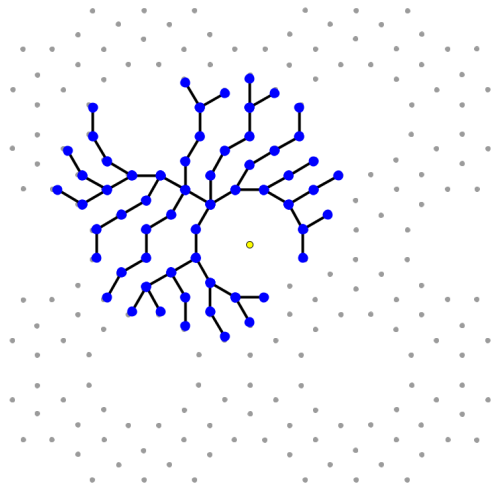
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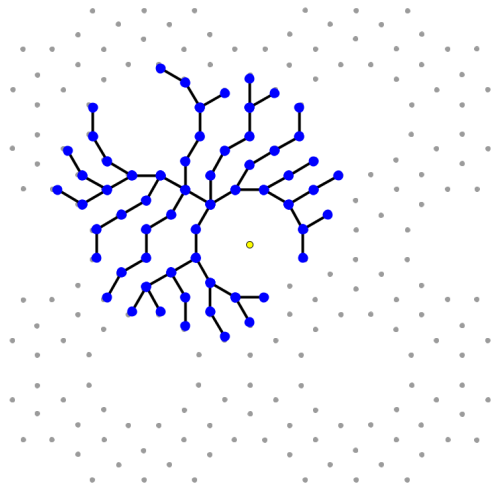
Automatic acquisition from tiny point cloud images



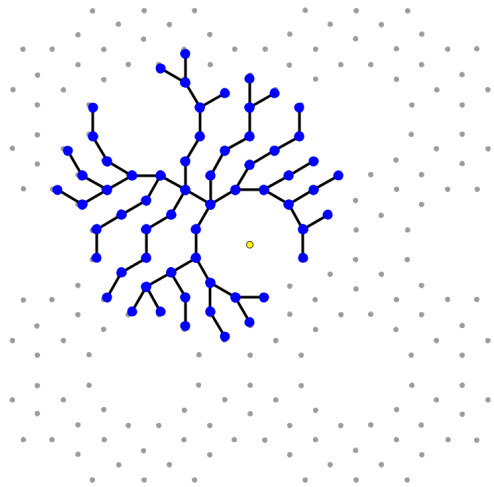
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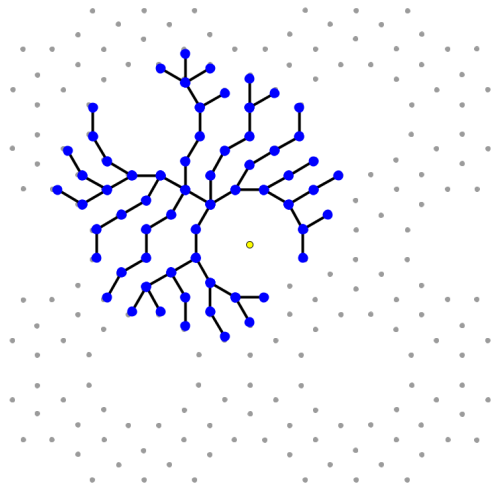
Automatic acquisition from tiny point cloud images



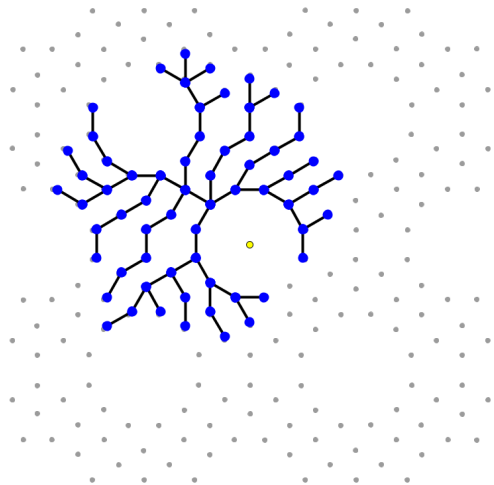
Automatic acquisition from tiny point cloud images



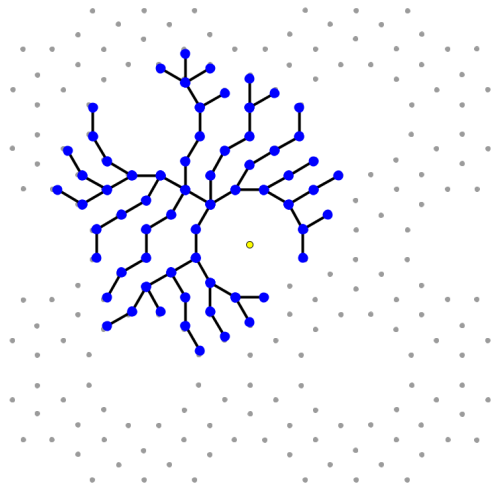
Automatic acquisition from tiny point cloud images



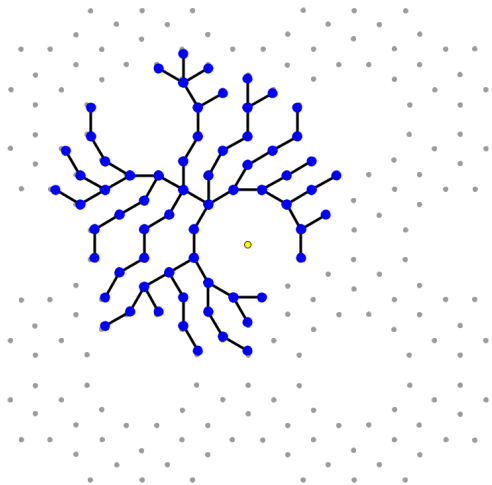
Automatic acquisition from tiny point cloud images



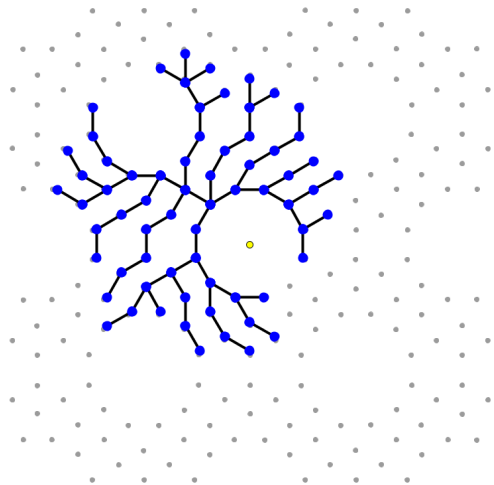
Automatic acquisition from tiny point cloud images



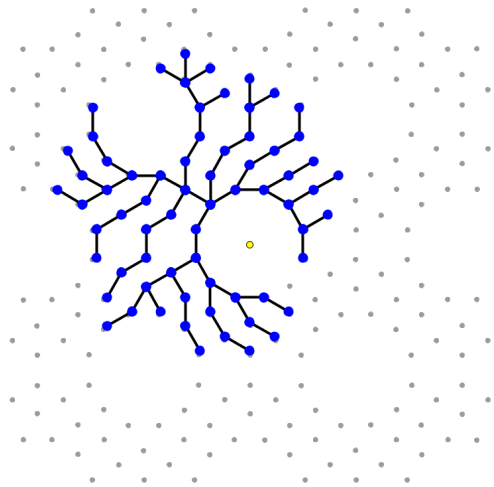
Automatic acquisition from tiny point cloud images



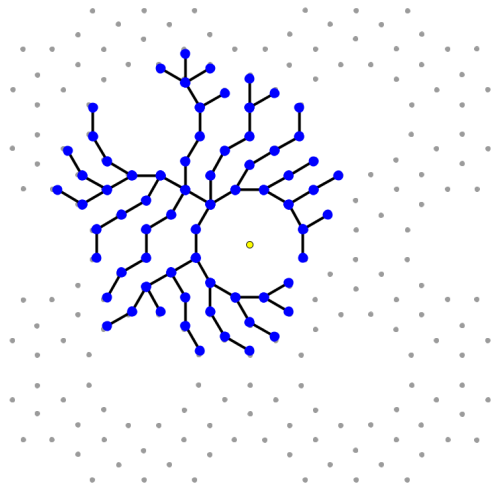
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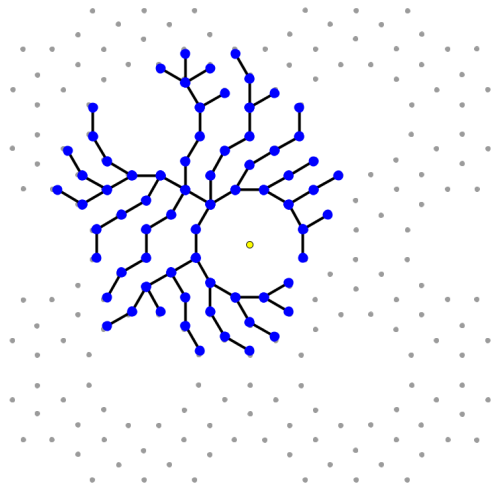
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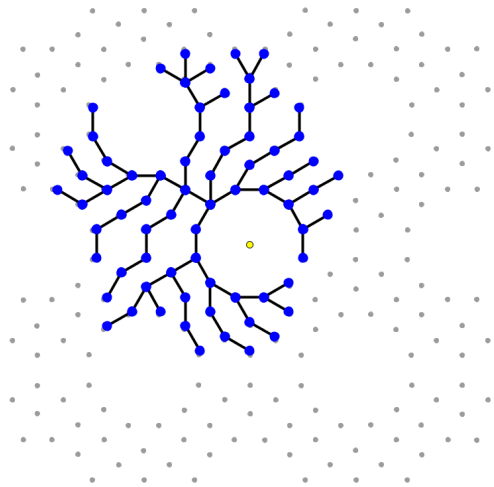
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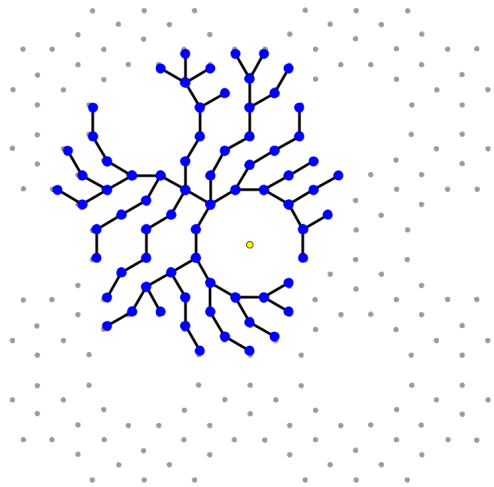
Automatic acquisition from tiny point cloud images



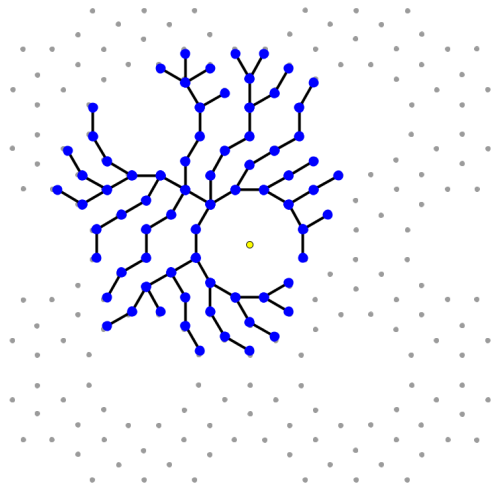
Automatic acquisition from tiny point cloud images



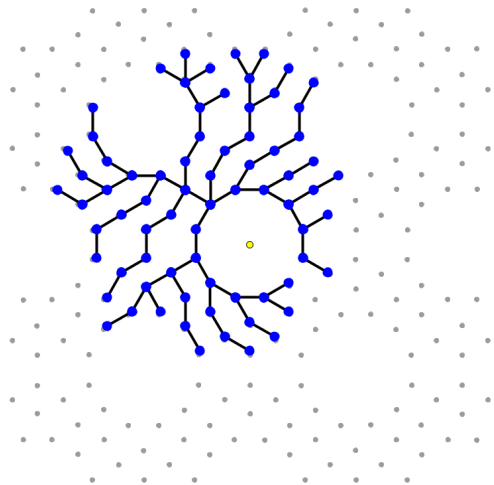
Automatic acquisition from tiny point cloud images



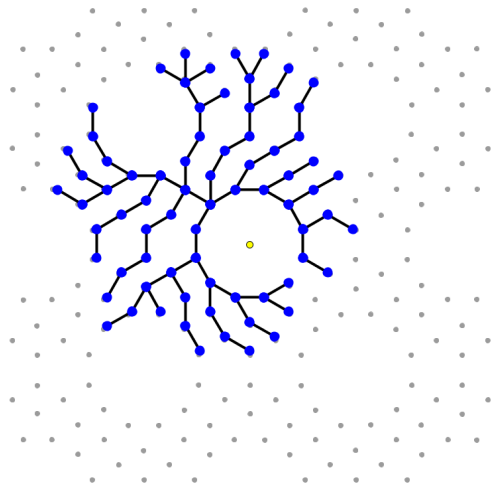
Automatic acquisition from tiny point cloud images



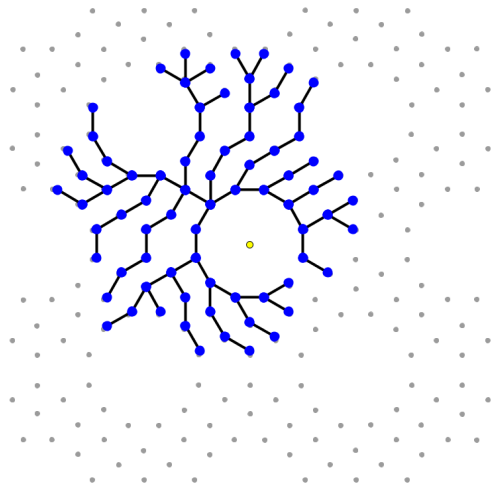
Automatic acquisition from tiny point cloud images



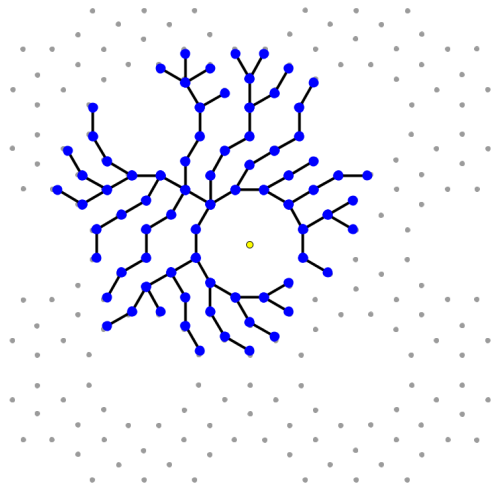
Automatic acquisition from tiny point cloud images



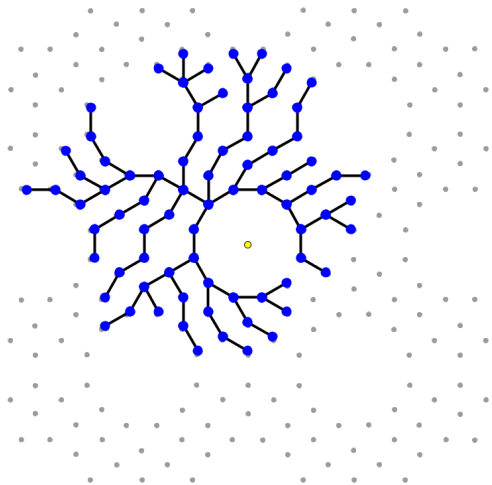
Automatic acquisition from tiny point cloud images



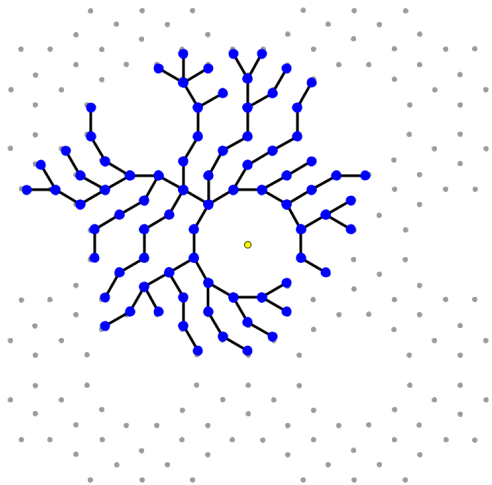
Automatic acquisition from tiny point cloud images



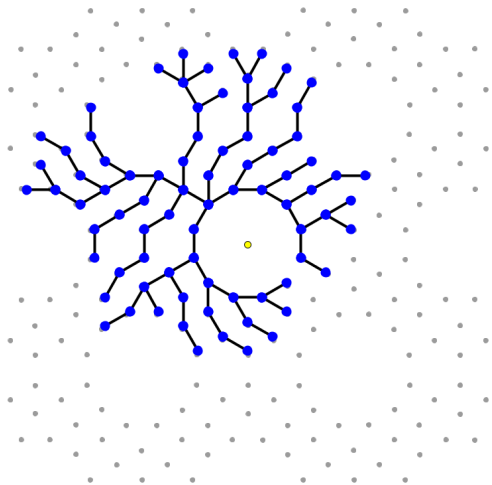
Automatic acquisition from tiny point cloud images



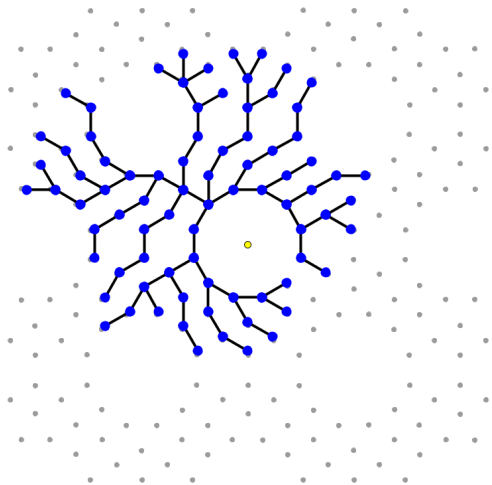
Automatic acquisition from tiny point cloud images



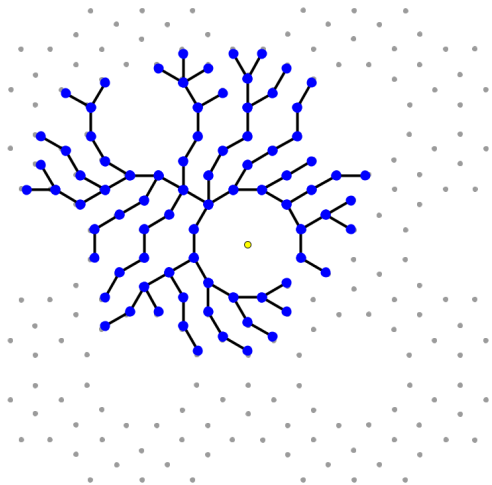
Automatic acquisition from tiny point cloud images



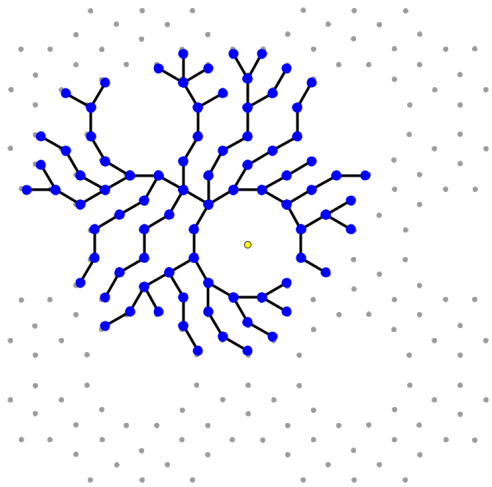
Automatic acquisition from tiny point cloud images



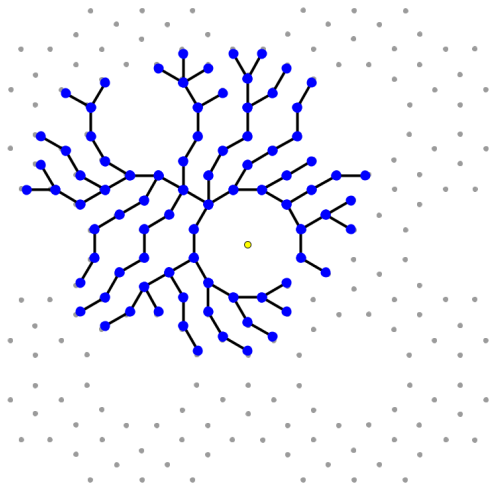
Automatic acquisition from tiny point cloud images



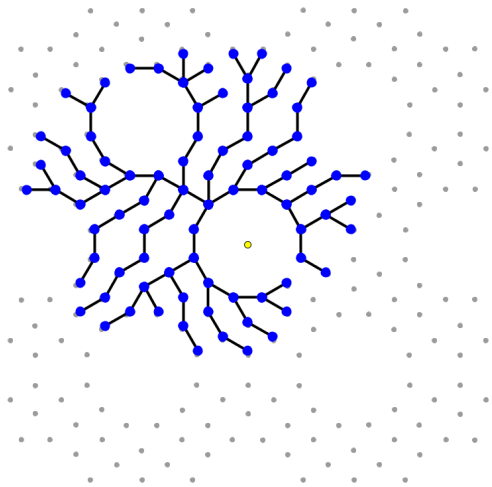
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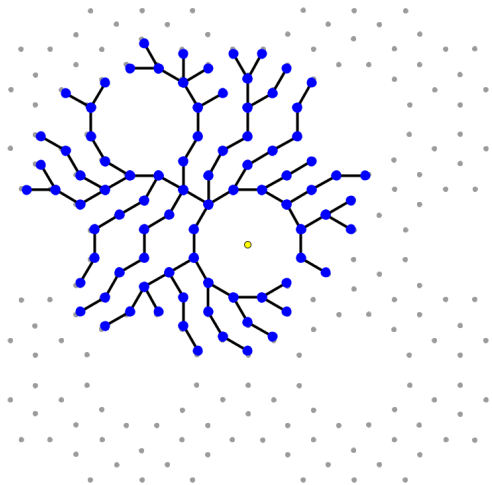
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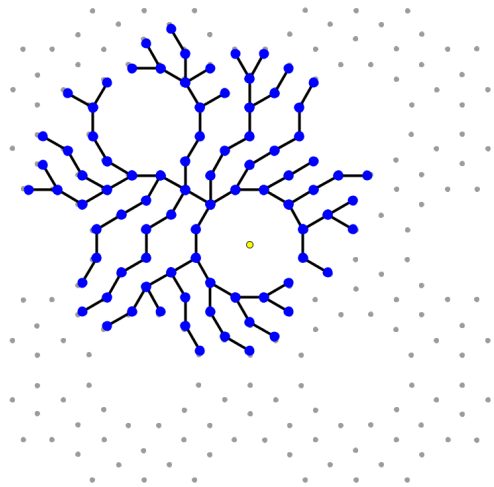
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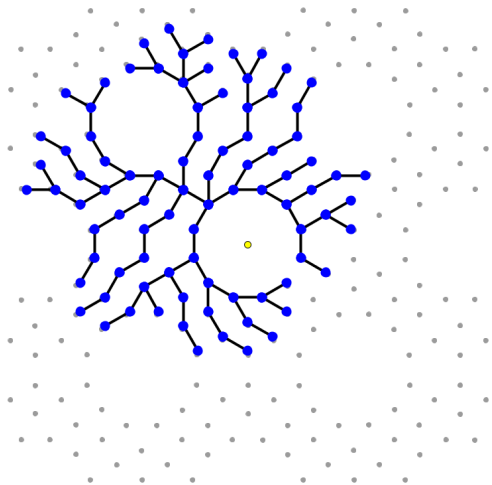
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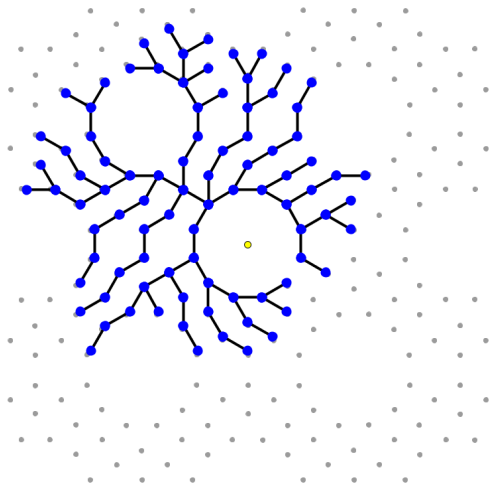
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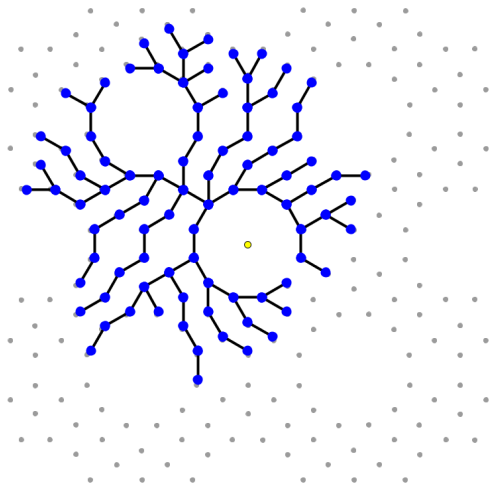
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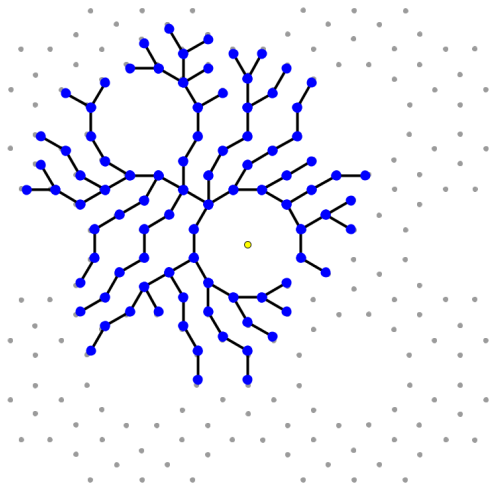
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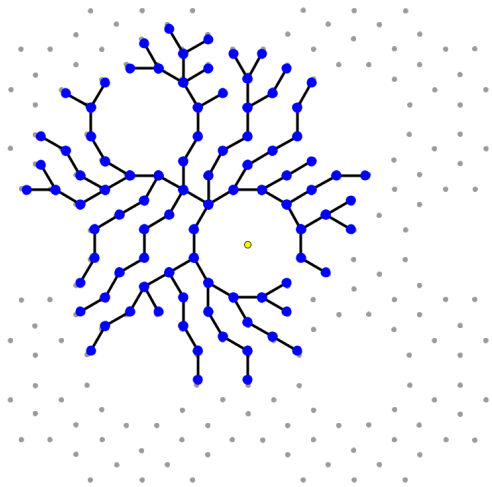
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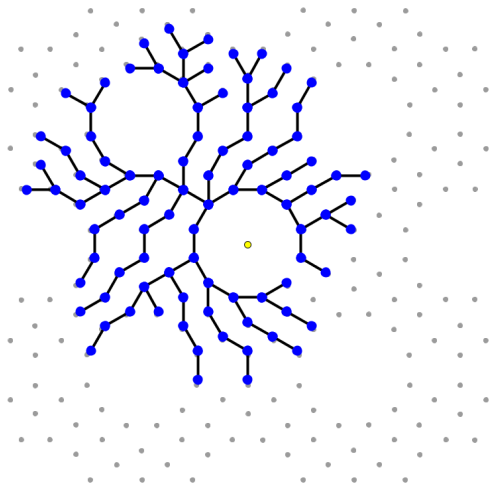
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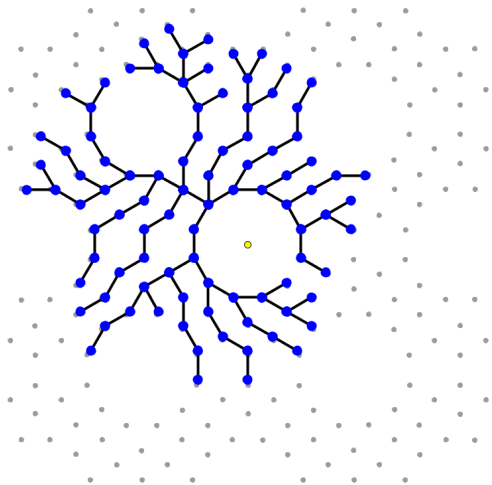
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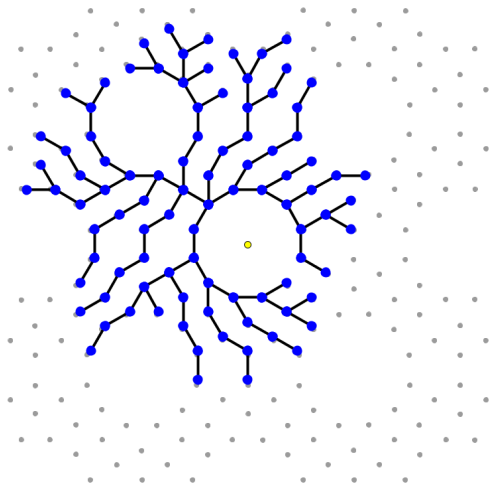
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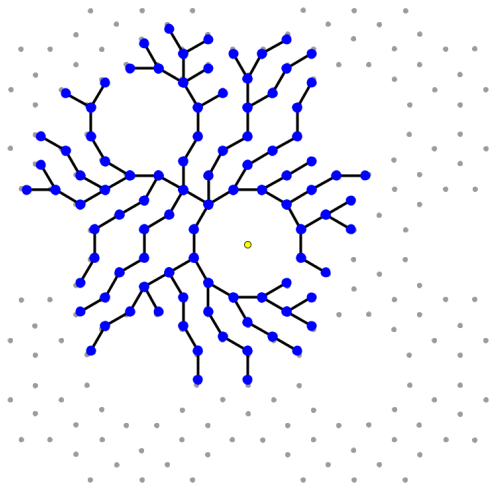
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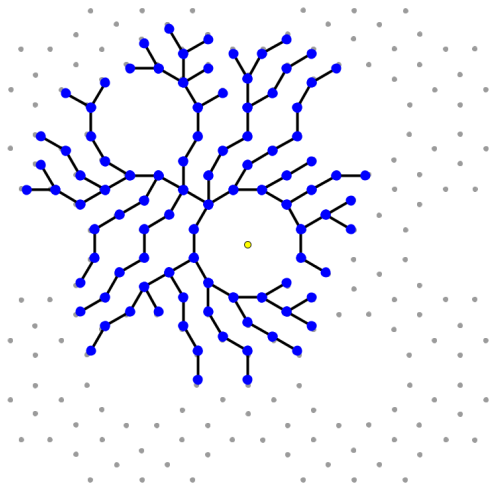
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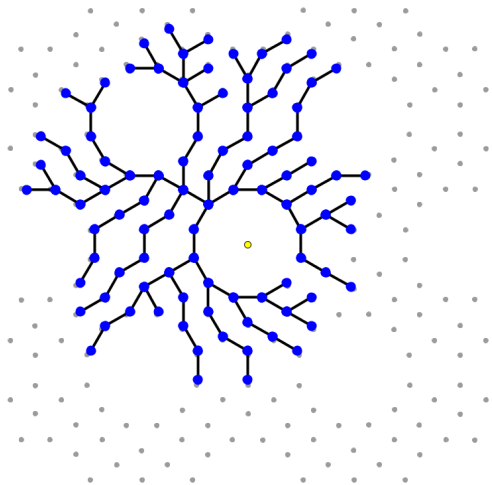
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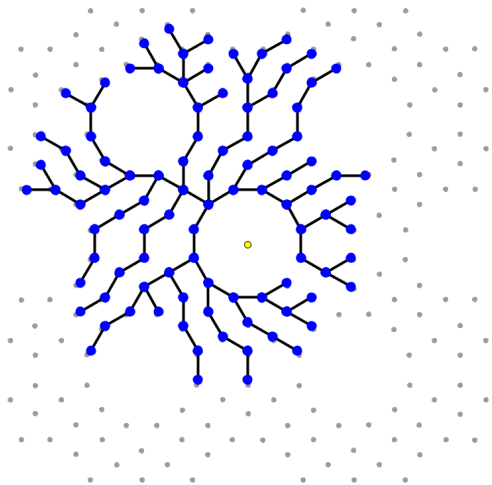
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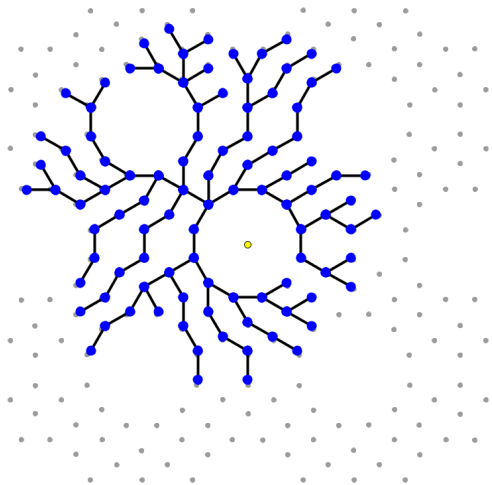
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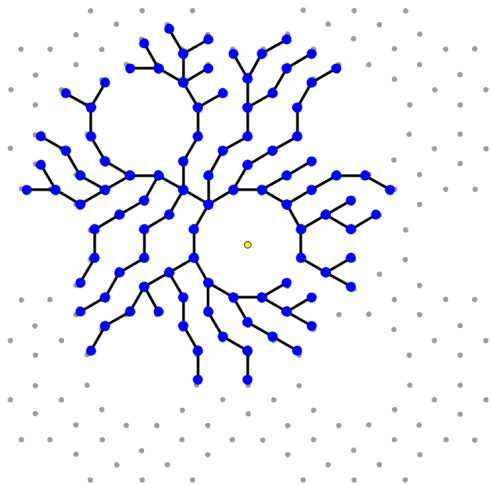
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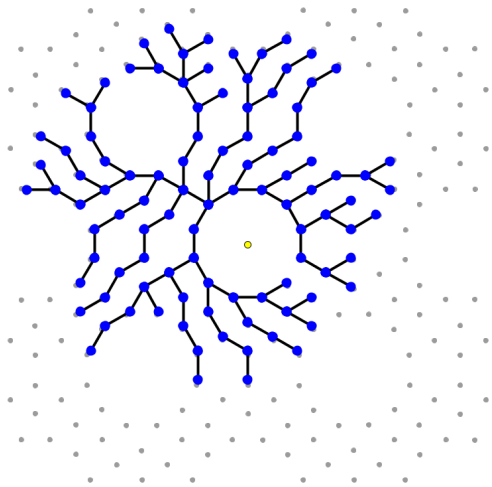
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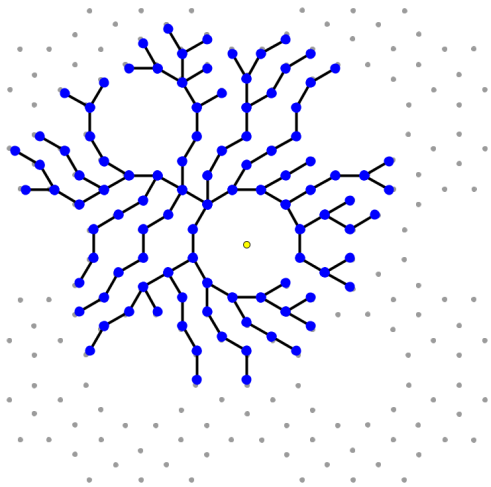
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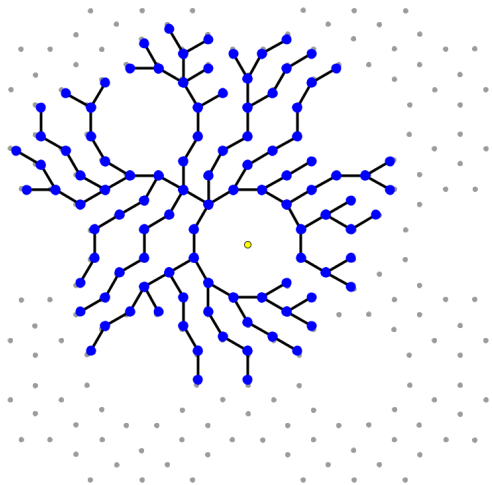
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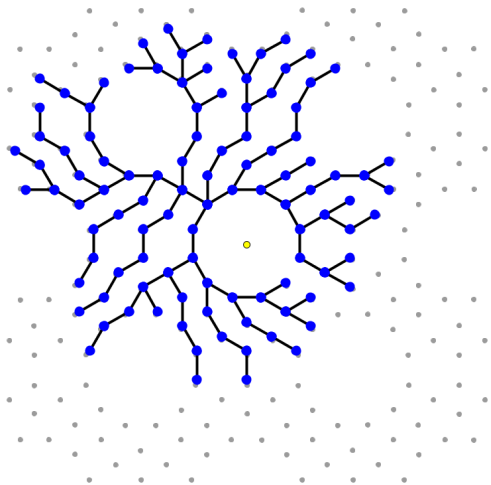
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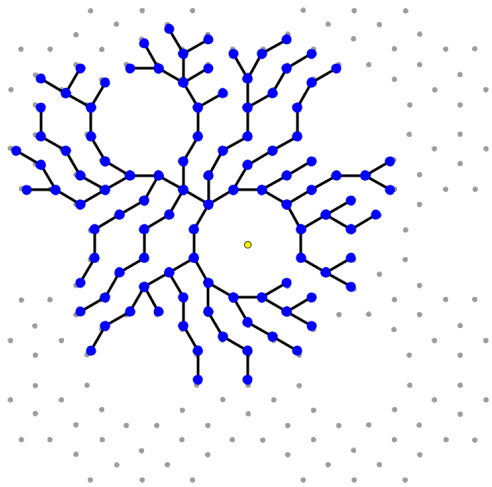
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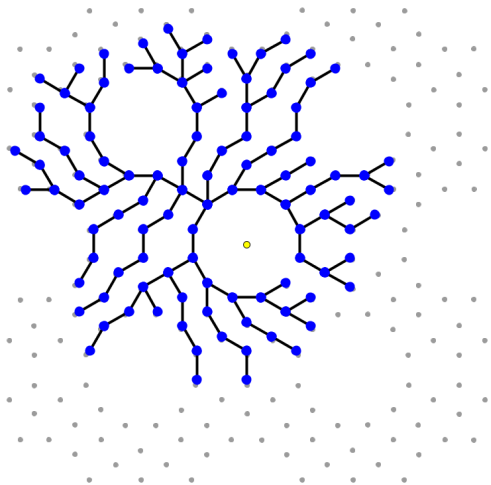
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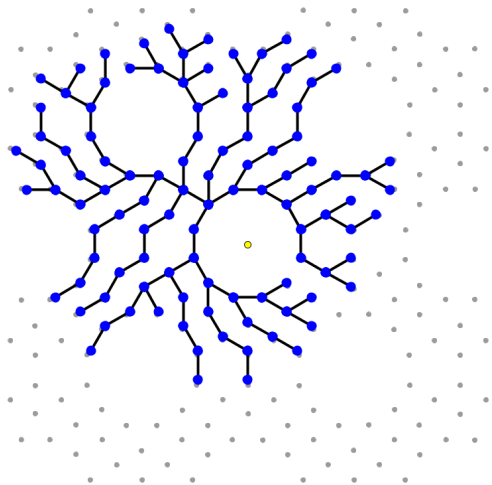
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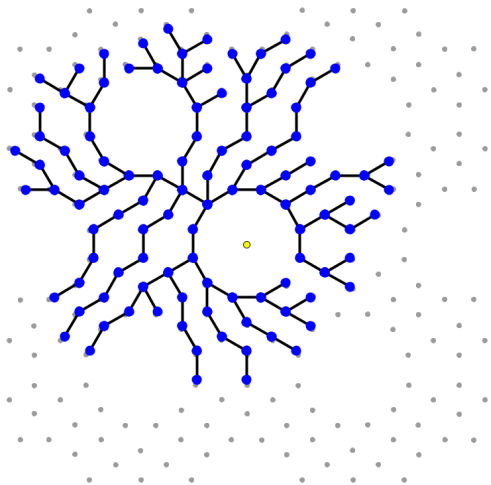
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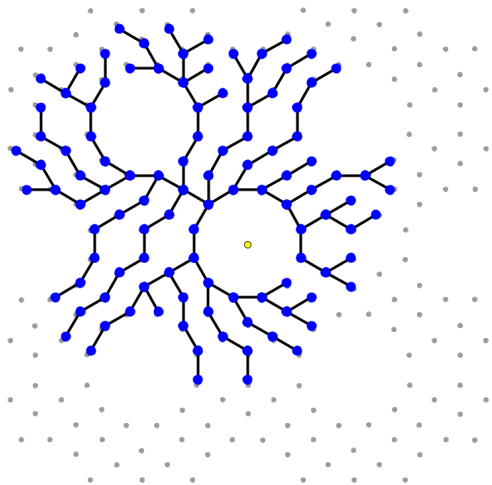
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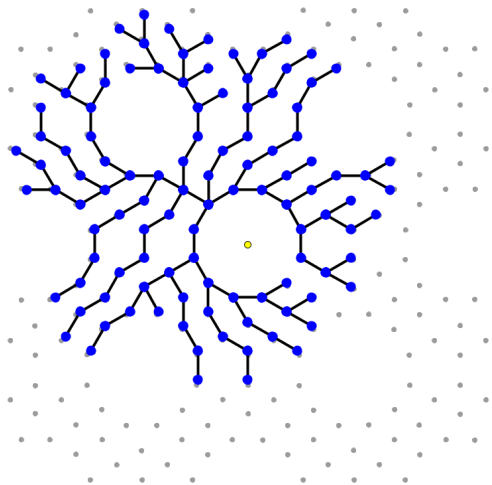
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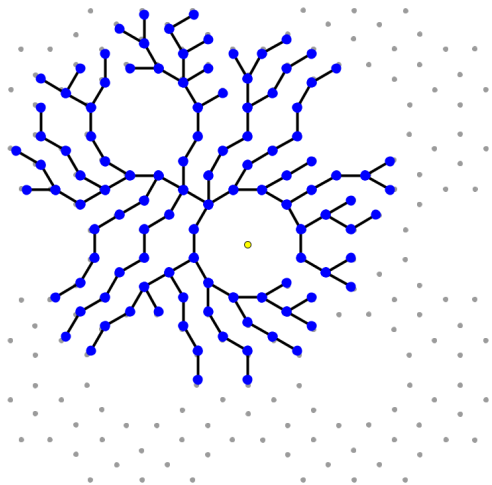
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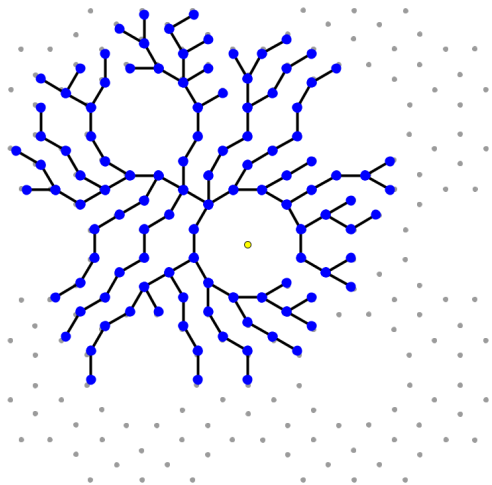
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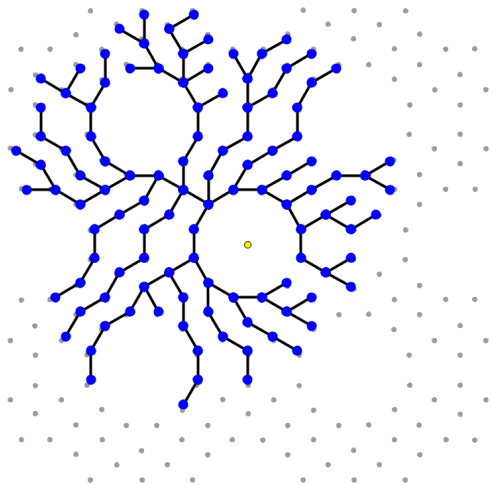
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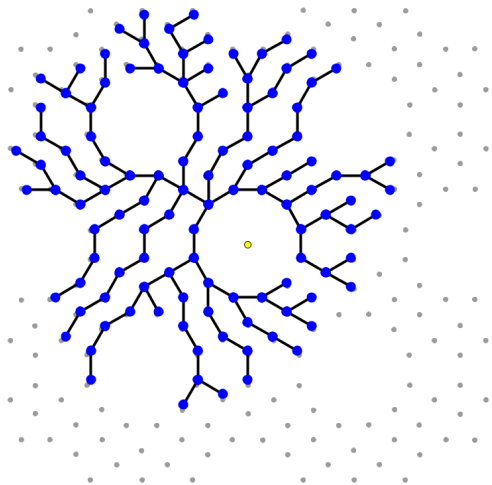
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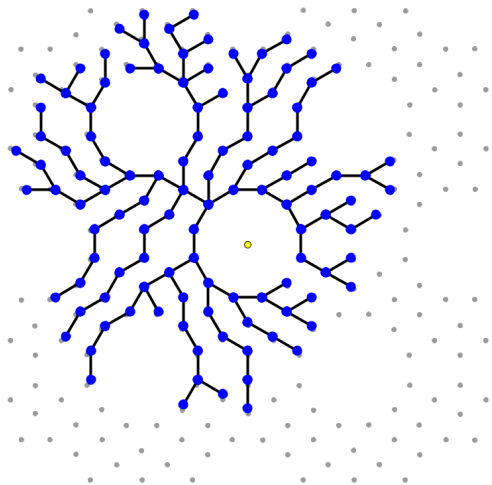
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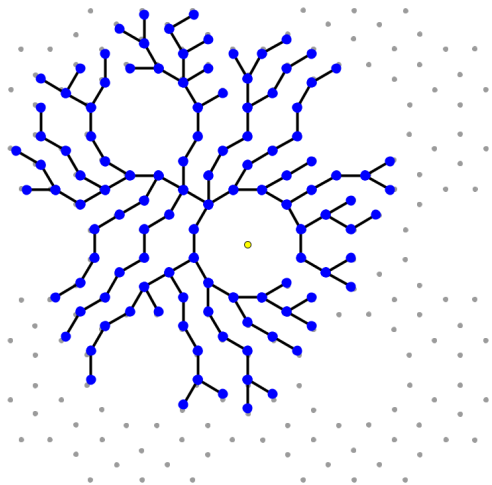
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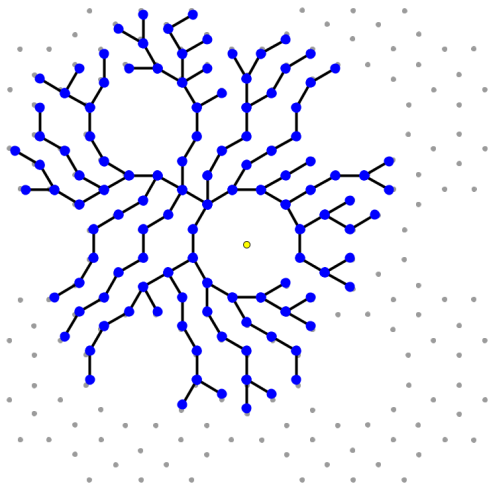
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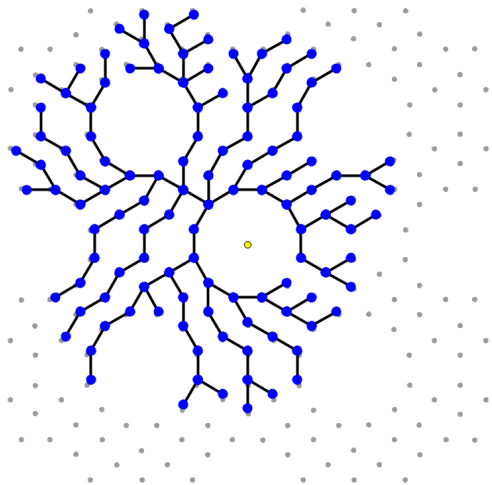
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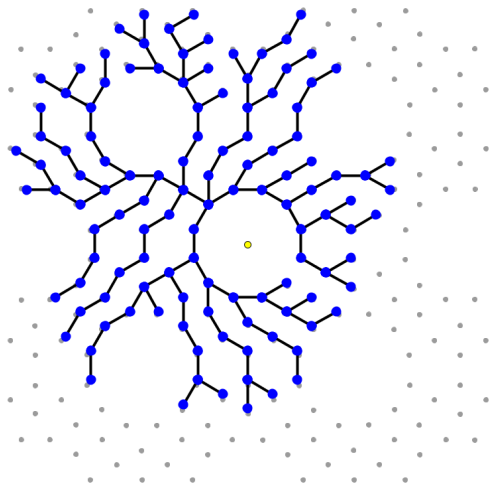
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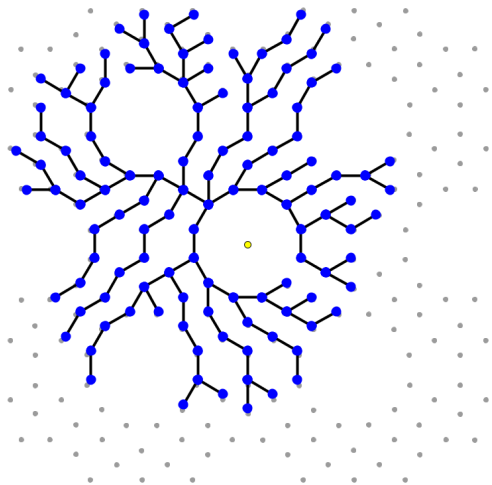
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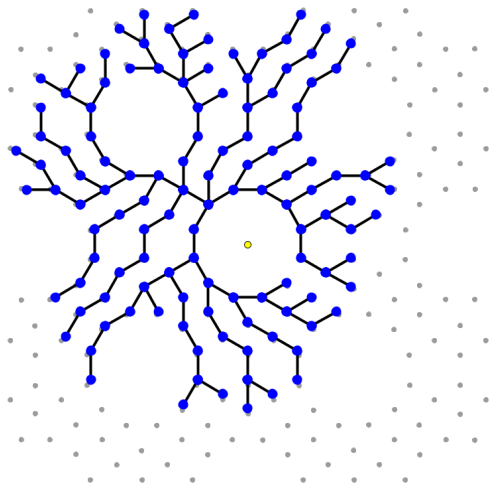
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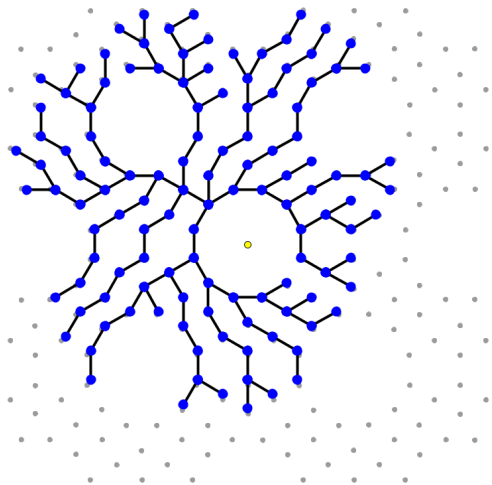
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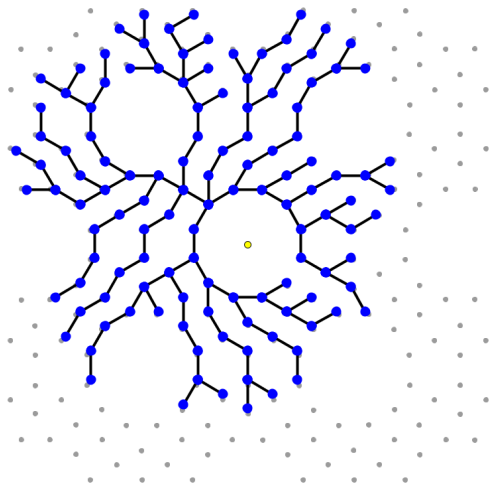
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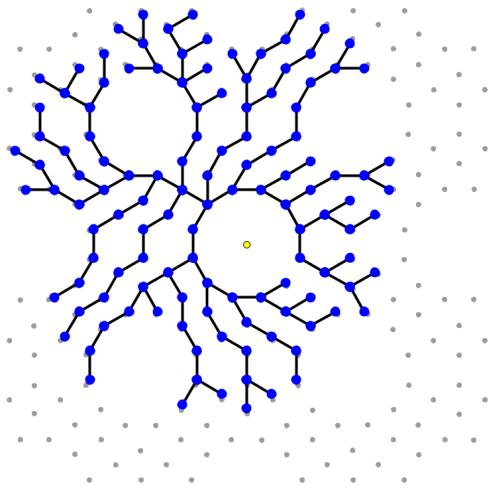
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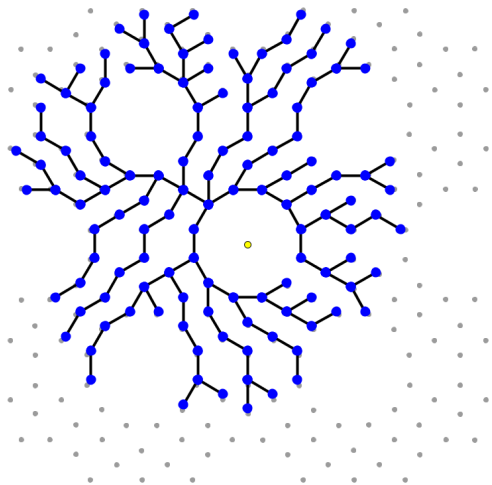
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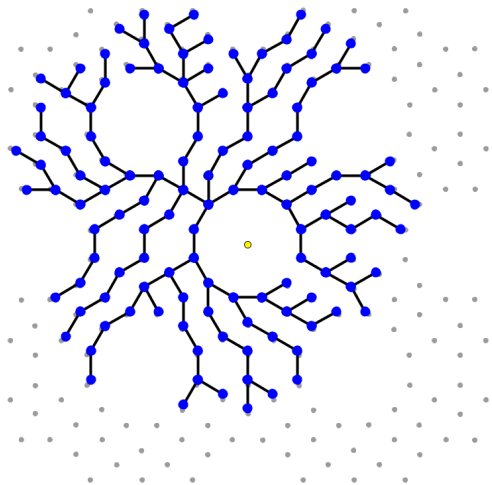
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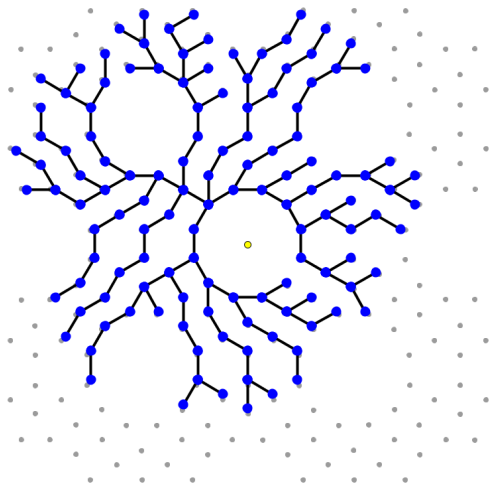
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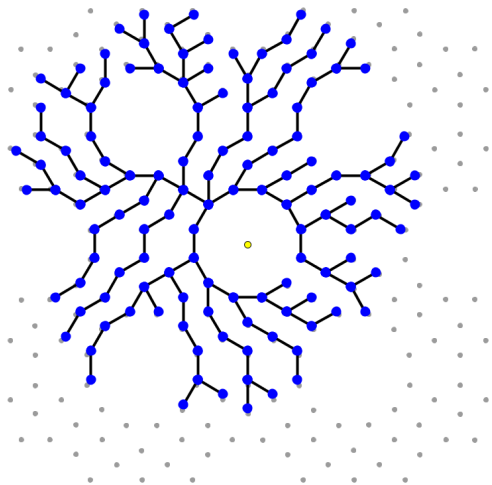
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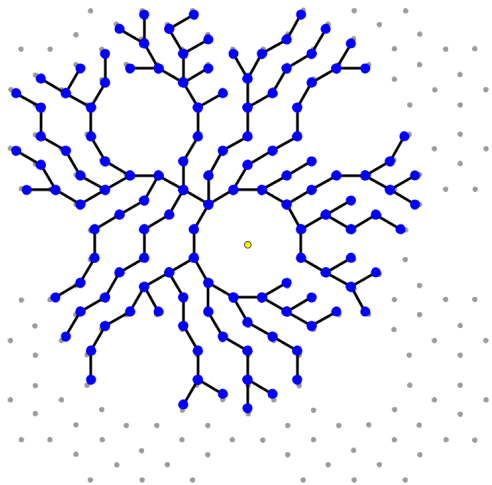
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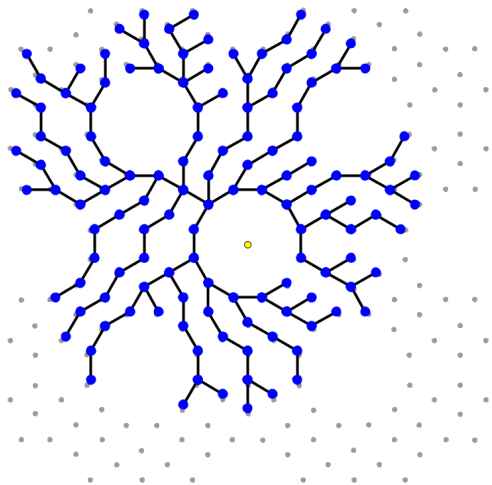
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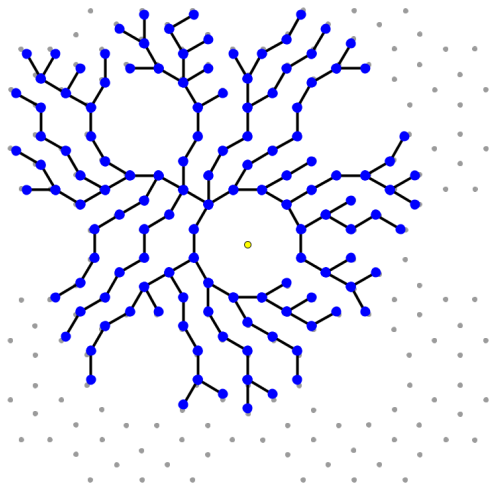
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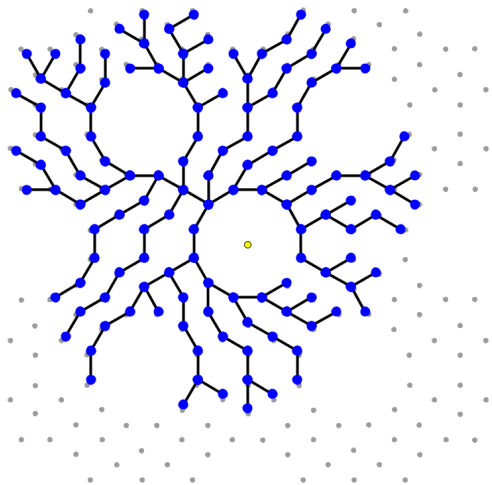
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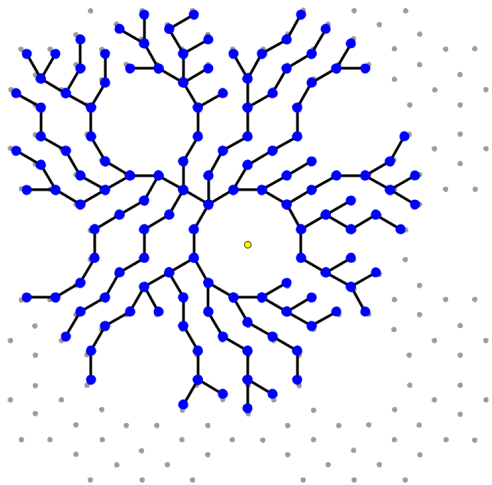
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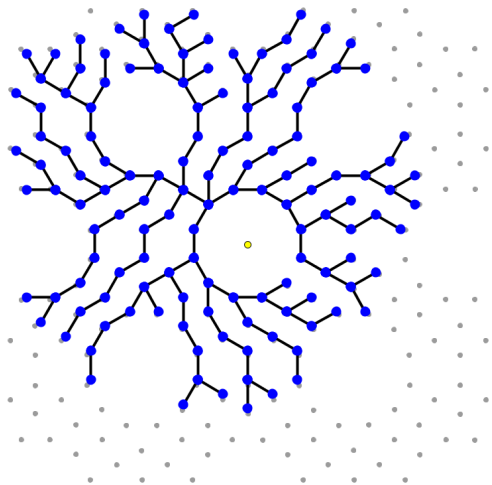
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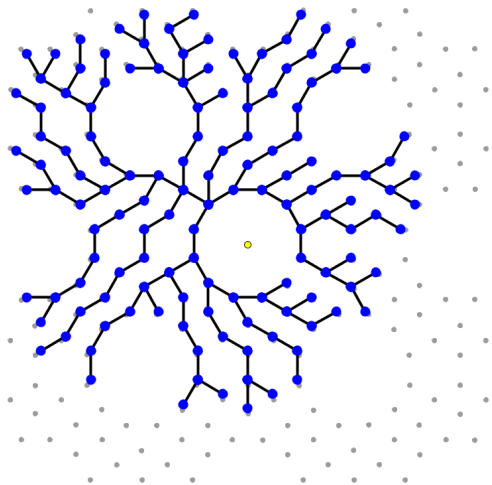
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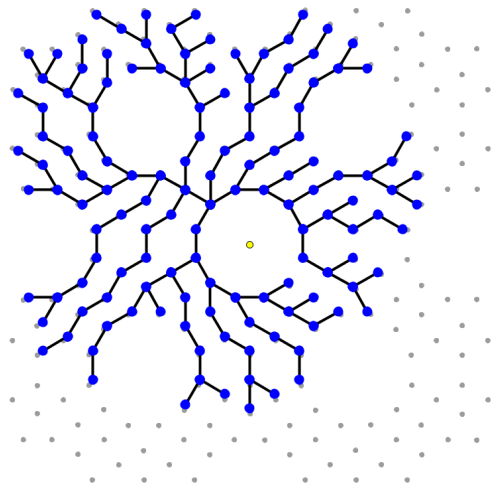
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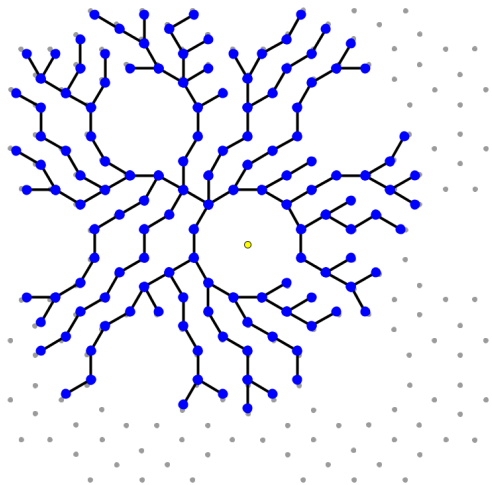
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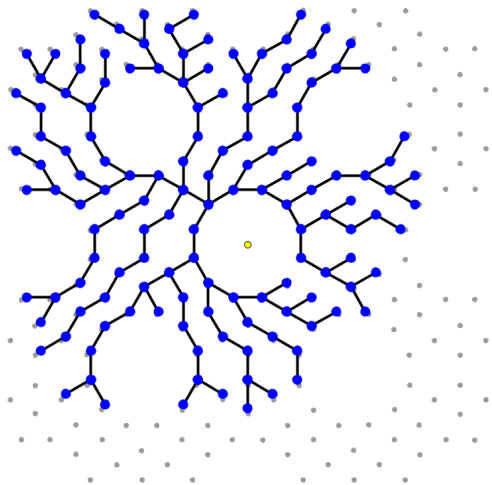
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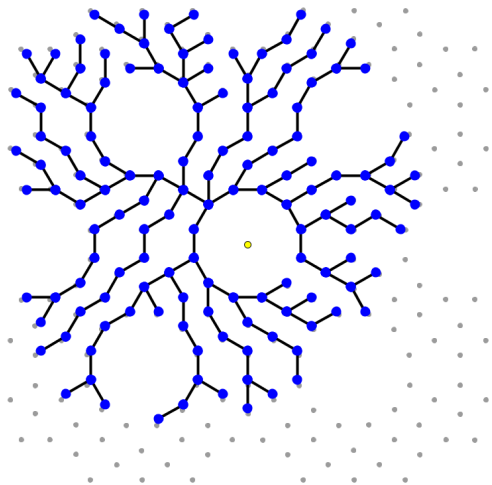
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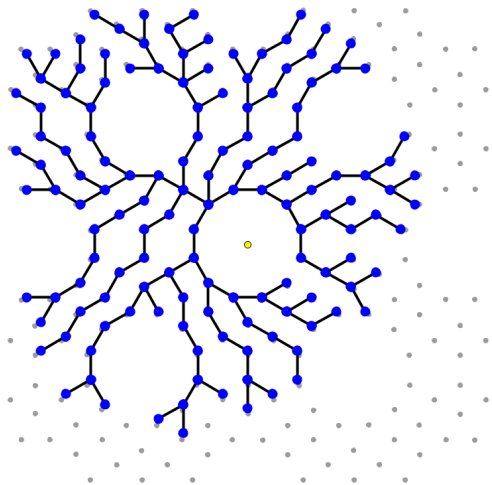
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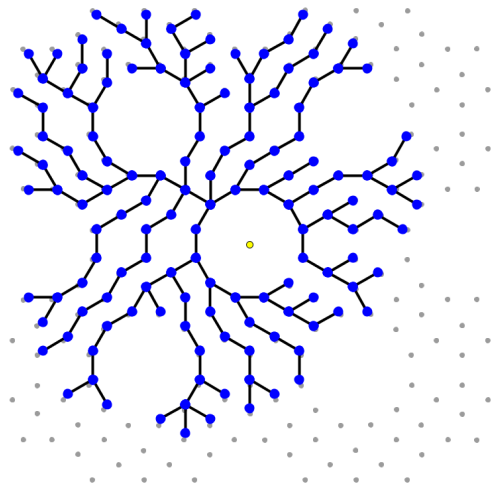
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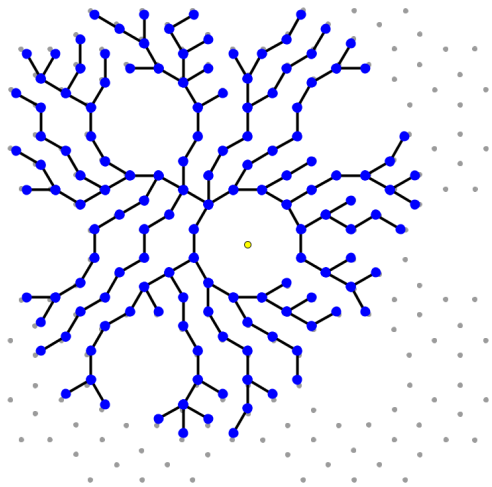
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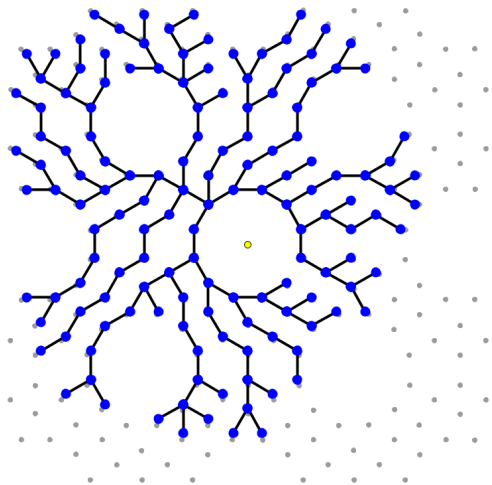
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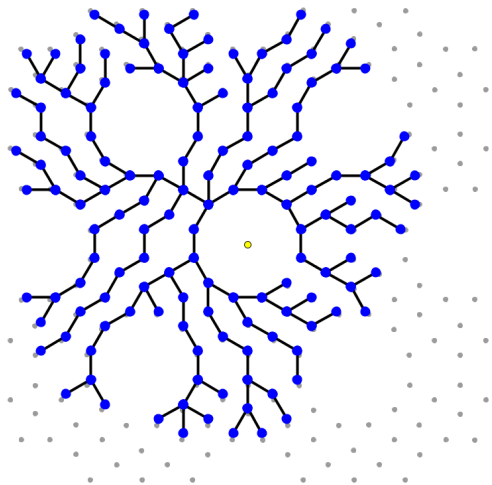
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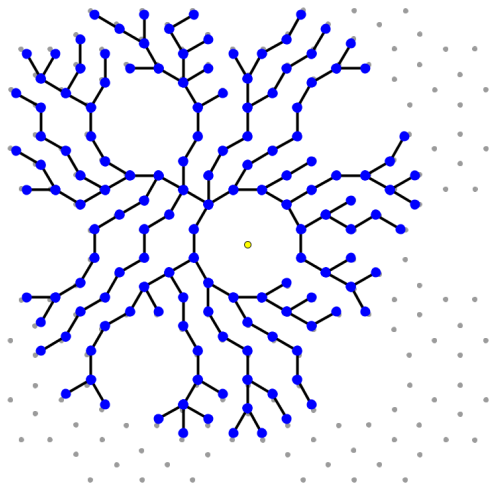
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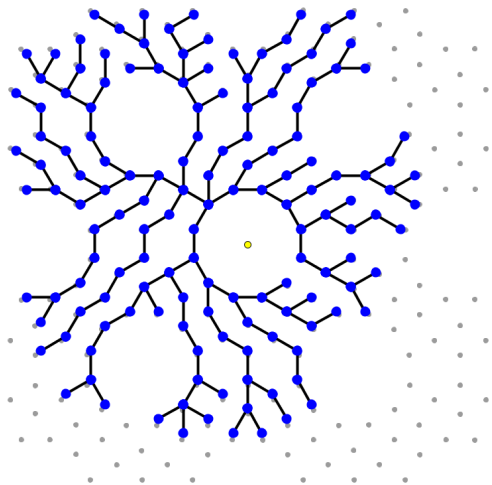
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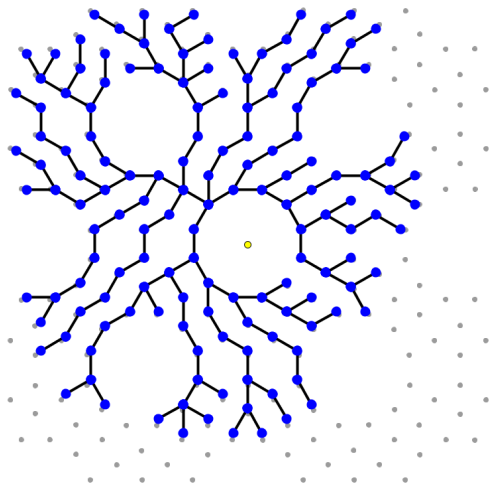
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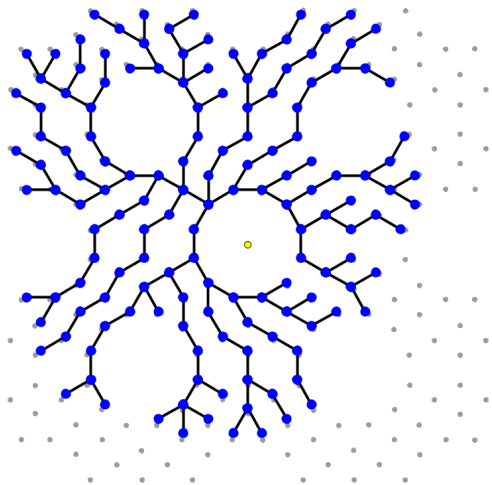
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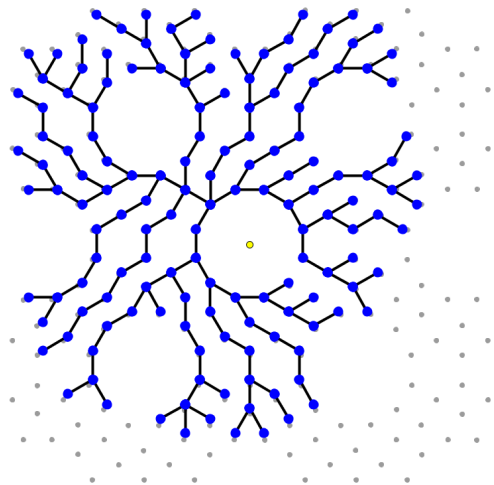
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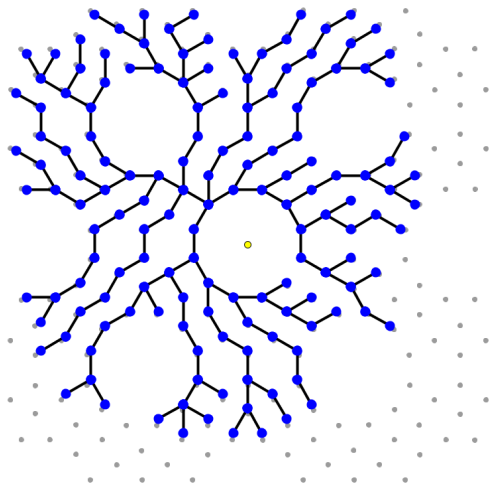
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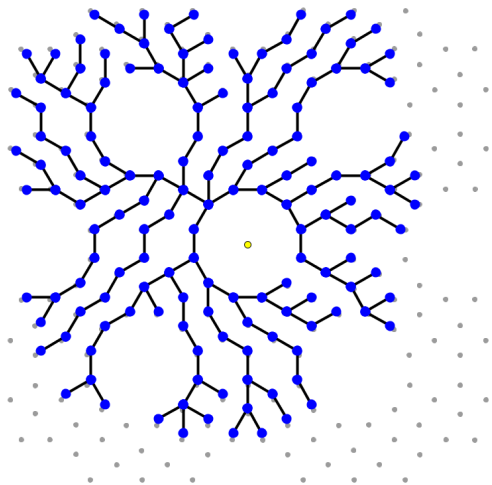
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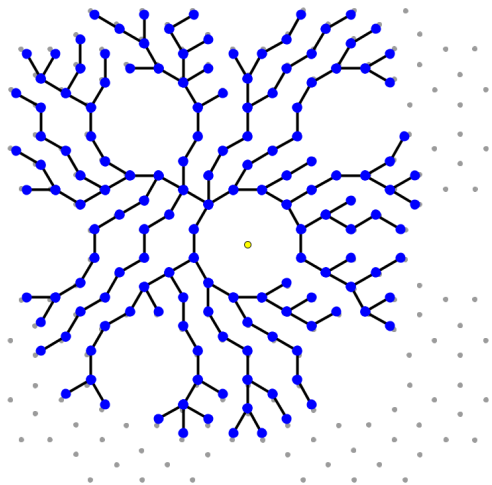
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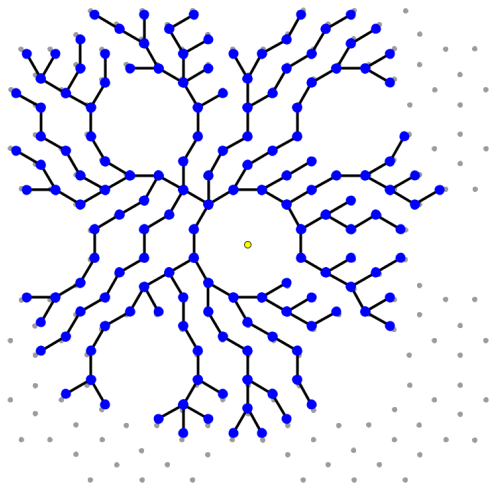
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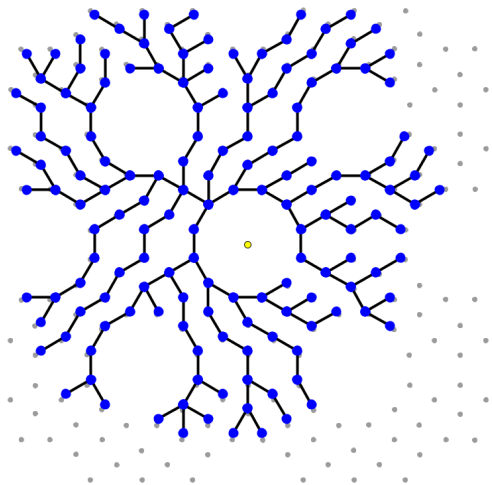
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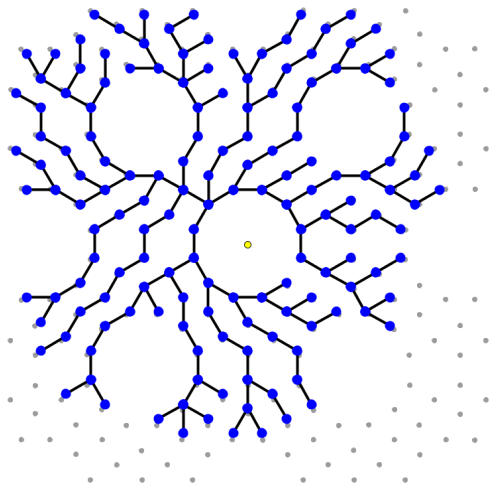
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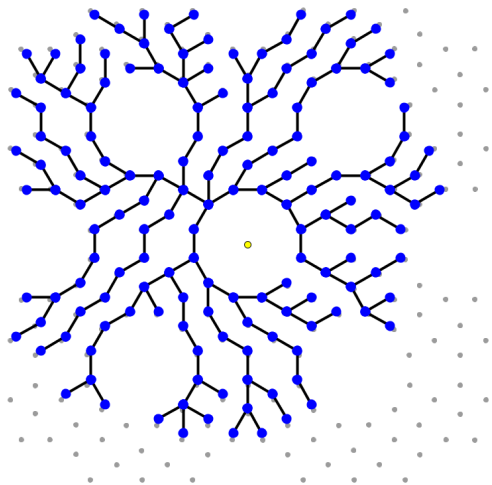
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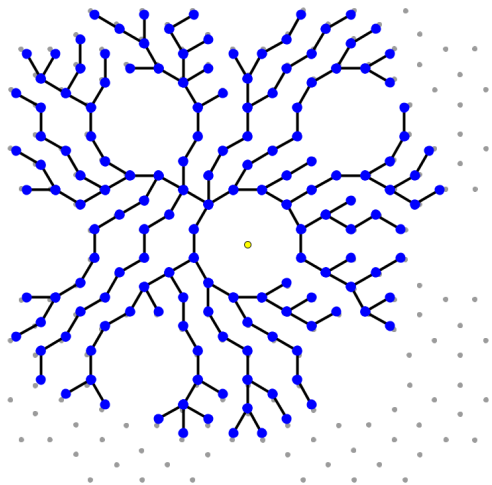
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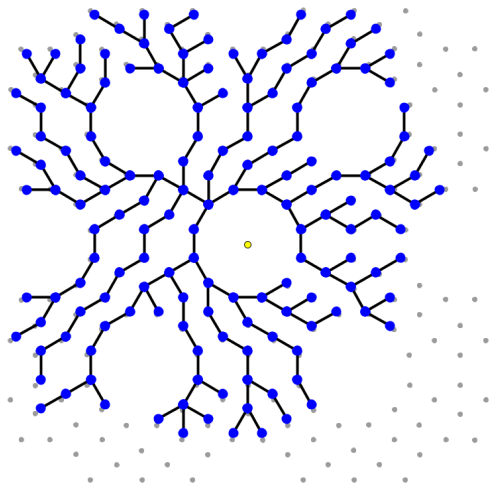
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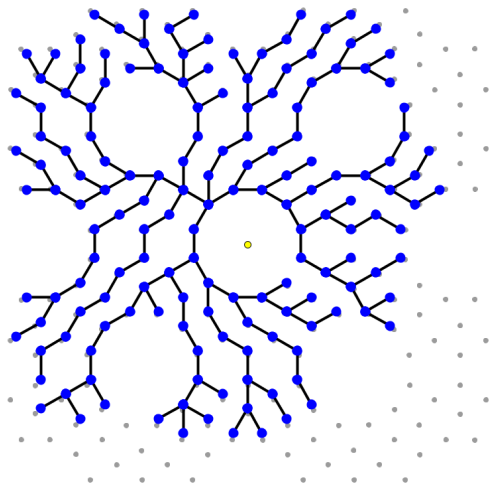
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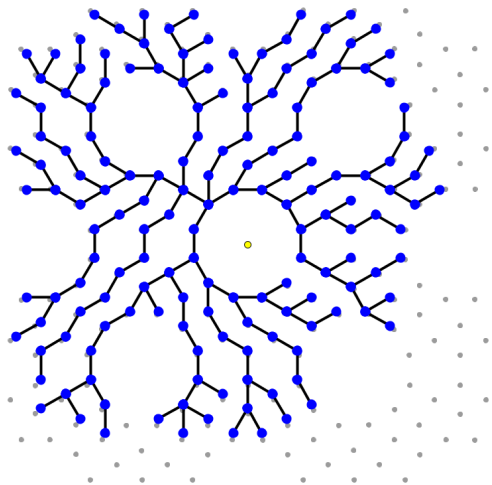
Automatic acquisition from tiny point cloud images



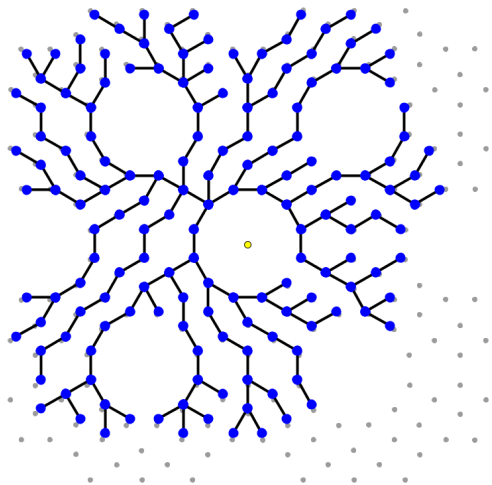
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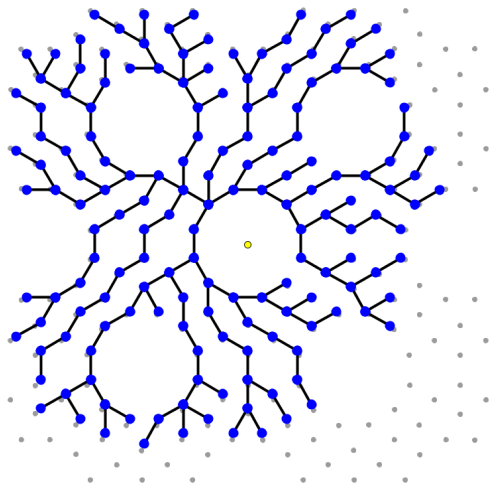
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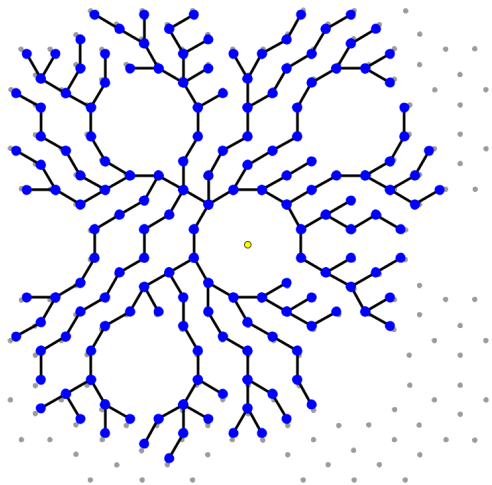
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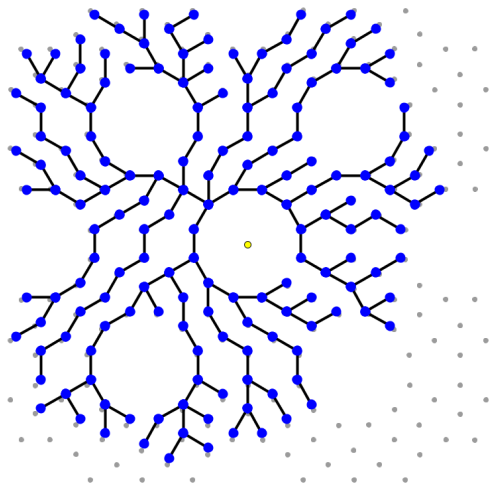
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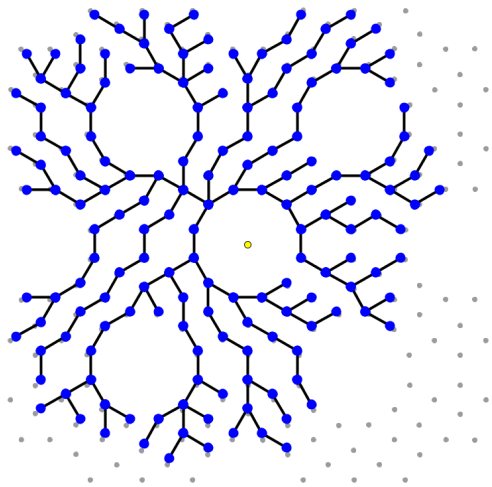
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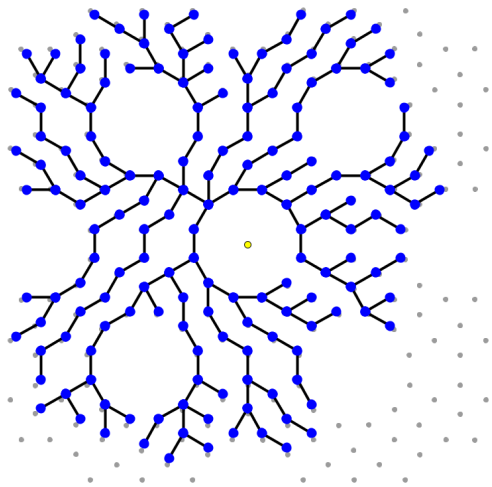
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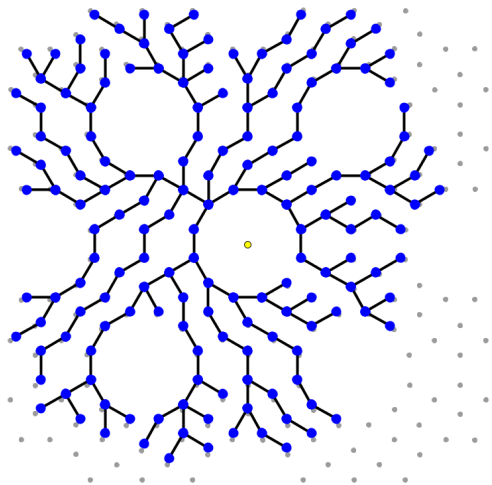
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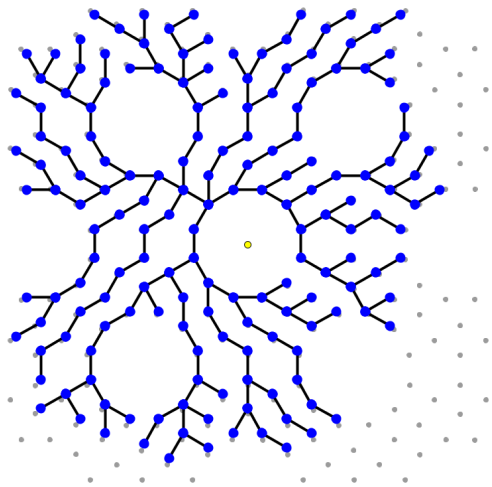
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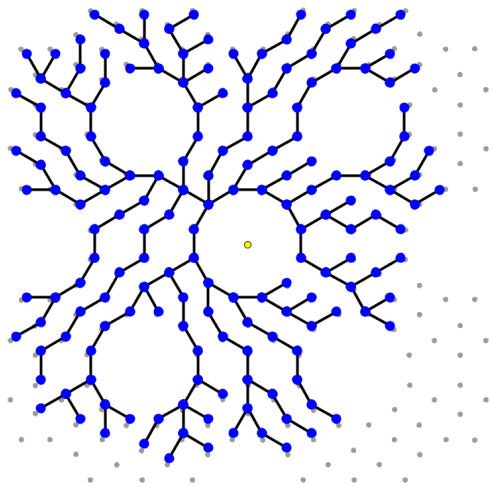
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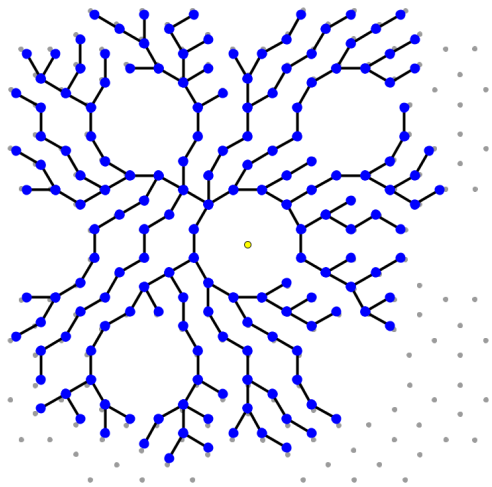
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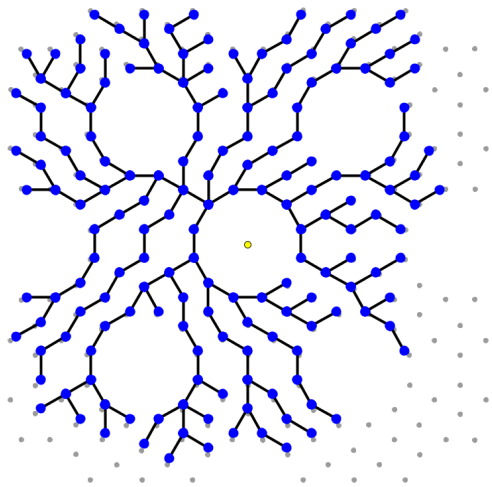
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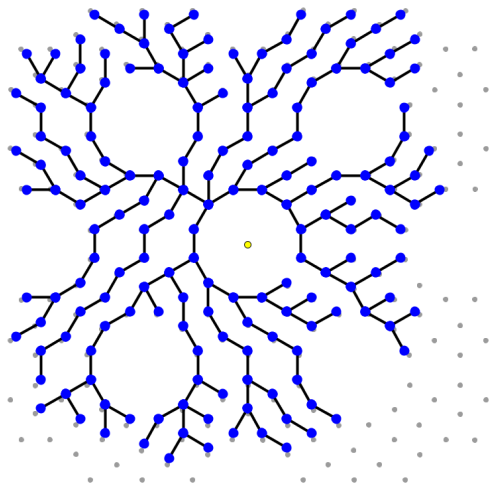
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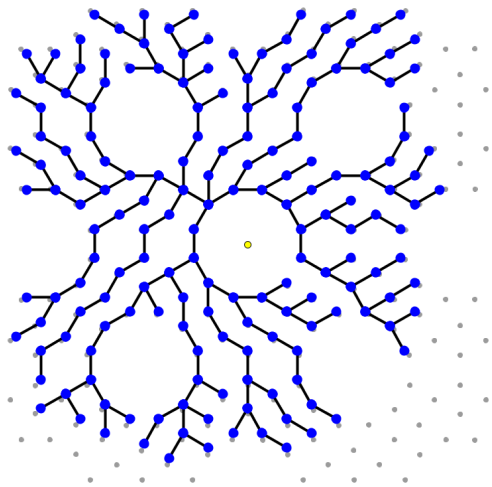
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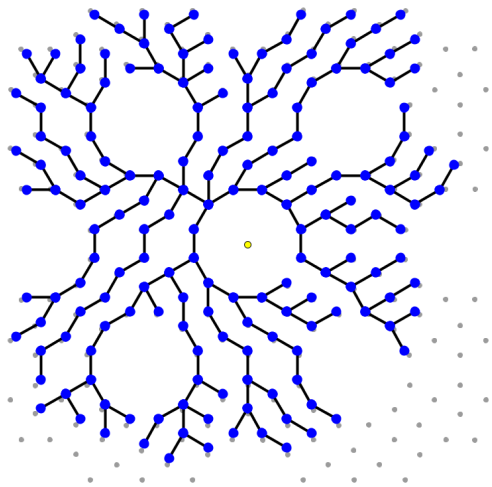
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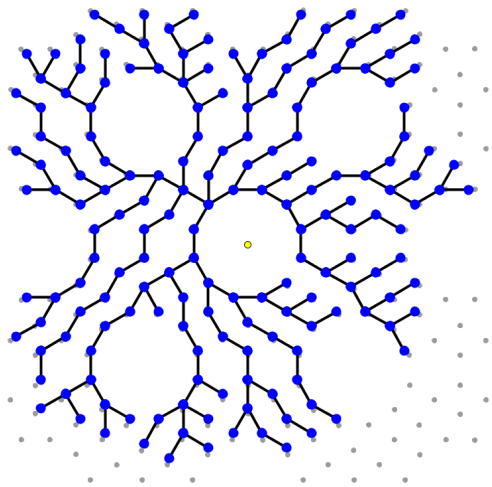
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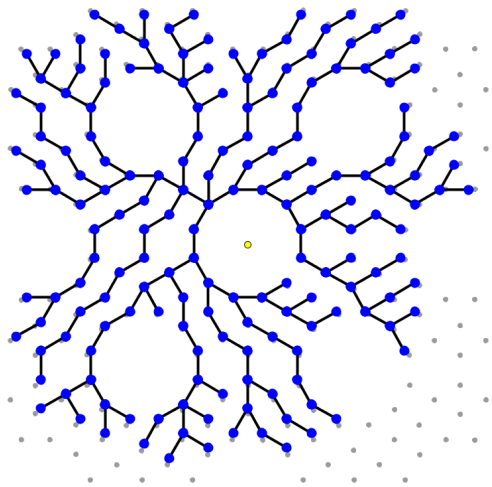
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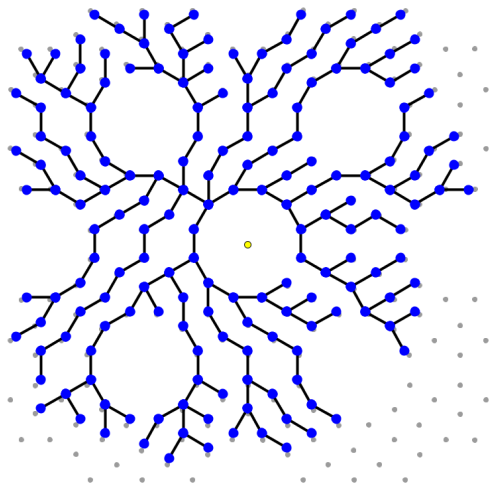
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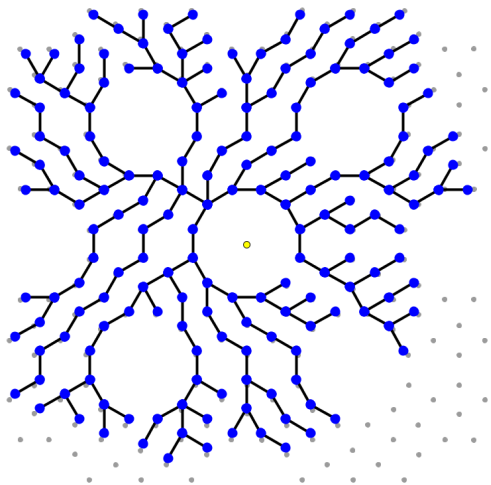
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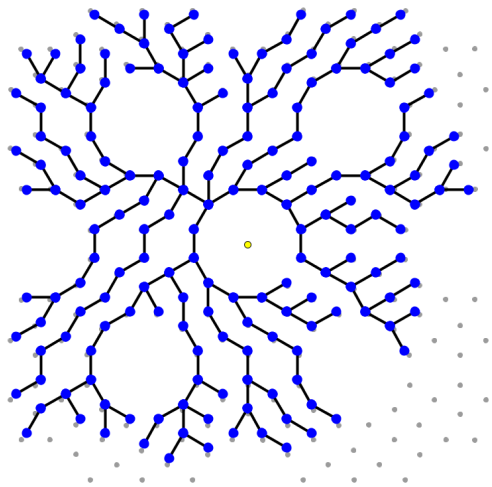
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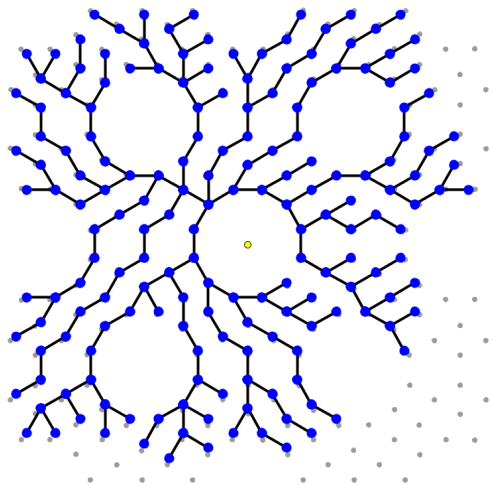
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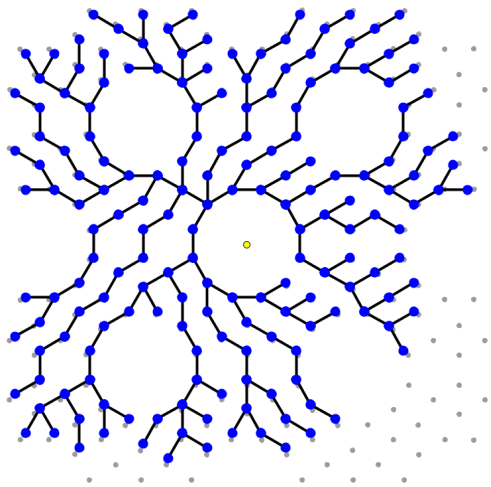
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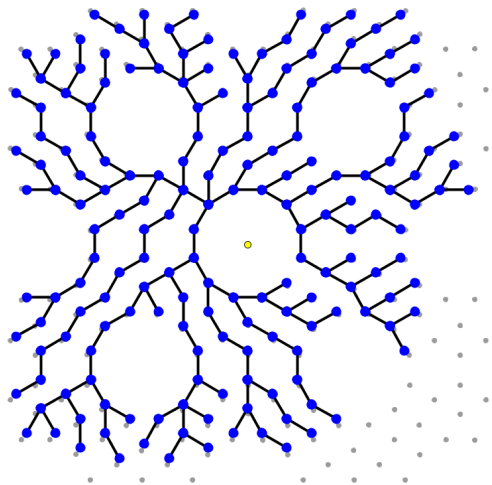
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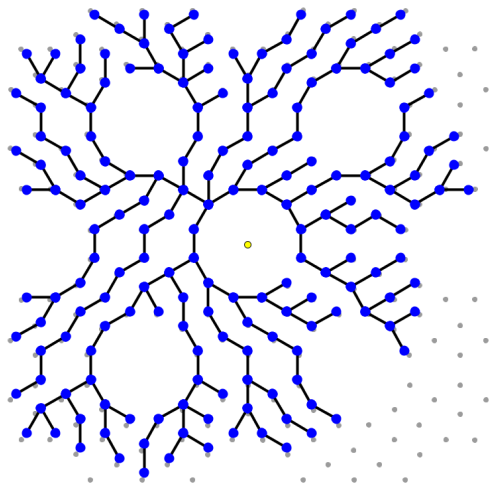
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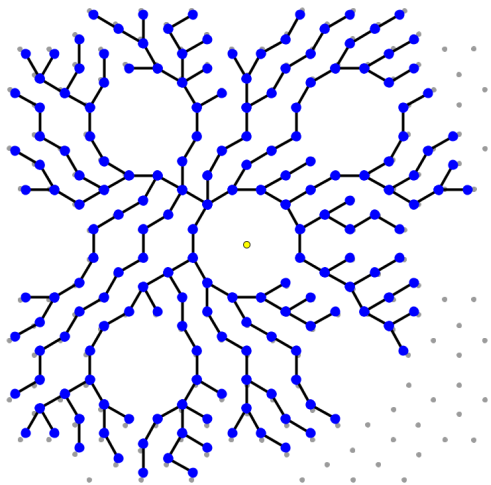
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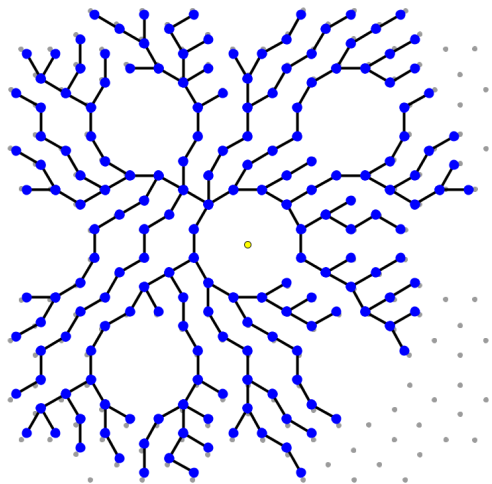
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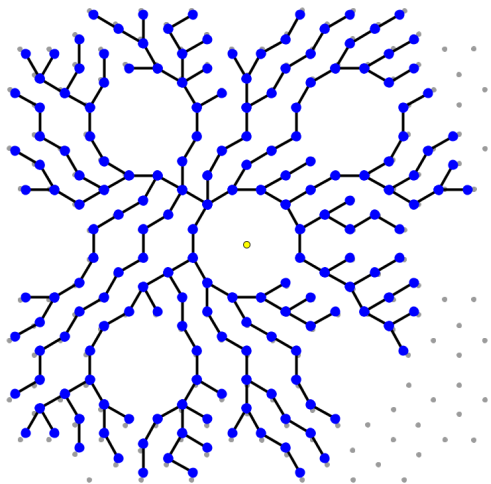
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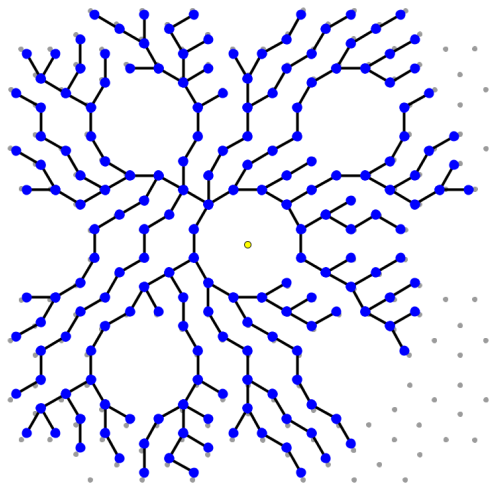
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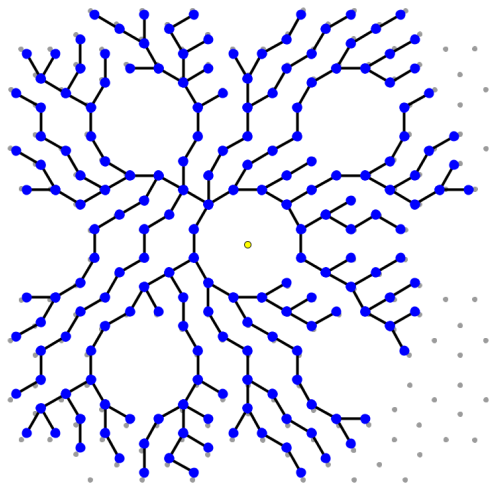
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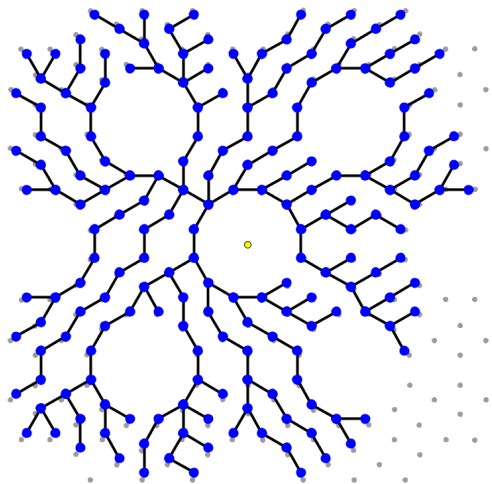
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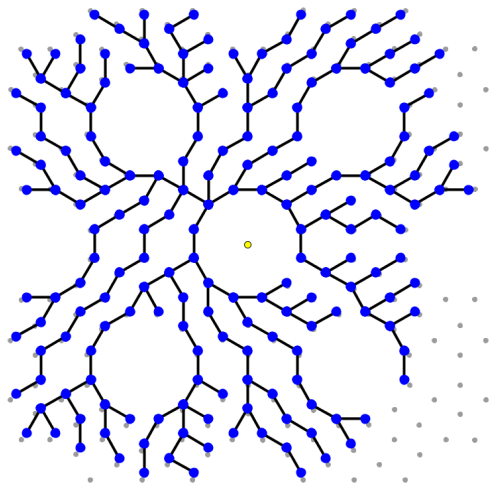
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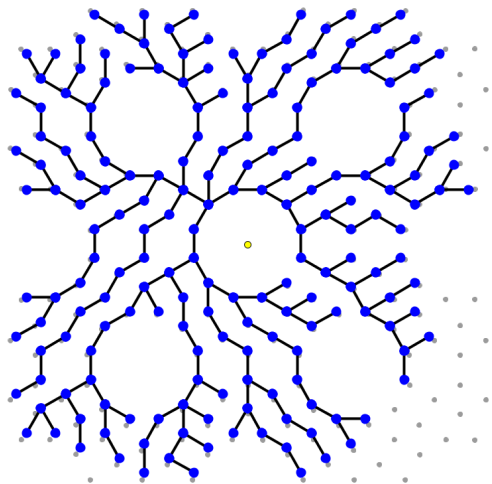
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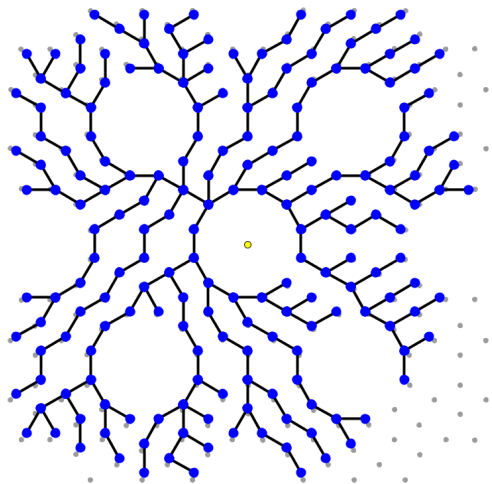
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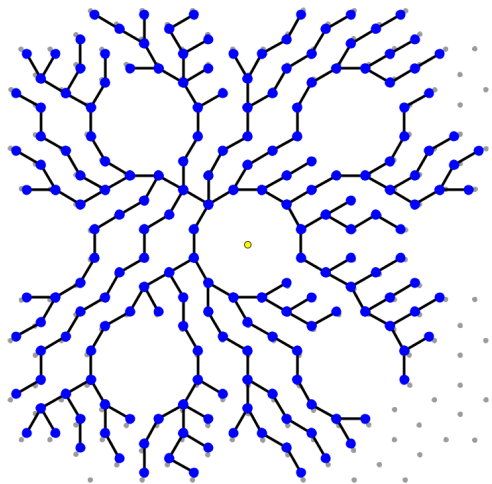
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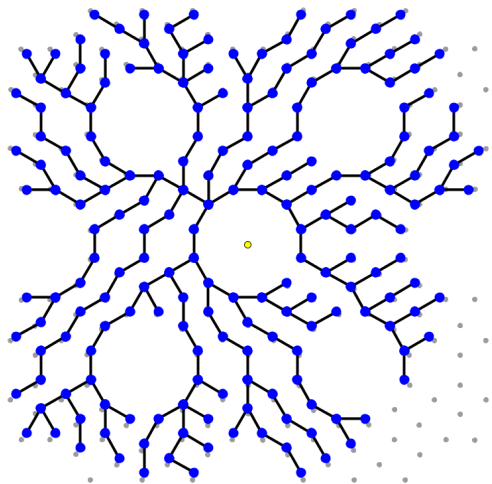
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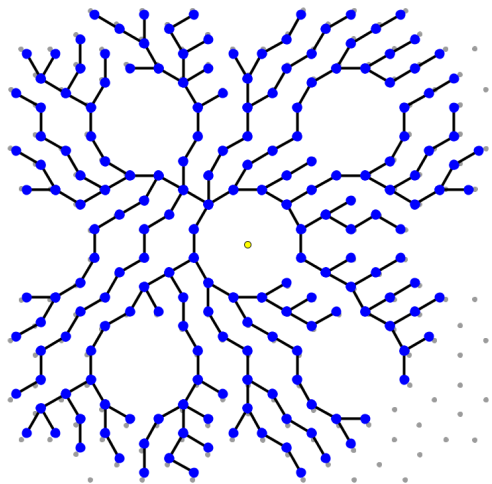
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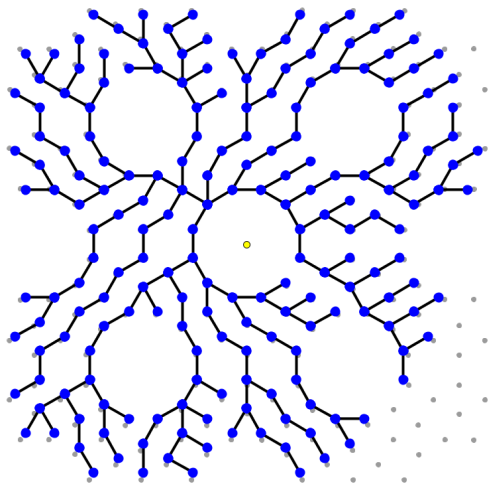
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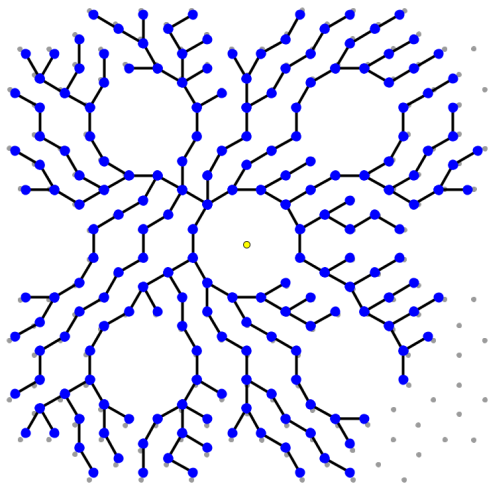
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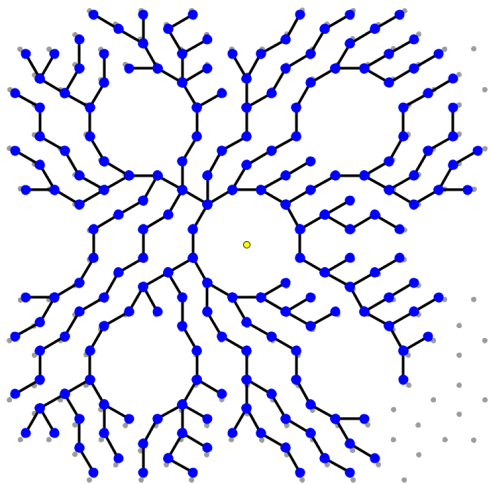
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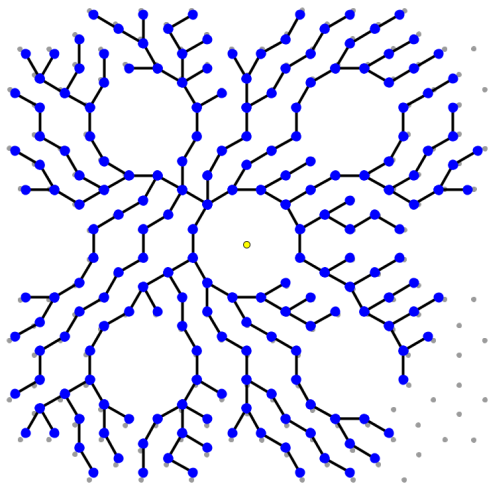
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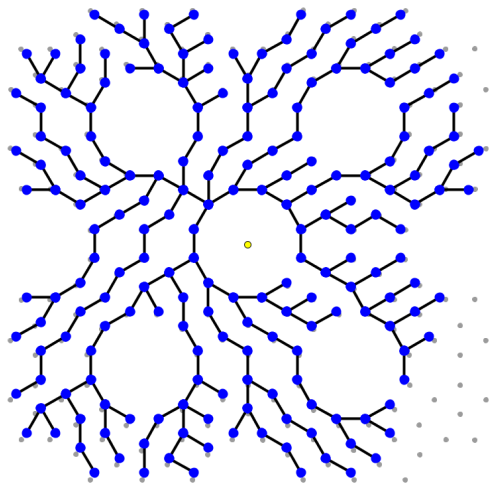
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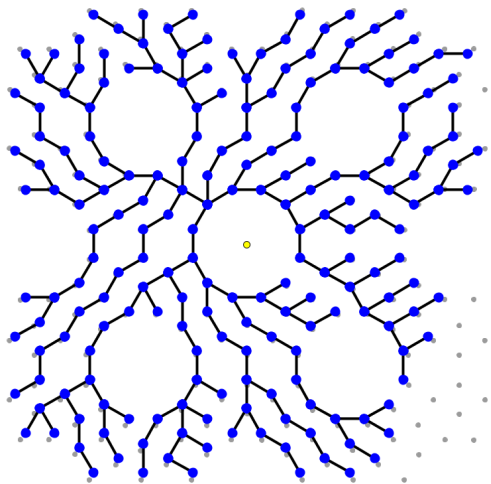
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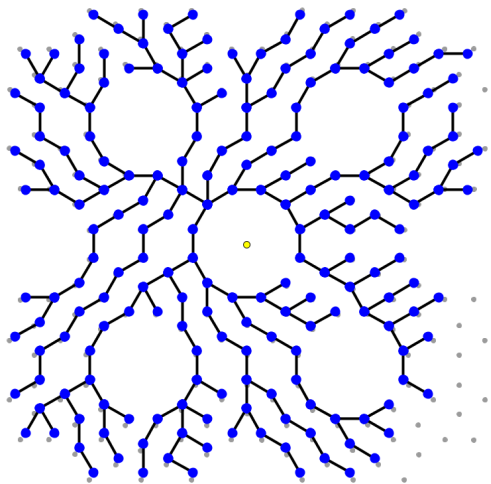
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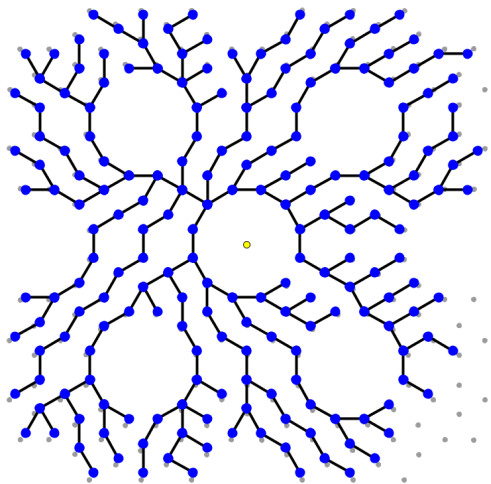
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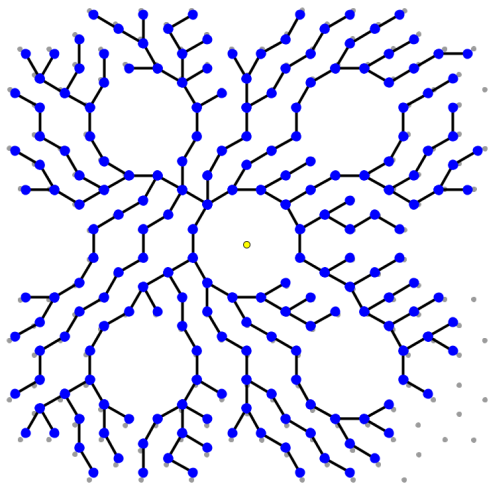
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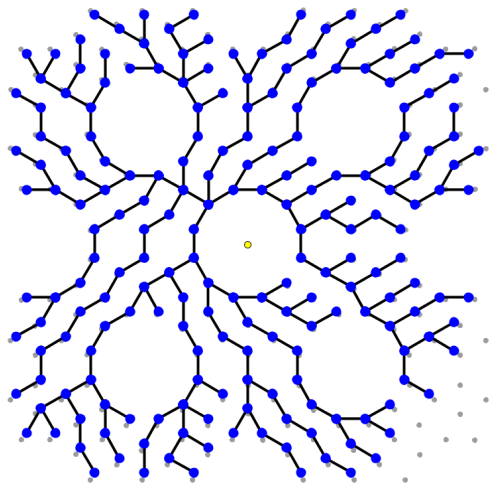
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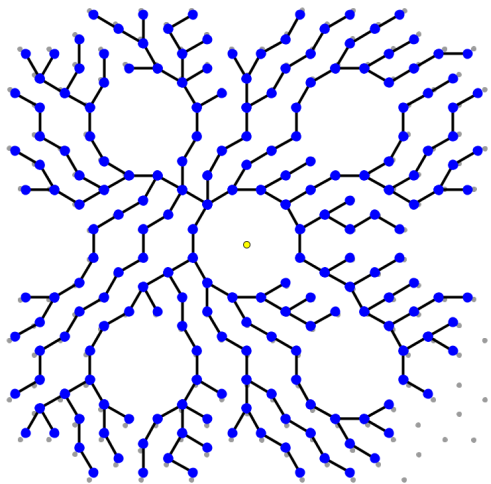
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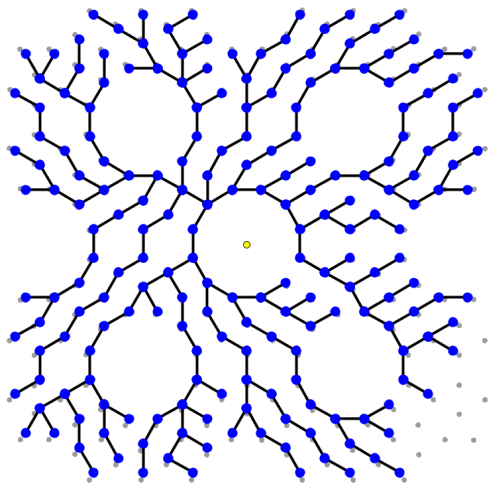
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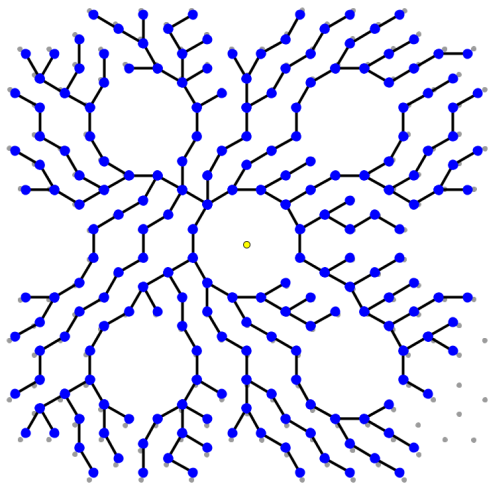
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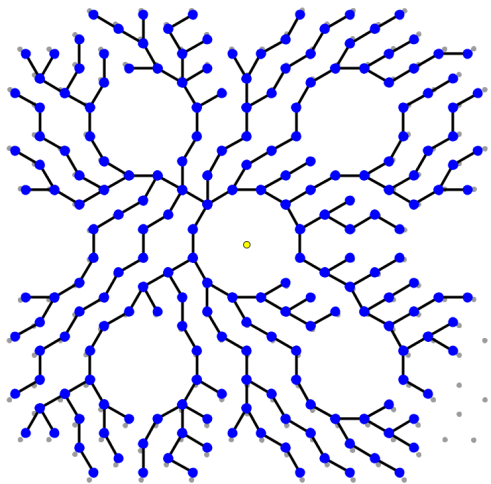
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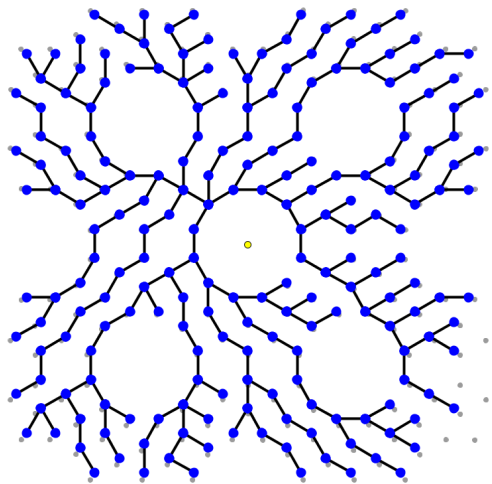
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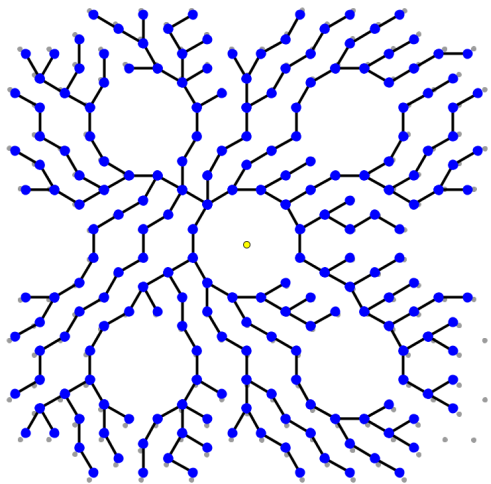
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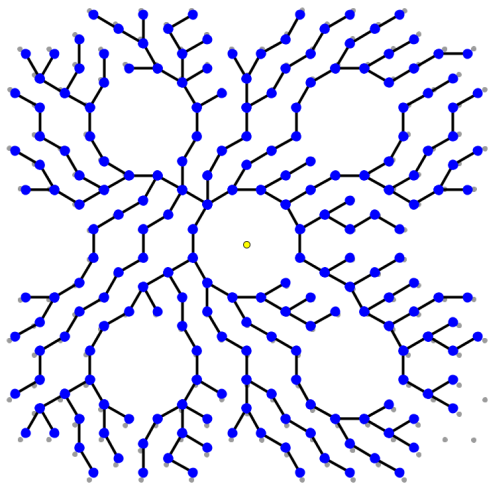
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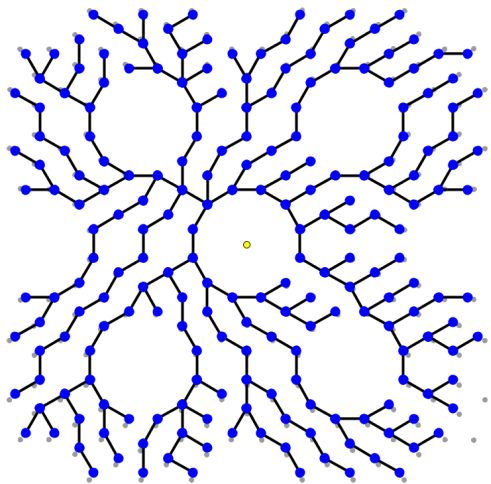
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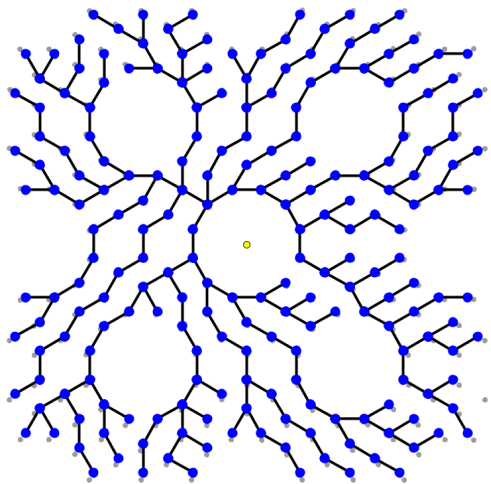
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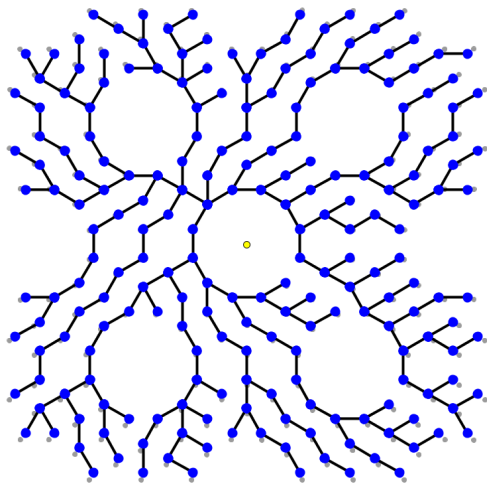
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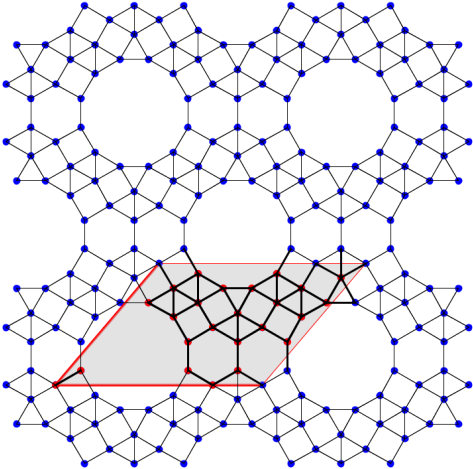
Automatic acquisition from tiny point cloud images



Automatic acquisition from tiny point cloud images



Automatic acquisition from tiny point cloud images



Web interface to catalogue

Synthesizing Periodic Tilings of Regular Polygons [\[pdf\]](#)

Asla Medeiros e Sá - Luiz Henrique de Figueiredo - José Ezequiel Soto Sánchez

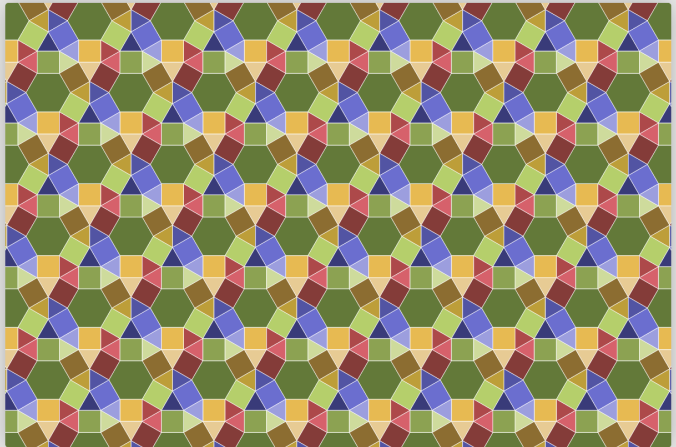


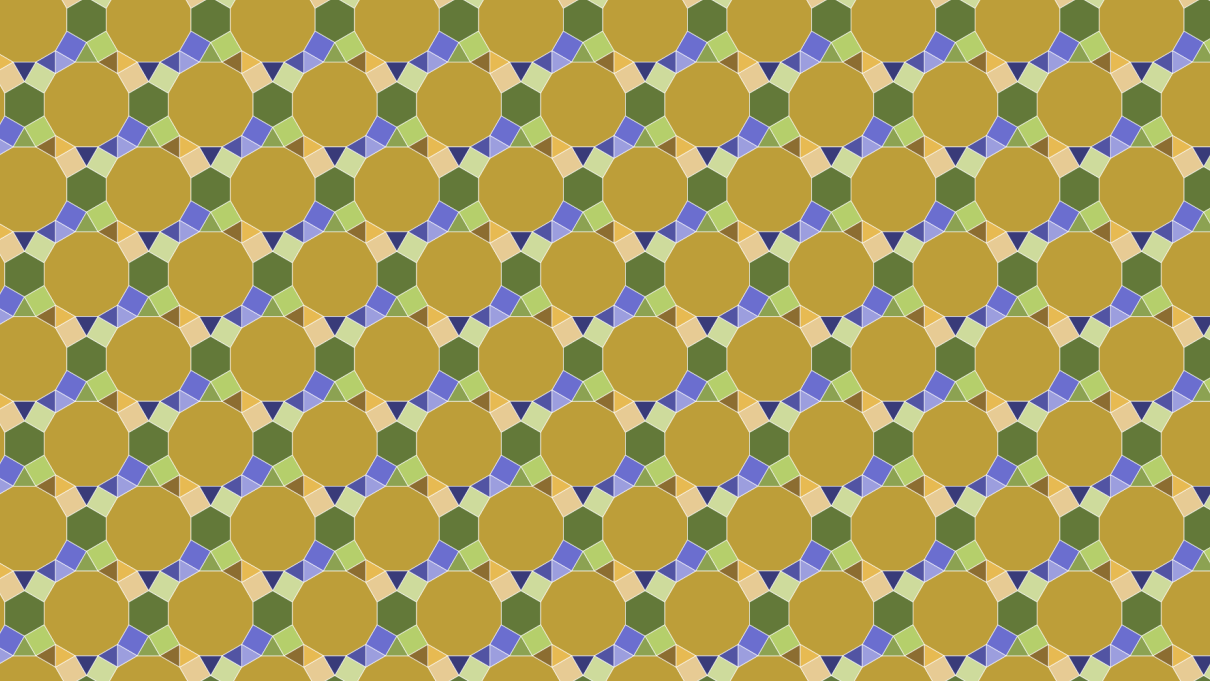
Tiling: MPU Color palette: D3 Category 20b

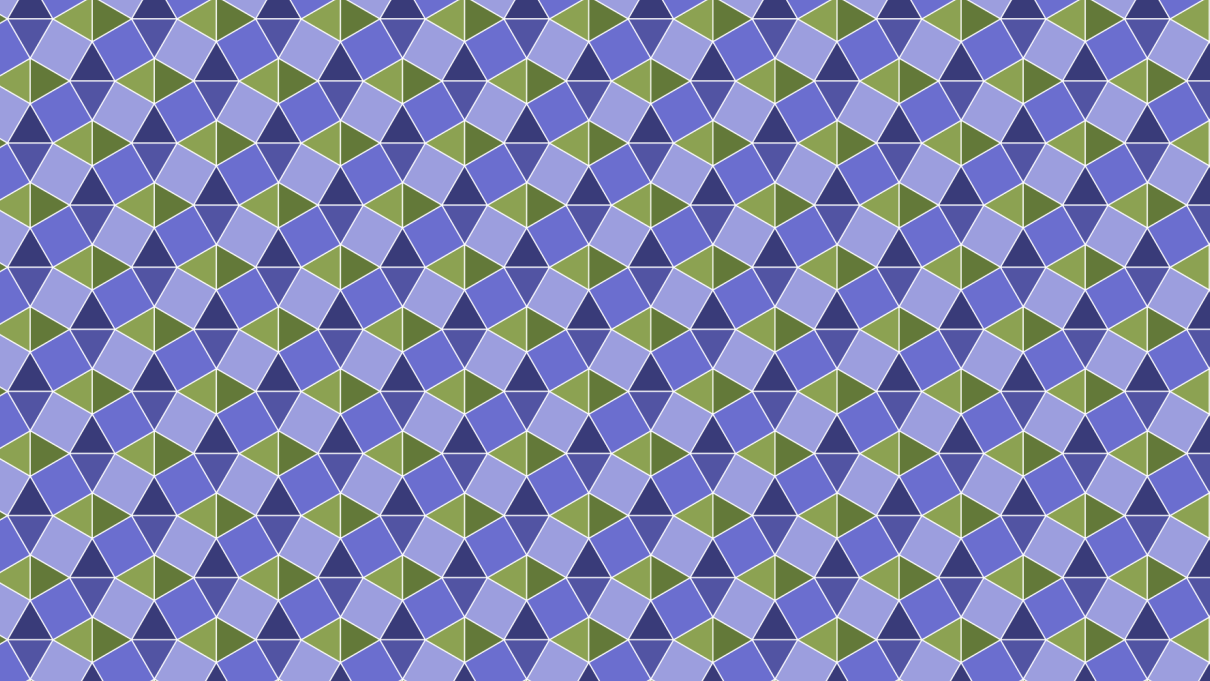
Show grid Show points Point Size: 7

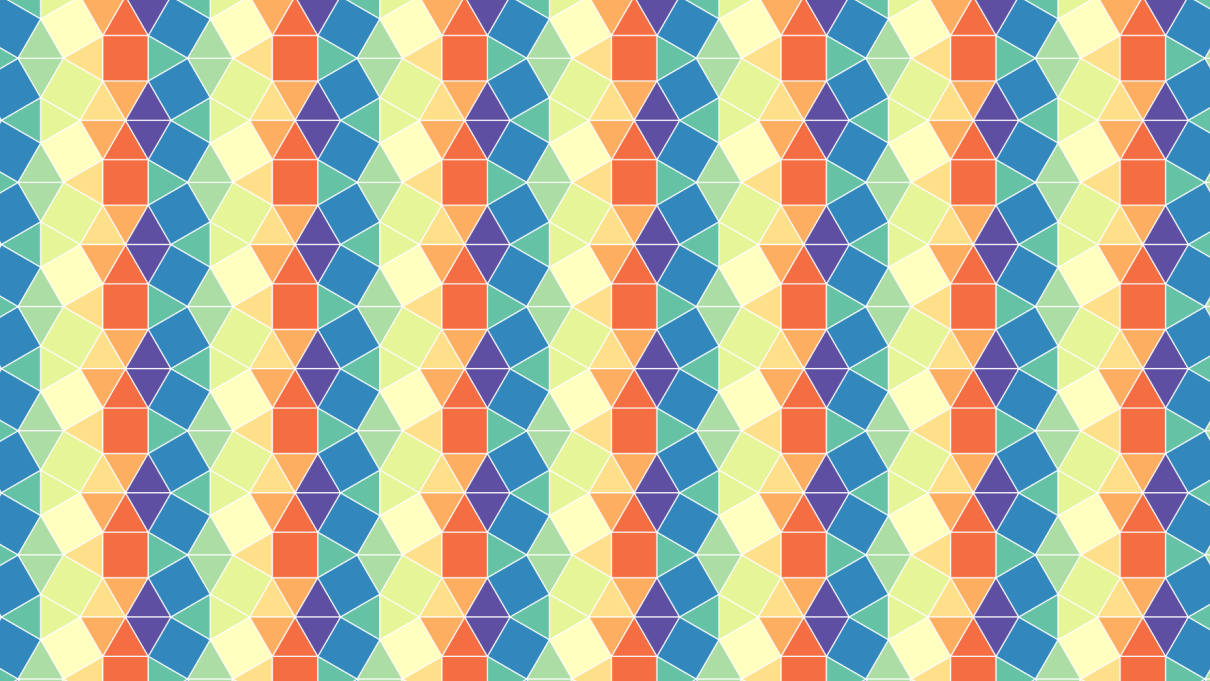
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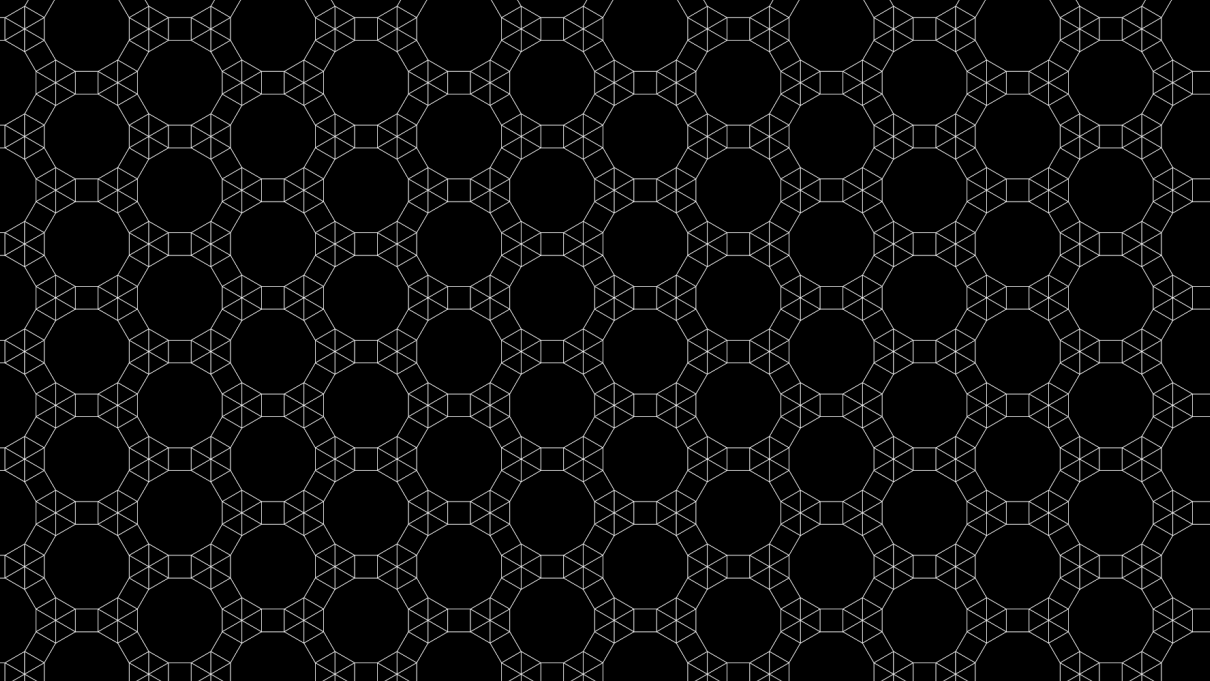
Export SVG

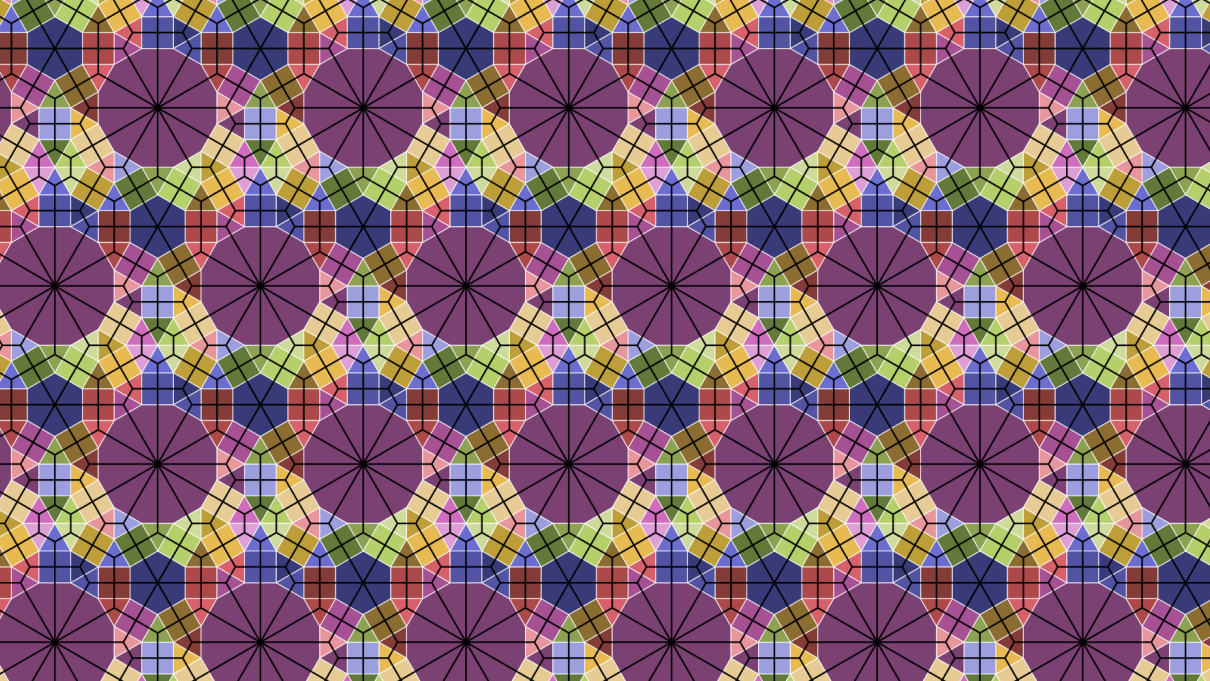


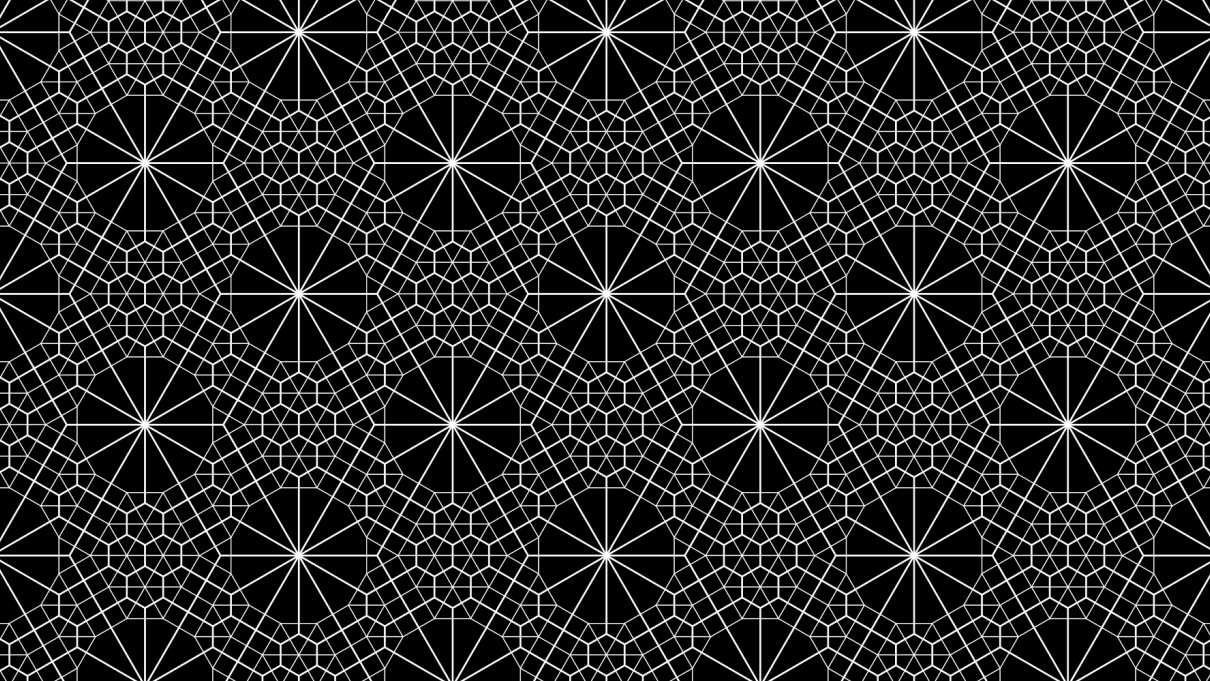












Web interface to catalogue



www.impa.br/~cheque/tiling/

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Synthesizing Periodic Tilings of Regular Polygons

Asla Medeiros e Sá · FGV

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