



Oktobermat

Images of Julia sets that you can trust

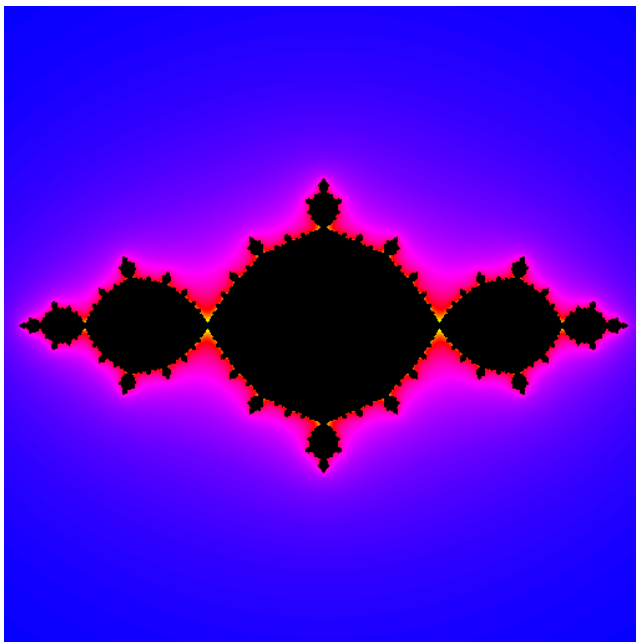
Luiz Henrique de Figueiredo



with

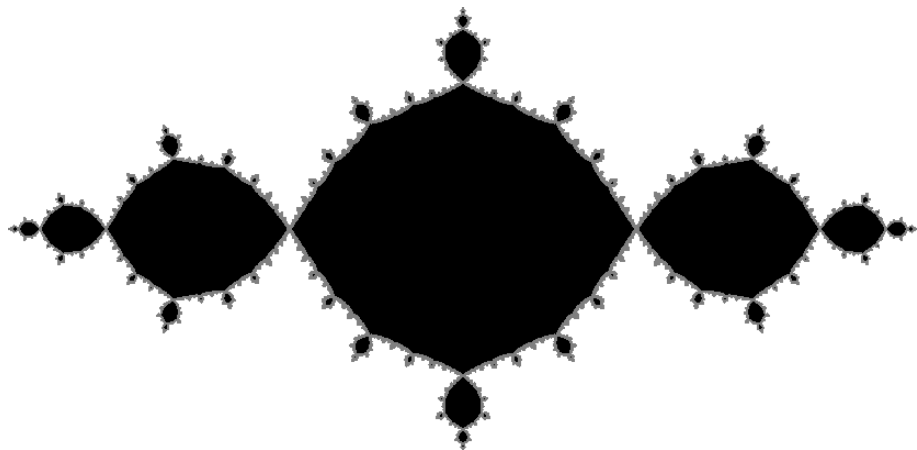
Diego Nehab (IMPA) • Jorge Stolfi (UNICAMP) • João Batista Oliveira (PUCRS)

Can we trust this beautiful image?



Curtis McMullen

Julia sets

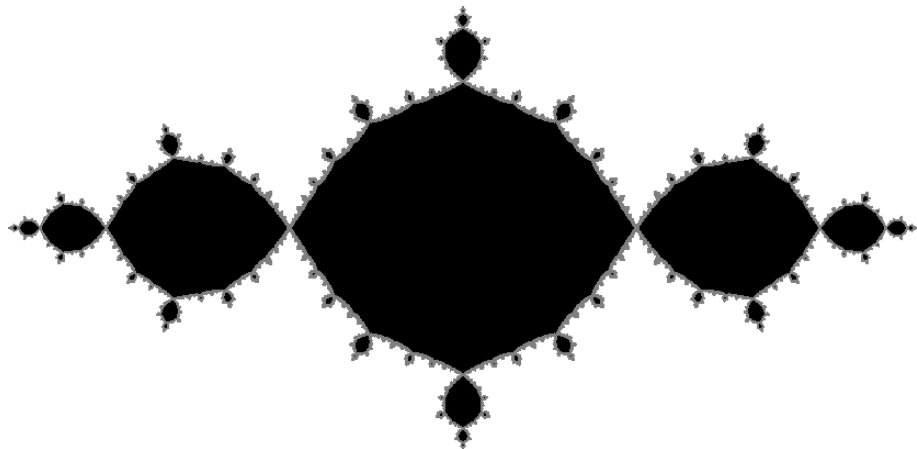


Study the **dynamics** of $f(z) = z^2 + c$ for $c \in \mathbb{C}$ fixed

$$z_1 = f(z_0), \quad z_2 = f(z_1), \quad \dots, \quad z_n = f(z_{n-1}) = f^n(z_0)$$

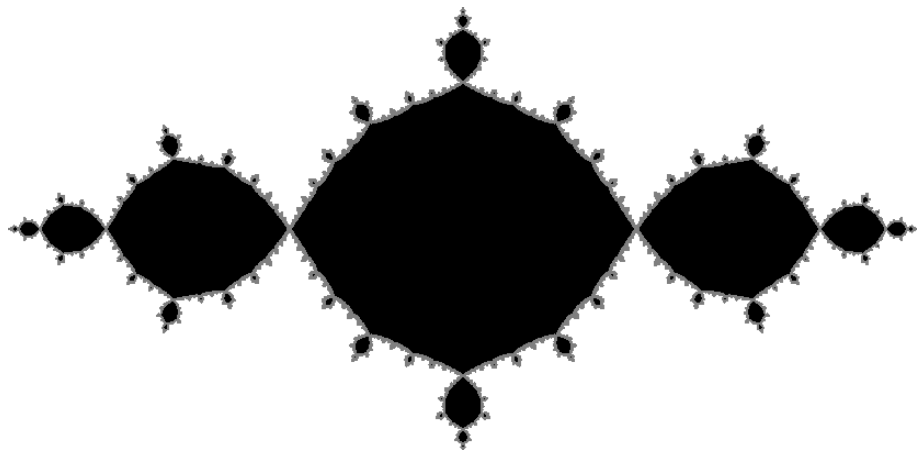
What happens with the **orbit** of $z_0 \in \mathbb{C}$ under f ?

Julia sets



- unbounded orbits
- bounded orbits

Julia sets



unbounded orbits

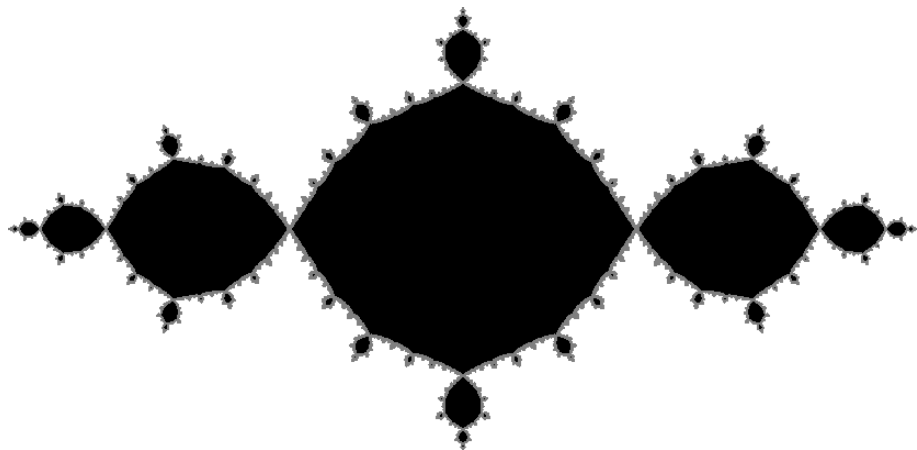


bounded orbits

attraction basin of ∞

$A(\infty)$

Julia sets



unbounded orbits

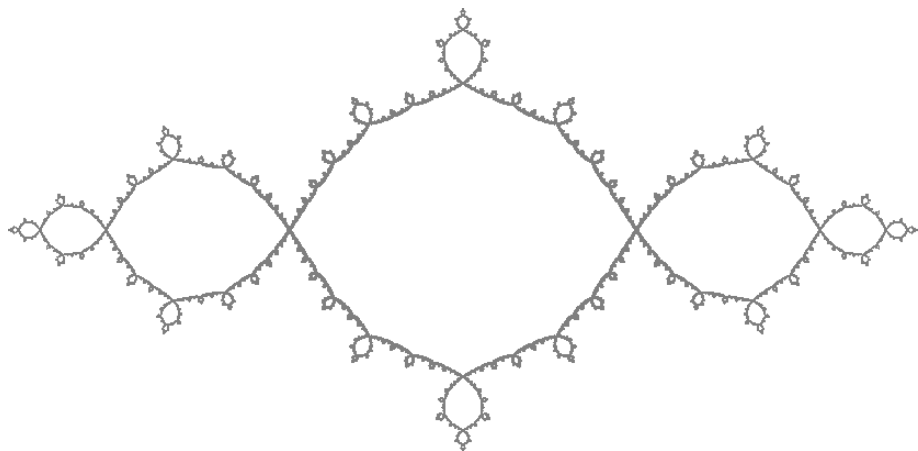





bounded orbits

attraction basin of ∞
filled Julia set

$A(\infty)$
 K

Julia sets

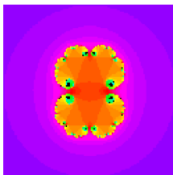


-  unbounded orbits
-  bounded orbits
-  common boundary

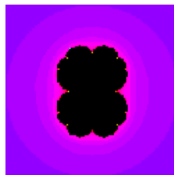
attraction basin of ∞
filled Julia set
Julia set

$A(\infty)$
 K
 J

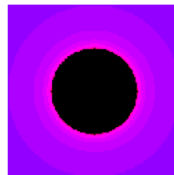
Julia set zoo



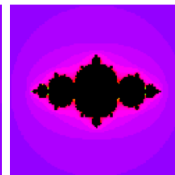
$c = 0.275$



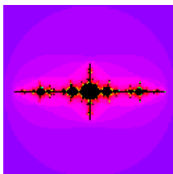
$c = \frac{1}{4}$



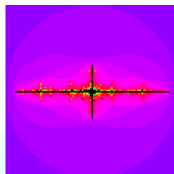
$c = 0$



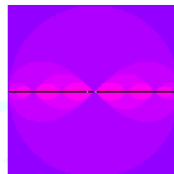
$c = -\frac{3}{4}$



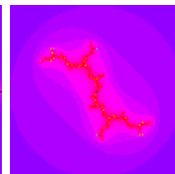
$c = -1.312$



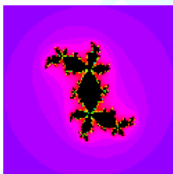
$c = -1.375$



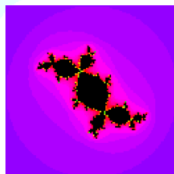
$c = -2$



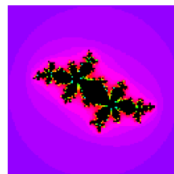
$c = i$



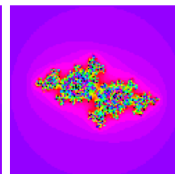
$c = (+0.285, +0.535)$



$c = (-0.125, +0.750)$

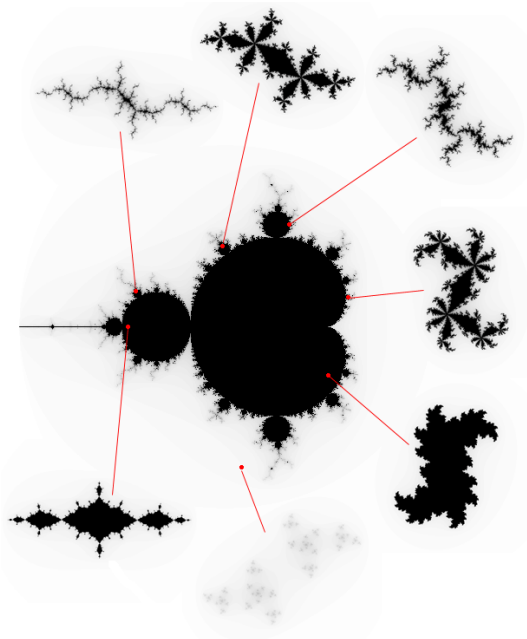


$c = (-0.500, +0.563)$



$c = (-0.687, +0.312)$

Julia set catalog: the Mandelbrot set

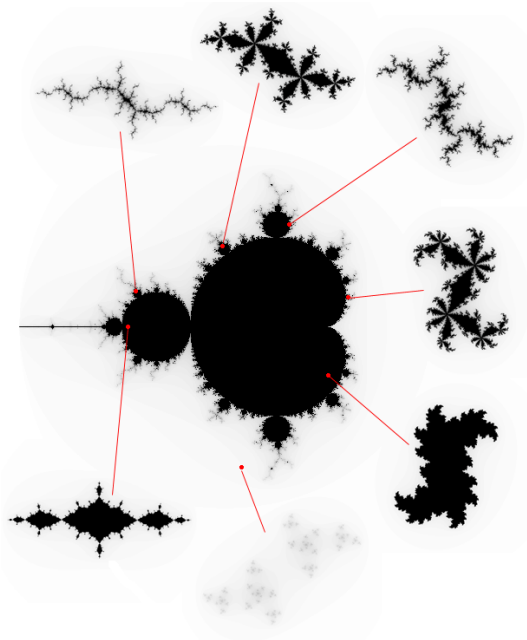


$$c \in \mathcal{M} := 0 \in K_c$$

Julia–Fatou dichotomy

$c \in \mathcal{M} \Rightarrow J_c$ is connected

$c \notin \mathcal{M} \Rightarrow J_c$ is a Cantor set



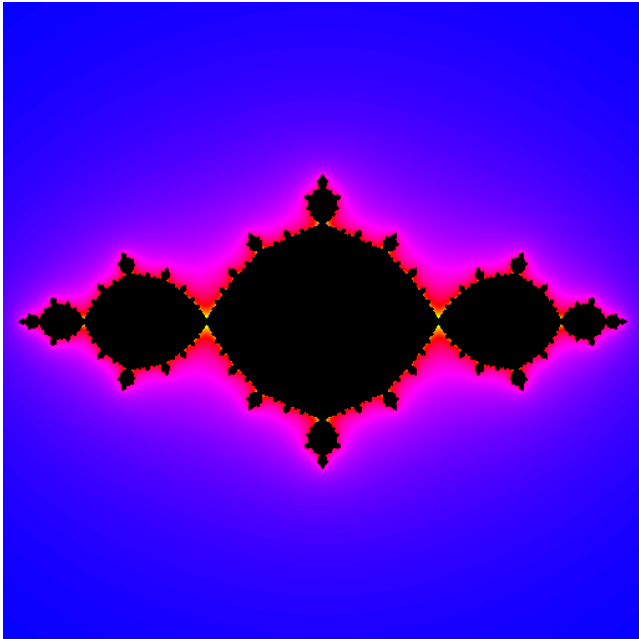
$$c \in \mathcal{M} := 0 \in K_c$$

Julia–Fatou dichotomy

$c \in \mathcal{M} \Rightarrow J_c$ is connected

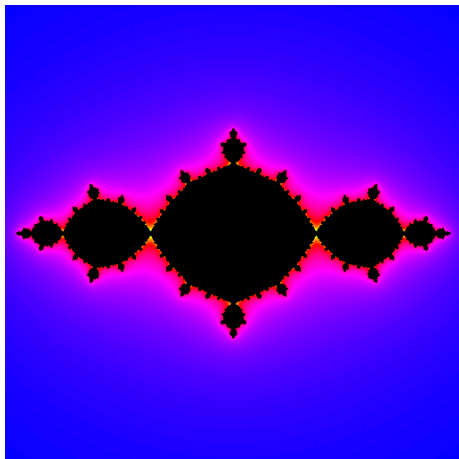
$c \notin \mathcal{M} \Rightarrow J_c$ is a Cantor set

Why distrust this beautiful image?



Curtis McMullen

Why distrust this beautiful image?



Escape-time algorithm

for z_0 in a grid of points in Ω

$z \leftarrow z_0$

$n \leftarrow 0$

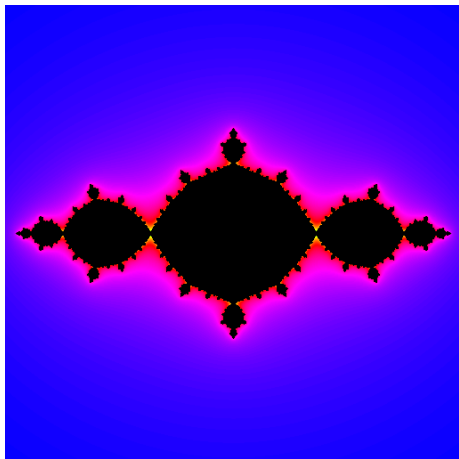
while $|z| \leq R$ and $n \leq N$ do

$z \leftarrow z^2 + c$

$n \leftarrow n + 1$

paint z_0 with color n

Why distrust this beautiful image?



Curtis McMullen

Escape-time algorithm

for z_0 in a grid of points in Ω

$z \leftarrow z_0$

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while $|z| \leq R$ and $n \leq N$ do

$z \leftarrow z^2 + c$

$n \leftarrow n + 1$

paint z_0 with color n

escape radius

$$R = \max(|c|, 2) \quad J \subset B(0, R)$$

Escape radius

Lemma. If $z \in \mathbb{C}$ and $|z| > R = \max(|c|, 2) \Rightarrow |f^n(z)| \rightarrow \infty$ as $n \rightarrow \infty$.

Proof. The triangle inequality gives

$$|z^2| = |z^2 + c - c| \leq |z^2 + c| + |c|$$

and so

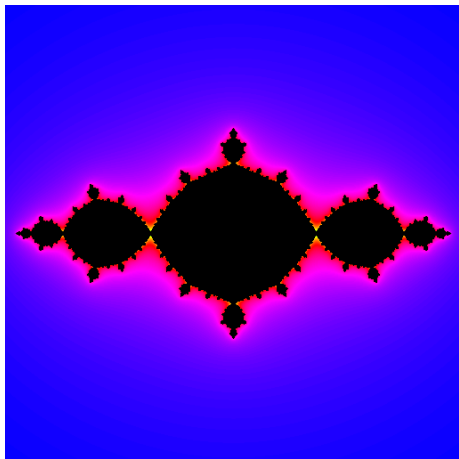
$$|f(z)| = |z^2 + c| \geq |z^2| - |c| = |z|^2 - |c| > |z|^2 - |z| = |z|(|z| - 1) > |z| > R$$

Iterating, we get $|f^n(z)| > |z|(|z| - 1)^n \rightarrow \infty$ because $|z| - 1 > 1$. \square

Corollary. Every unbounded orbit escapes to ∞ .

$A(\infty)$

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Curtis McMullen

Escape-time algorithm

for z_0 in a grid of points in Ω

$z \leftarrow z_0$

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while $|z| \leq R$ and $n \leq N$ do

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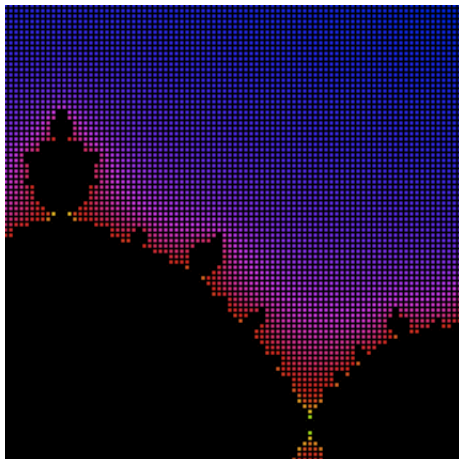
$n \leftarrow n + 1$

paint z_0 with color n

escape radius

$$R = \max(|c|, 2) \quad J \subset B(0, R)$$

Why distrust this beautiful image?



Curtis McMullen

Escape-time algorithm

```
for  $z_0$  in a grid of points in  $\Omega$   
   $z \leftarrow z_0$   
   $n \leftarrow 0$   
  while  $|z| \leq R$  and  $n \leq N$  do  
     $z \leftarrow z^2 + c$   
     $n \leftarrow n + 1$   
  paint  $z_0$  with color  $n$ 
```


Why distrust this beautiful image?

- ▶ Spatial sampling
need fine grid
what happens between samples?

Escape-time algorithm

```
for  $z_0$  in a grid of points in  $\Omega$   
   $z \leftarrow z_0$   
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  while  $|z| \leq R$  and  $n \leq N$  do  
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     $n \leftarrow n + 1$   
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```

Why distrust this beautiful image?

- ▶ Spatial sampling
- ▶ Partial orbits
program cannot run forever

Escape-time algorithm

```
for  $z_0$  in a grid of points in  $\Omega$   
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  while  $|z| \leq R$  and  $n \leq N$  do  
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  paint  $z_0$  with color  $n$ 
```

Why distrust this beautiful image?

- ▶ Spatial sampling
- ▶ Partial orbits
- ▶ Floating-point rounding errors
squaring needs double digits

Escape-time algorithm

```
for  $z_0$  in a grid of points in  $\Omega$ 
   $z \leftarrow z_0$ 
   $n \leftarrow 0$ 
  while  $|z| \leq R$  and  $n \leq N$  do
     $z \leftarrow z^2 + c$ 
     $n \leftarrow n + 1$ 
  paint  $z_0$  with color  $n$ 
```

Why distrust this beautiful image?

- ▶ Spatial sampling

Compute color on grid points

Cannot be sure grid is fine enough

Cannot be sure behavior at sample points is typical

Finer grid \Rightarrow more detail

- ▶ Partial orbits

Can only compute partial orbits

Cannot be sure partial orbits are long enough

Longer orbits \Rightarrow more detail

- ▶ Floating-point errors

z^2 needs twice the number of digits that z needs

Do rounding errors during iteration influence classification of points?

Multiple-precision \Rightarrow more detail (deep zoom)

You can trust our method

- ▶ No spatial sampling
- ▶ No orbits
- ▶ No floating-point errors

You can trust our method

- ▶ No spatial sampling

Classify **entire rectangles** in the complex plane

Spatial resolution limited by available memory

Deeper quadtree \Rightarrow more detail

- ▶ No orbits

- ▶ No floating-point errors

You can trust our method

- ▶ No spatial sampling

Classify **entire rectangles** in the complex plane

Spatial resolution limited by available memory

Deeper quadtree \Rightarrow more detail

- ▶ No orbits

Evaluate f once on each cell using interval arithmetic

Perform **no function iteration** at all

Use cell mapping and color propagation in graphs

- ▶ No floating-point errors

You can trust our method

- ▶ No spatial sampling

Classify **entire rectangles** in the complex plane

Spatial resolution limited by available memory

Deeper quadtree \Rightarrow more detail

- ▶ No orbits

Evaluate f once on each cell using interval arithmetic

Perform **no function iteration** at all

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- ▶ No floating-point errors

All numbers are dyadic fractions with restricted range and precision

Use **error-free fixed-point** arithmetic

Precision depends only on spatial resolution

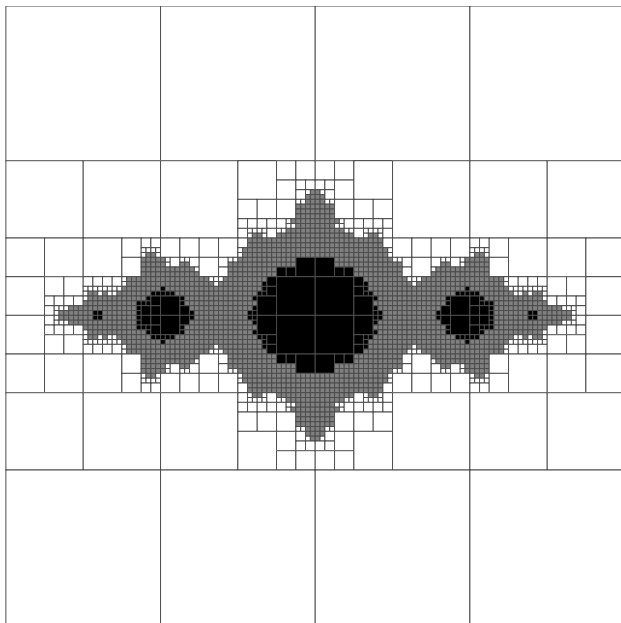
Standard double-precision floating-point enough for huge images

Our algorithm

quadtrees for

$$\Omega = [-R, R] \times [-R, R]$$

- ▶ white rectangles contained in $A(\infty)$
- ▶ black rectangles contained in K
- ▶ gray rectangles contain J



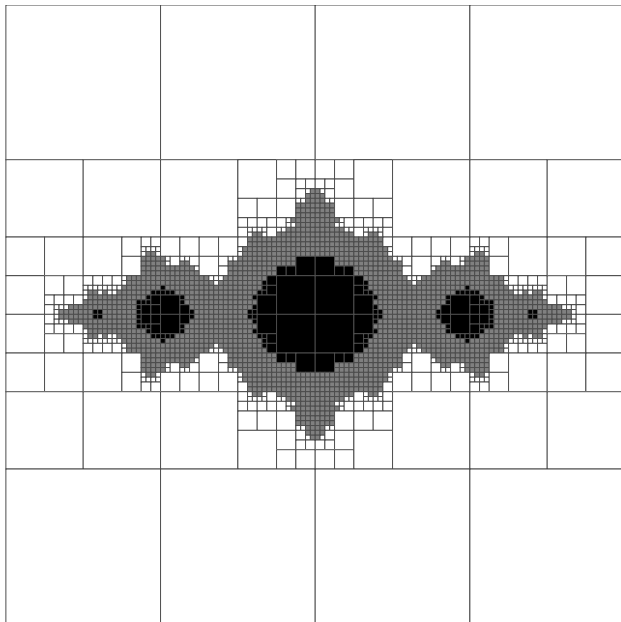
Our algorithm

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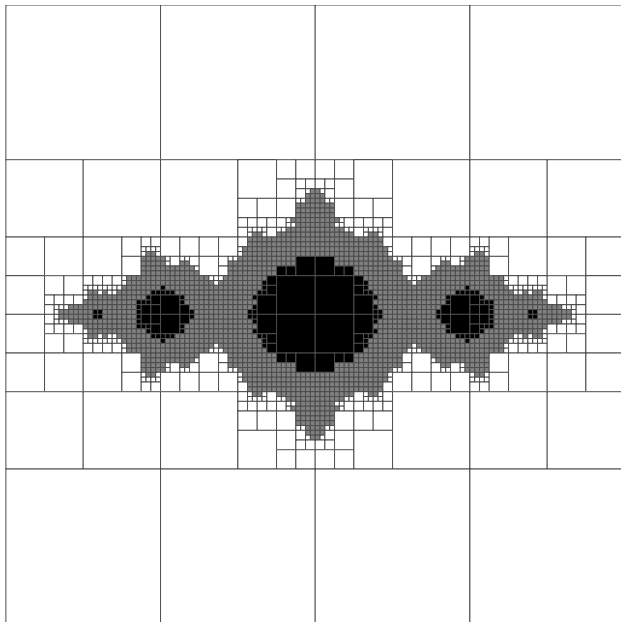
certified decomposition



Our algorithm

quadtrees for
 $\Omega = [-R, R] \times [-R, R]$

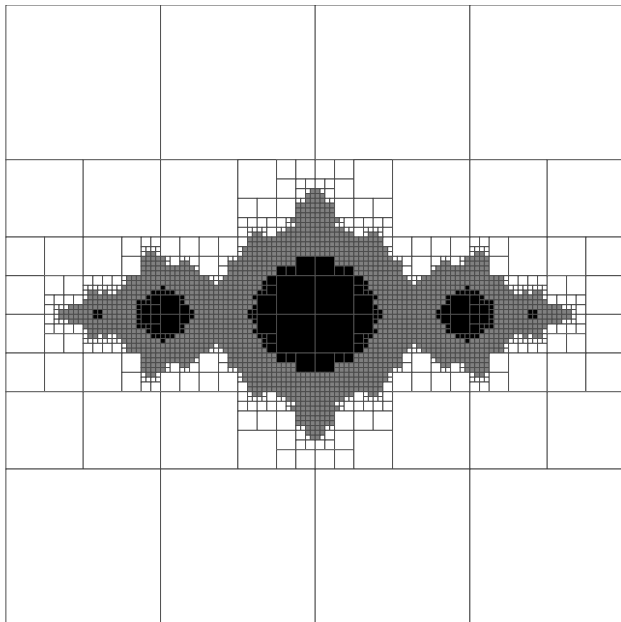
- ▶ refinement
- ▶ cell mapping
- ▶ color propagation



Our algorithm

quadtrees for
 $\Omega = [-R, R] \times [-R, R]$

- ▶ refinement
- ▶ cell mapping
- ▶ color propagation



Quadtree

$c = -1$

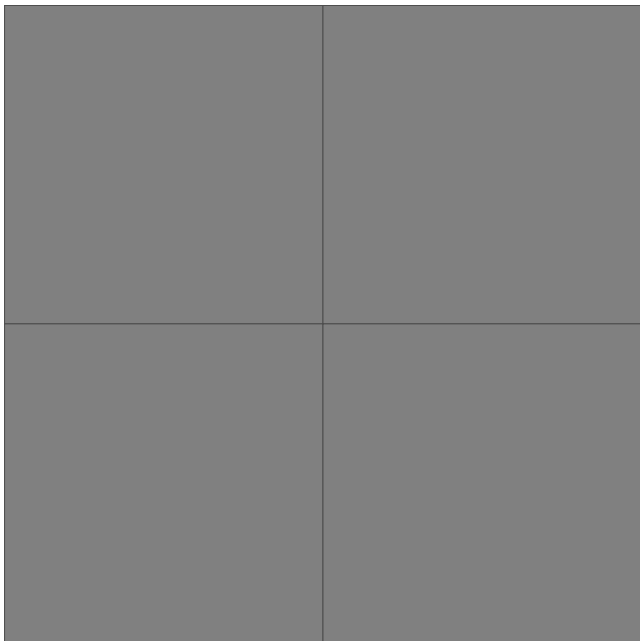
level 0



Quadtree

$c = -1$

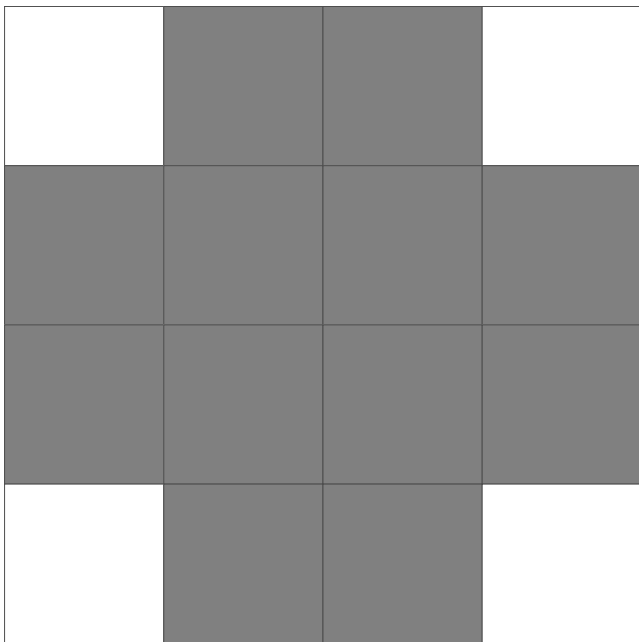
level 1



Quadtree

$c = -1$

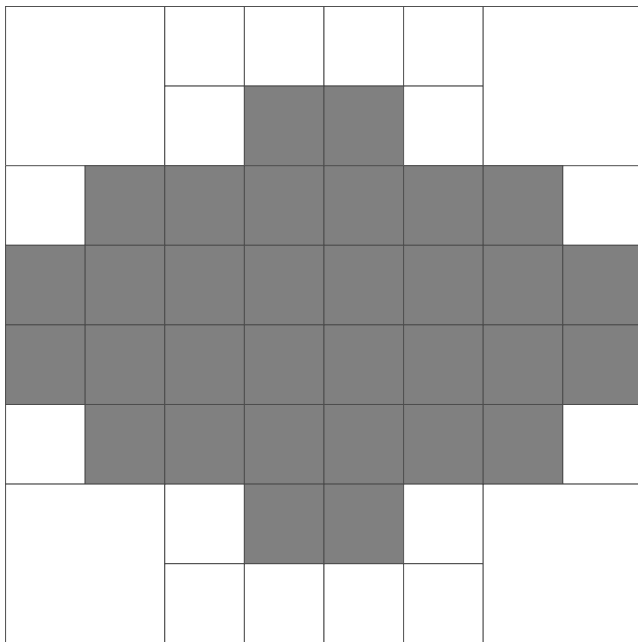
level 2



Quadtree

$c = -1$

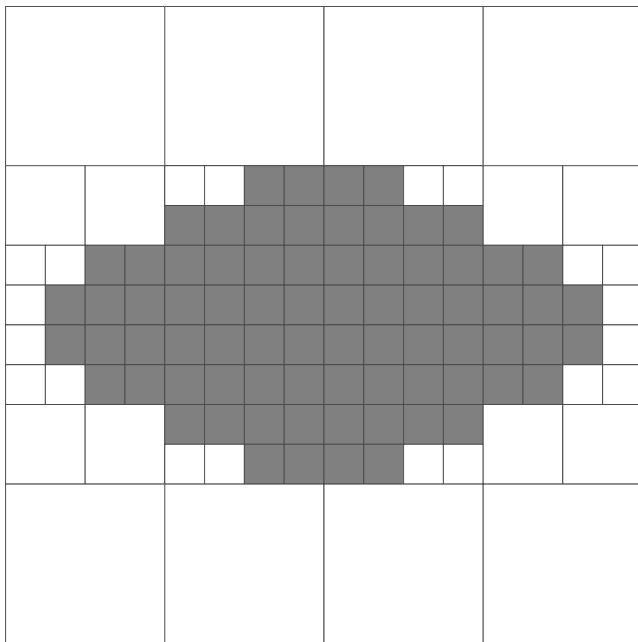
level 3



Quadtree

$c = -1$

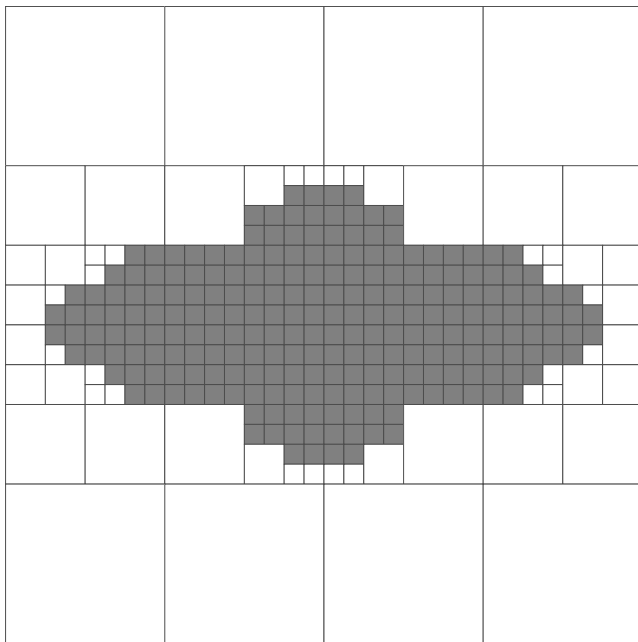
level 4



Quadtree

$c = -1$

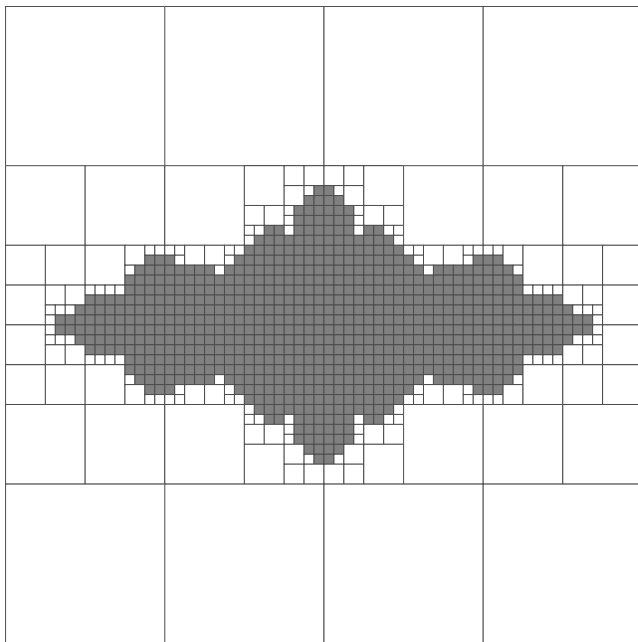
level 5



Quadtree

$c = -1$

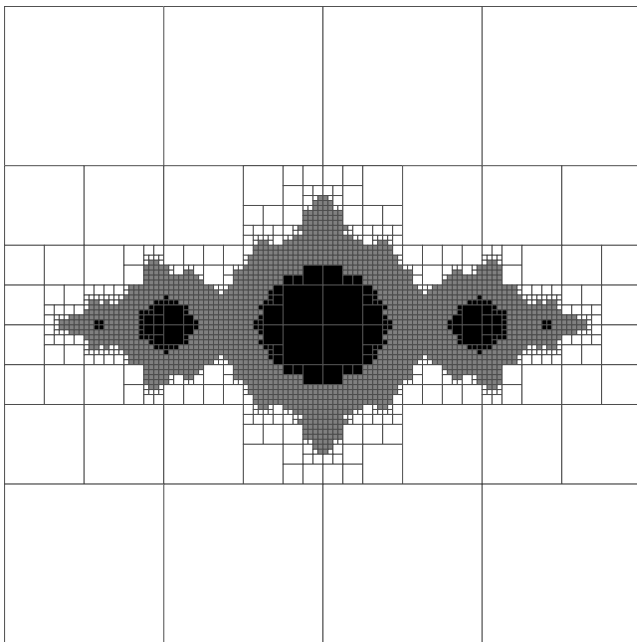
level 6



Quadtree

$c = -1$

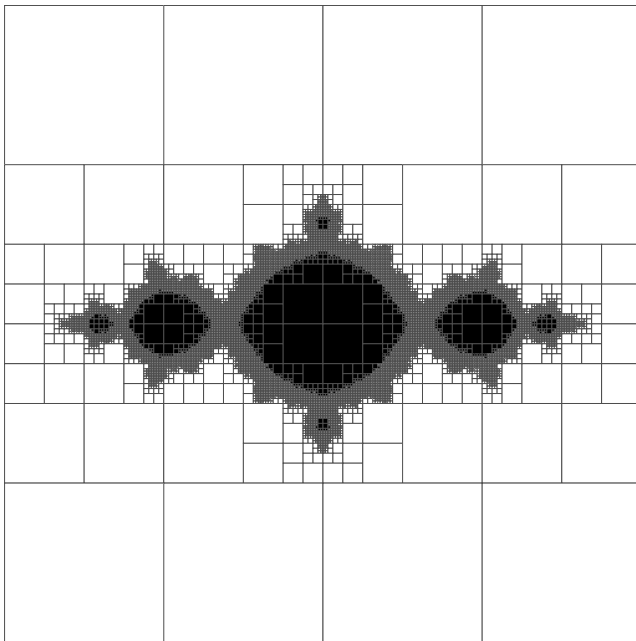
level 7



Quadtree

$c = -1$

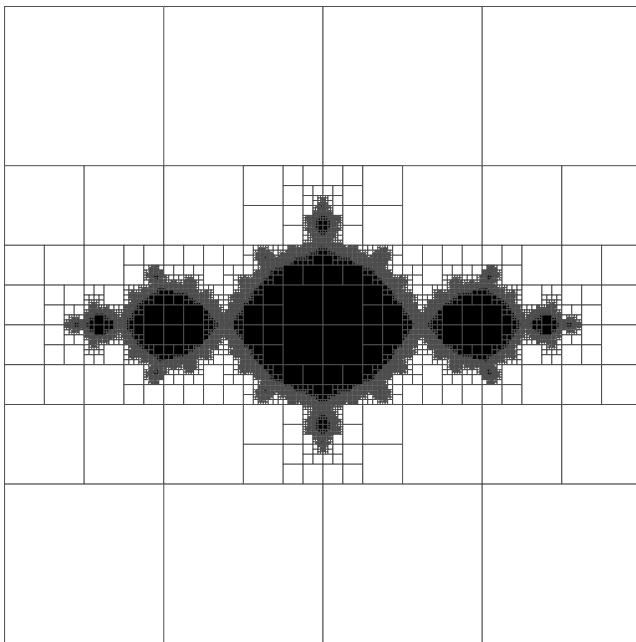
level 8



Quadtree

$c = -1$

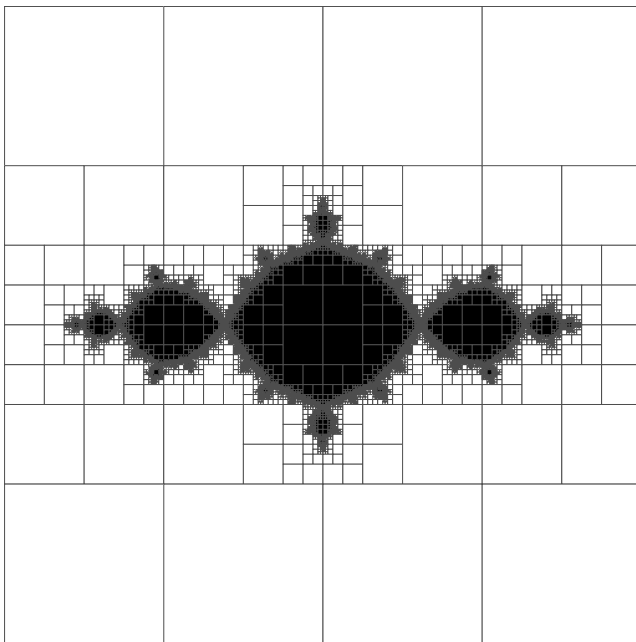
level 9



Quadtree

$c = -1$

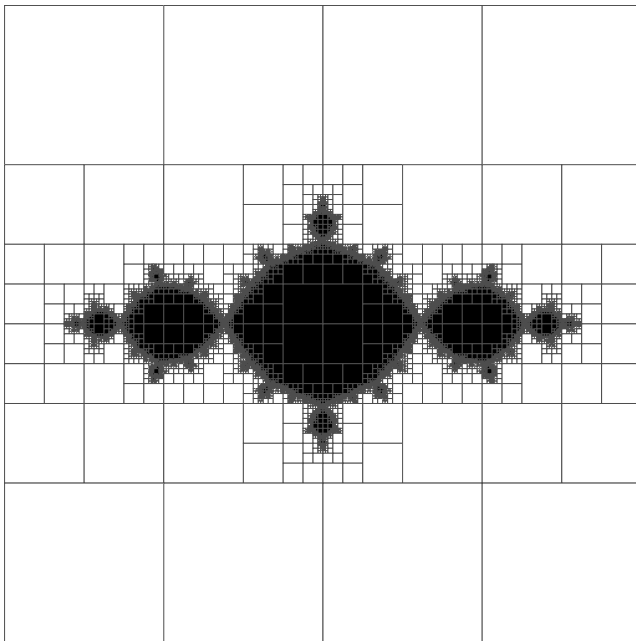
level 10



Quadtree

$c = -1$

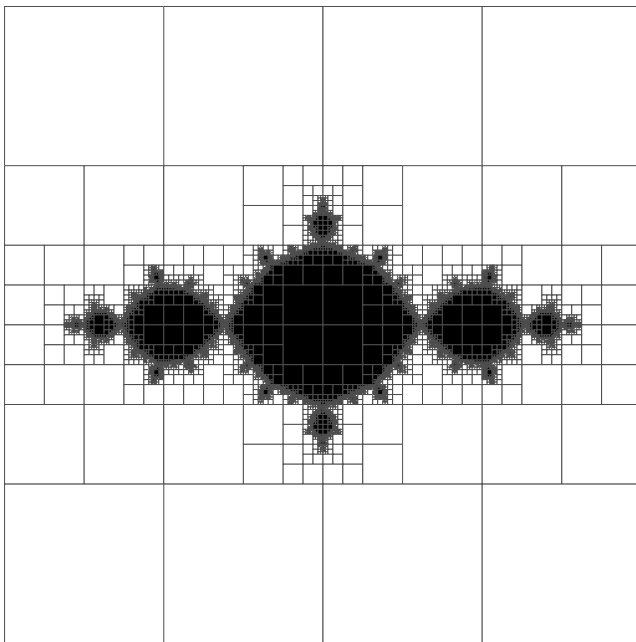
level 11



Quadtree

$c = -1$

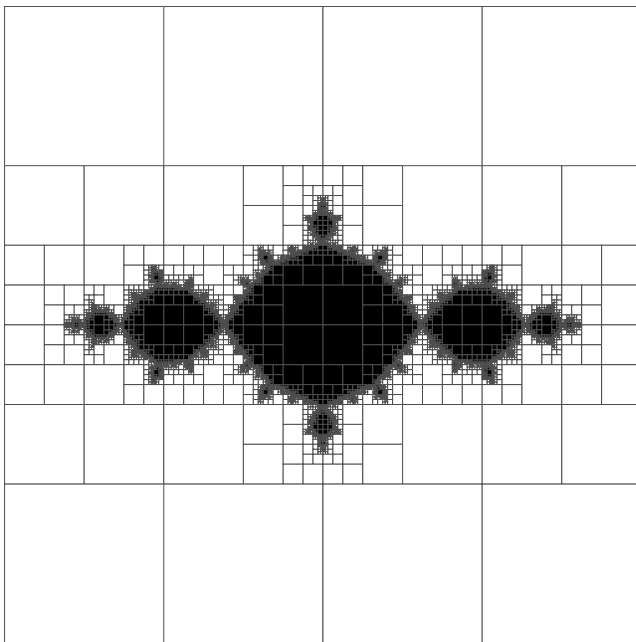
level 12



Quadtree

$c = -1$

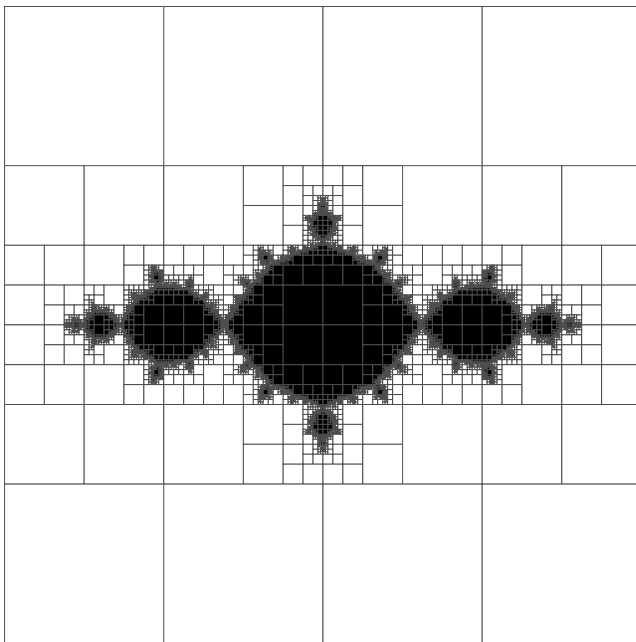
level 13



Quadtree

$c = -1$

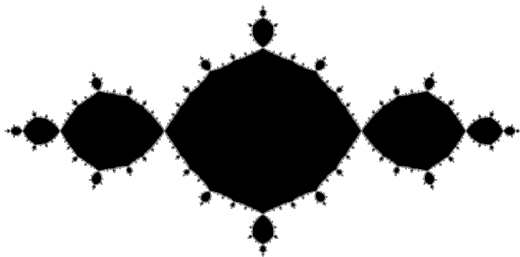
level 14



Adaptive approximation

$c = -1$

level 14



Adaptive approximation

$$c = -1$$

level 0



Adaptive approximation

$c = -1$

level 1



Adaptive approximation

$c = -1$

level 2



Adaptive approximation

$c = -1$

level 3



Adaptive approximation

$c = -1$

level 4



Adaptive approximation

$c = -1$

level 5



Adaptive approximation

$c = -1$

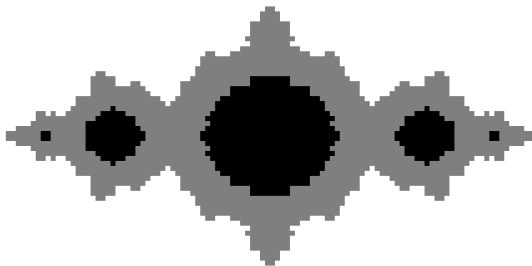
level 6



Adaptive approximation

$c = -1$

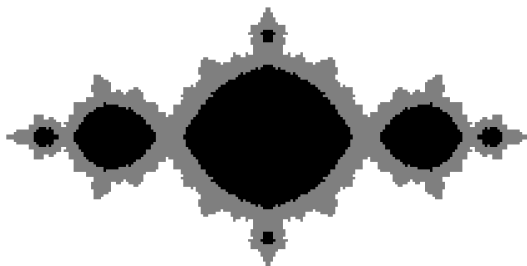
level 7



Adaptive approximation

$c = -1$

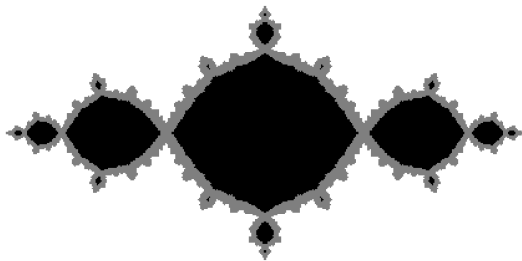
level 8



Adaptive approximation

$c = -1$

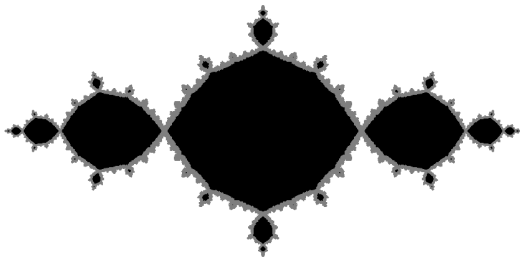
level 9



Adaptive approximation

$c = -1$

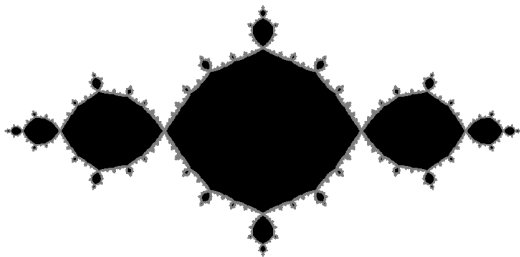
level 10



Adaptive approximation

$c = -1$

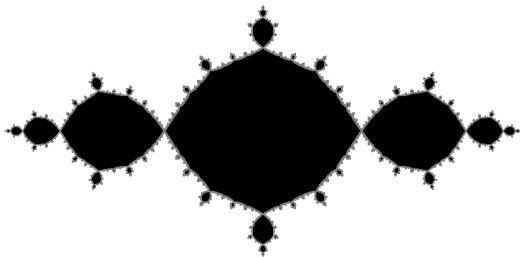
level 11



Adaptive approximation

$c = -1$

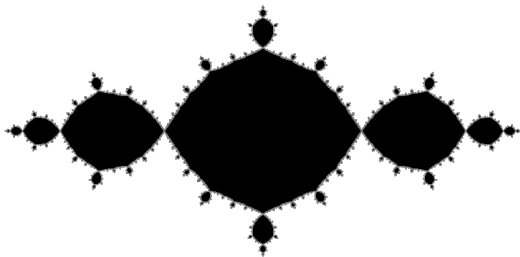
level 12



Adaptive approximation

$c = -1$

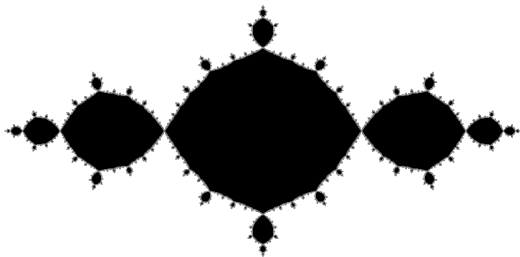
level 13



Adaptive approximation

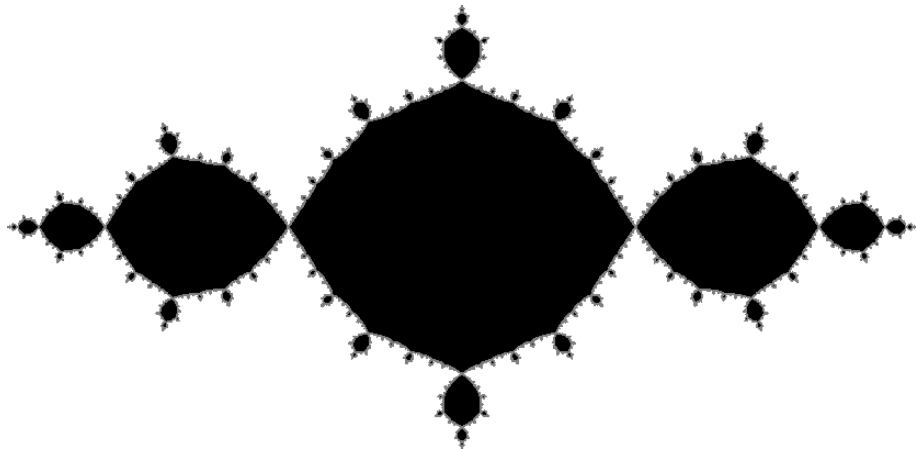
$c = -1$

level 14



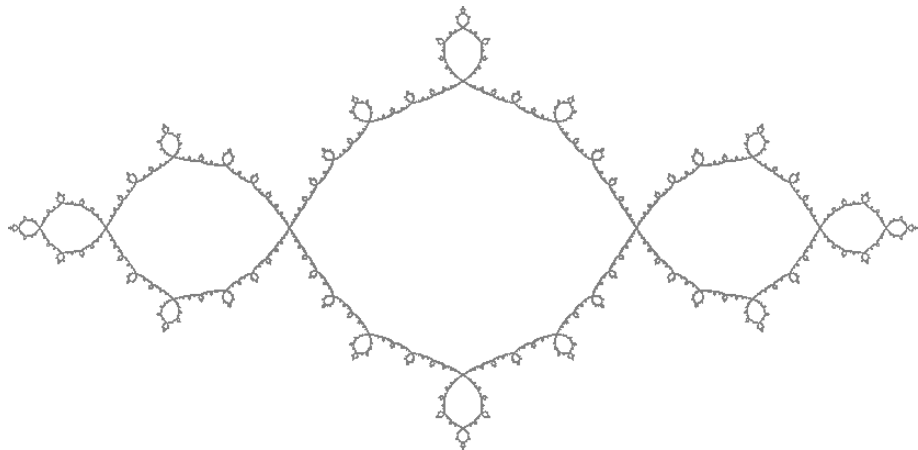
Adaptive approximation

$$c = -1$$



Adaptive approximation

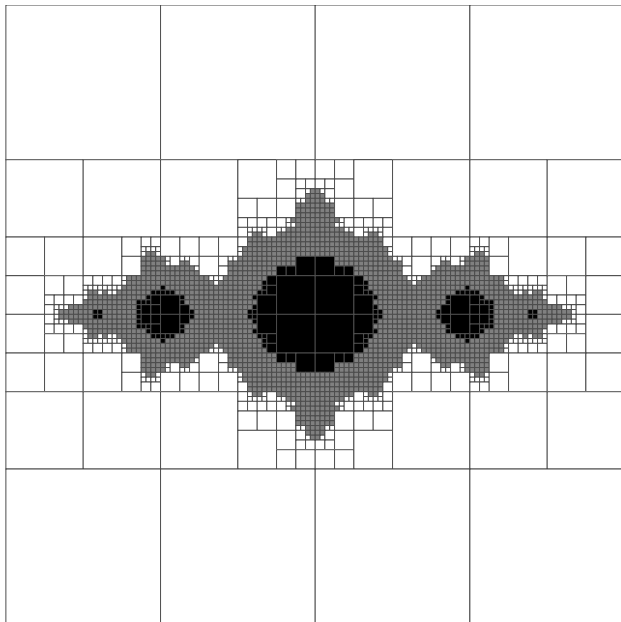
$$c = -1$$



Our algorithm

quadtree for
 $\Omega = [-R, R] \times [-R, R]$

- ▶ refinement
- ▶ cell mapping
- ▶ color propagation



Cell mapping

Directed graph on the leaves of the quadtree and exterior

- ▶ edges emanate from each leaf gray cell A
- ▶ add edge $A \rightarrow B$ for each leaf cell B that intersects $f(A)$

$$f(A) \subseteq \bigcup_{A \rightarrow B} B$$

Cell mapping

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- ▶ add edge $A \rightarrow B$ for each leaf cell B that intersects $f(A)$

$$f(A) \subseteq \bigcup_{A \rightarrow B} B$$

Conservative estimate of the dynamics

Avoid point sampling

Cell mapping

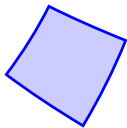
source cell

leaf gray cell



Cell mapping

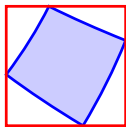
exact image under f

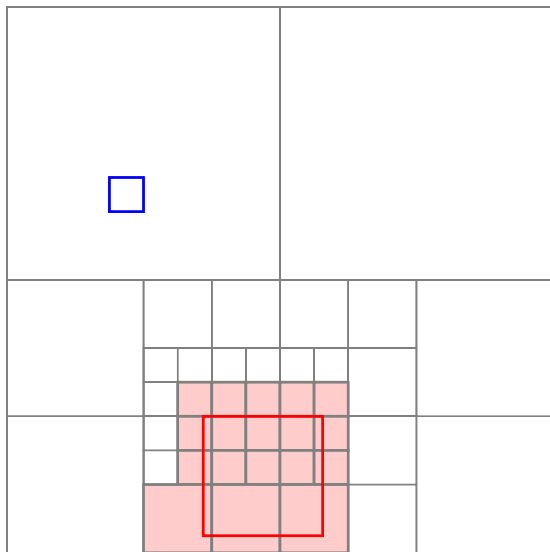


Cell mapping

bounding box

interval arithmetic

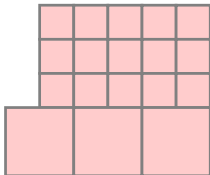


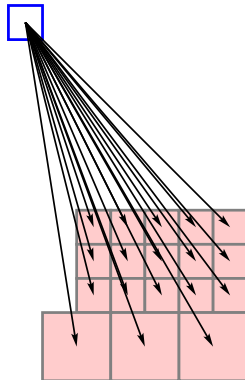


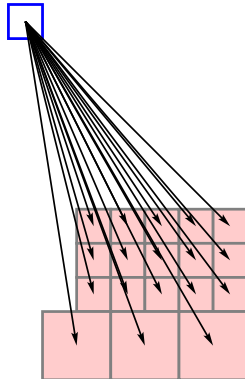
Cell mapping

target cells

contain exact image



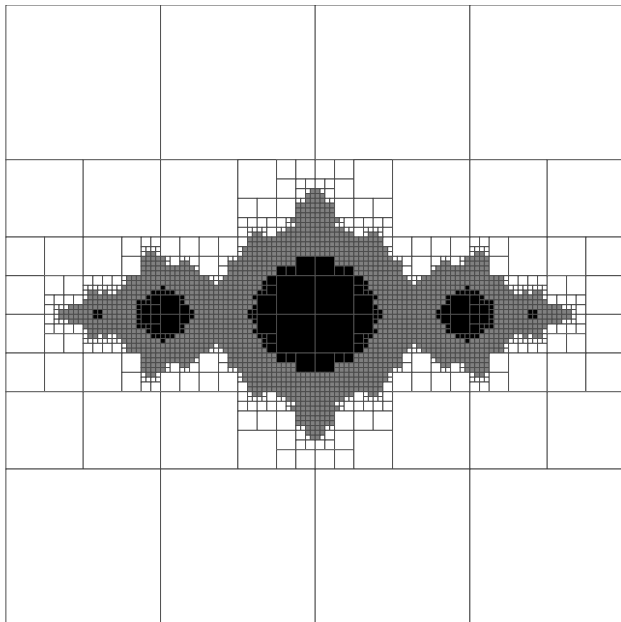




Our algorithm

quadtrees for
 $\Omega = [-R, R] \times [-R, R]$

- ▶ refinement
- ▶ cell mapping
- ▶ color propagation



Color propagation

Propagate white and black to gray cells

- ▶ new white cells
gray cells for which **all** paths end in white cells
- ▶ new black cells
gray cells for which **no** path ends in a white cell

Color propagation

Propagate white and black to gray cells

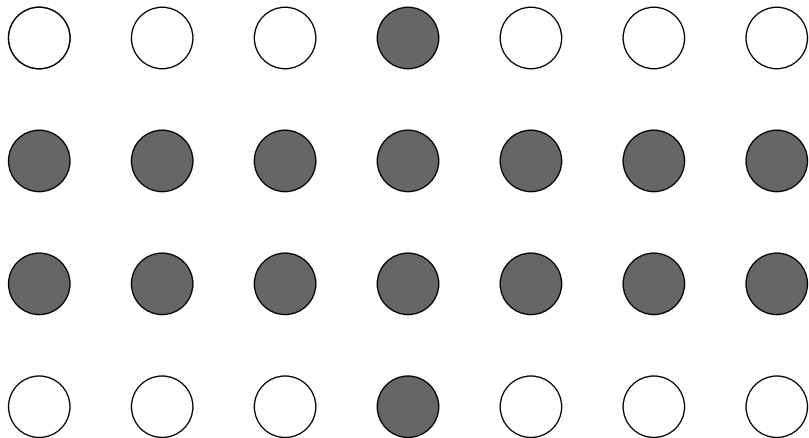
- ▶ new white cells
gray cells for which **all** paths end in white cells
- ▶ new black cells
gray cells for which **no** path ends in a white cell

Graph traversals replace function iteration

Avoid floating-point errors

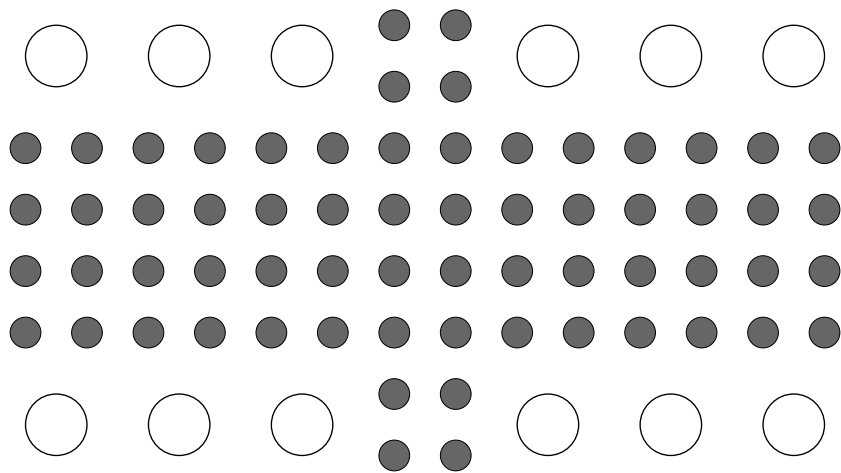
The algorithm

initial approximation



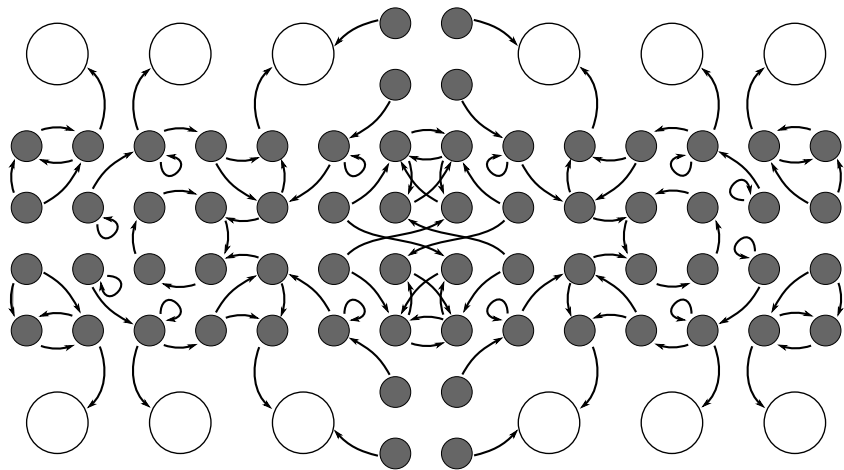
The algorithm

refinement



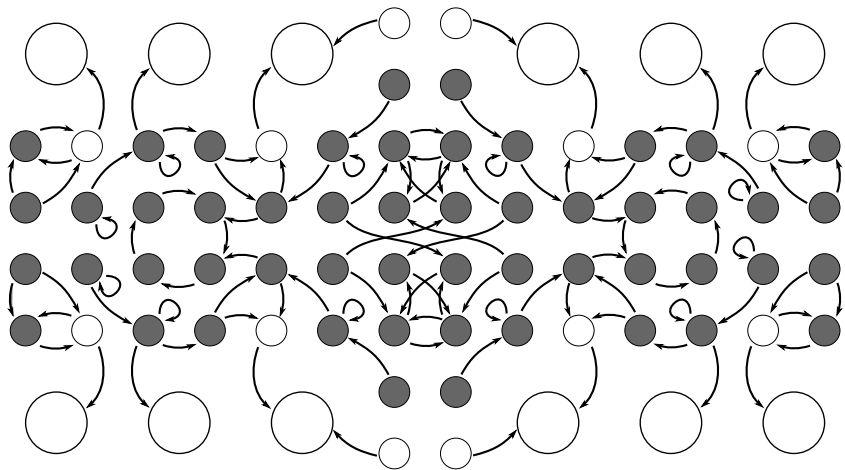
The algorithm

cell mapping



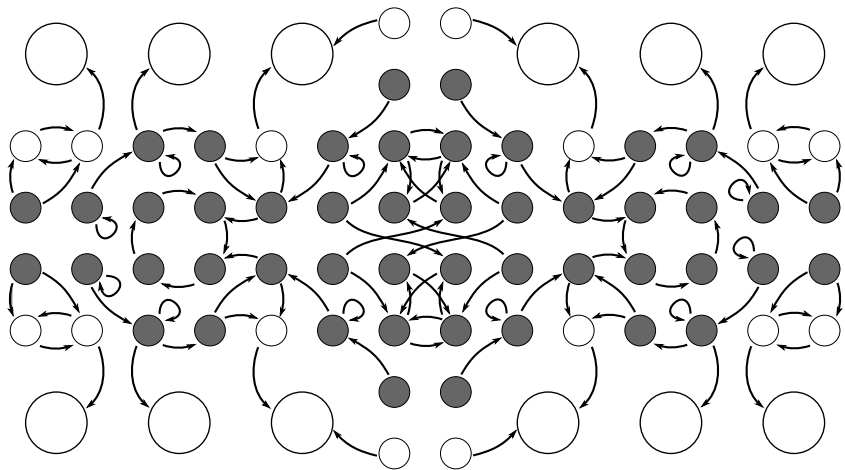
The algorithm

new white cells...



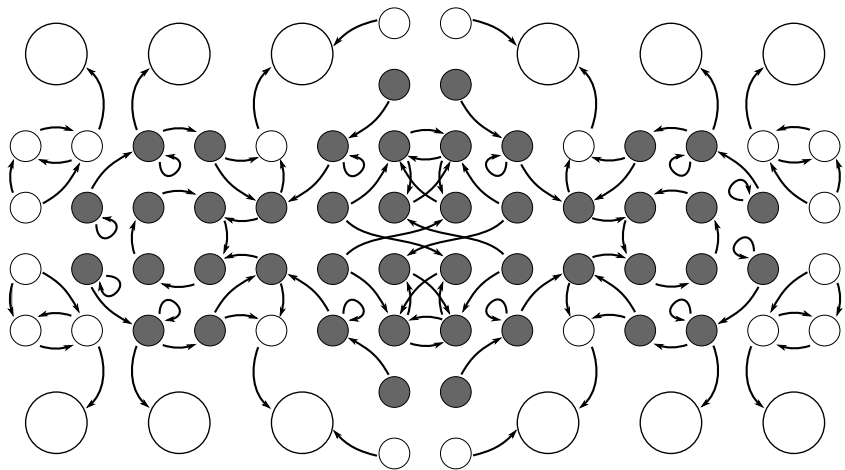
The algorithm

new white cells...



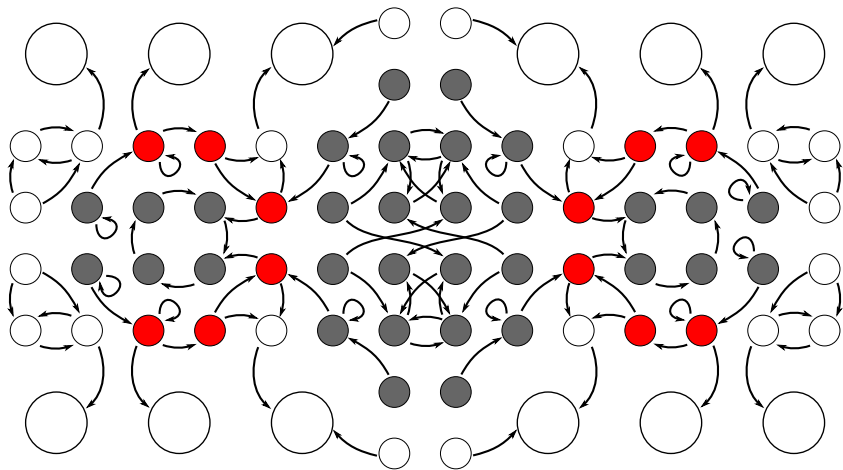
The algorithm

new white cells



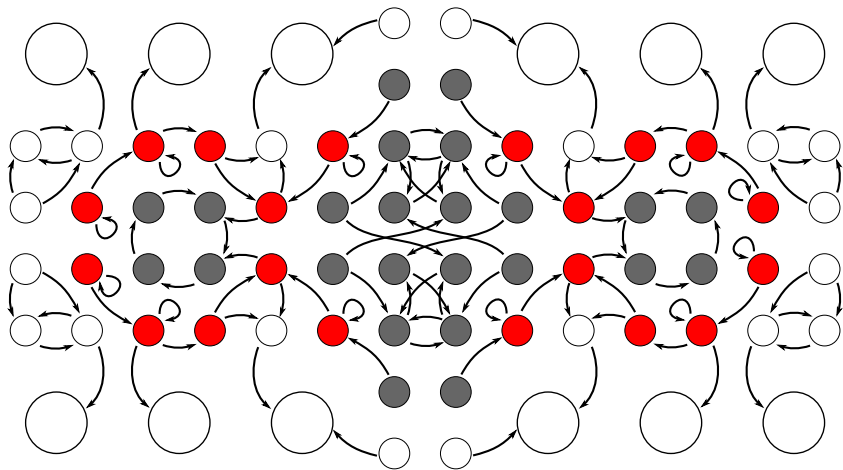
The algorithm

gray cells that reach white...



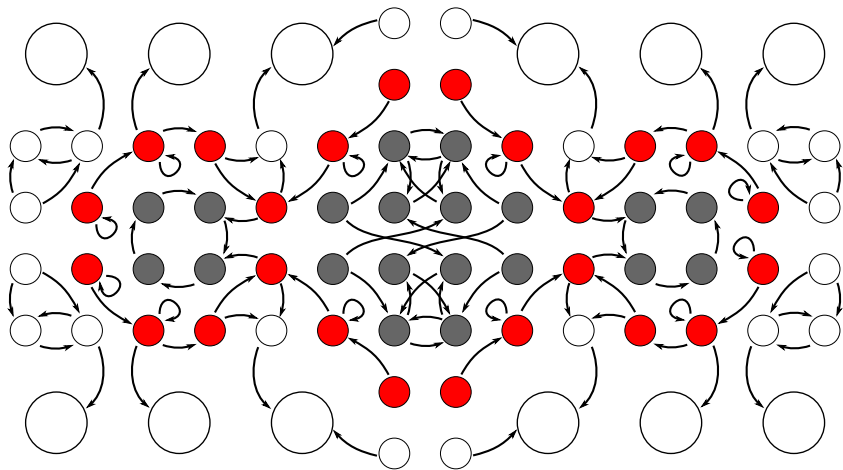
The algorithm

gray cells that reach white...



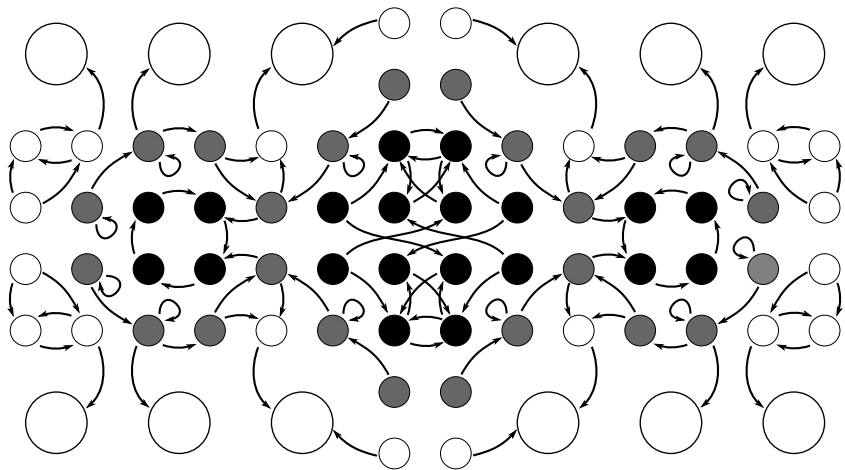
The algorithm

gray cells that reach white



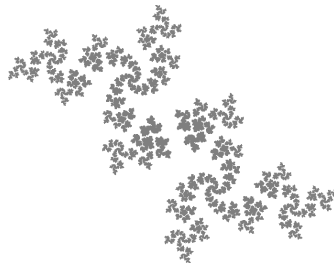
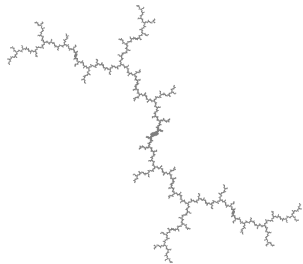
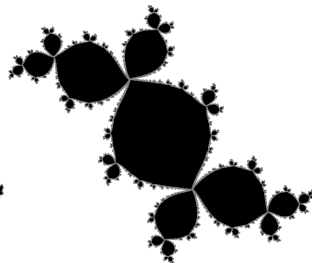
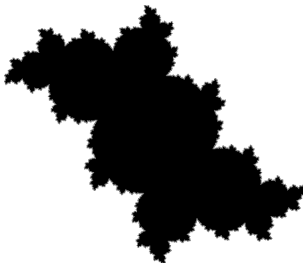
The algorithm

new black cells



Adaptive approximation

examples



Adaptive approximation

$$c = 0.12 + 0.30 i \quad \text{level 0}$$



Adaptive approximation

$$c = 0.12 + 0.30 i \quad \text{level 1}$$



Adaptive approximation

$$c = 0.12 + 0.30 i \quad \text{level 2}$$



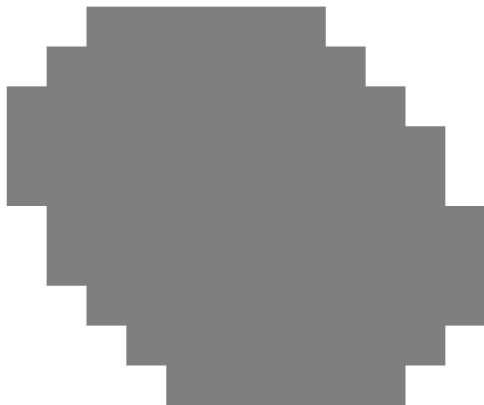
Adaptive approximation

$c = 0.12 + 0.30 i$ level 3



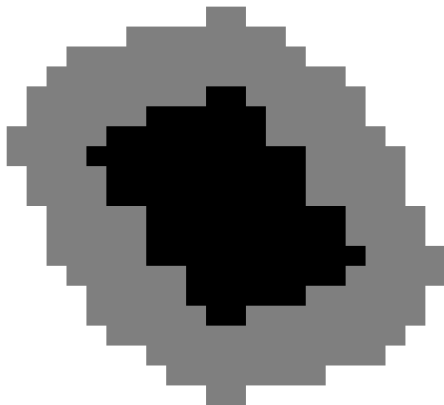
Adaptive approximation

$c = 0.12 + 0.30 i$ level 4



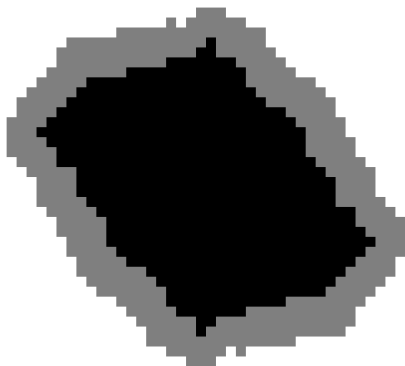
Adaptive approximation

$c = 0.12 + 0.30 i$ level 5



Adaptive approximation

$c = 0.12 + 0.30 i$ level 6



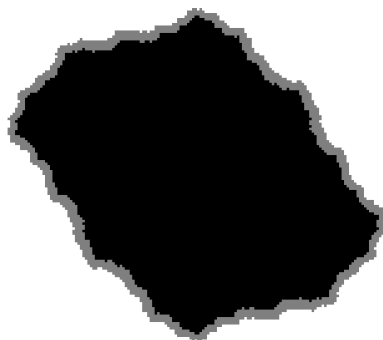
Adaptive approximation

$c = 0.12 + 0.30 i$ level 7



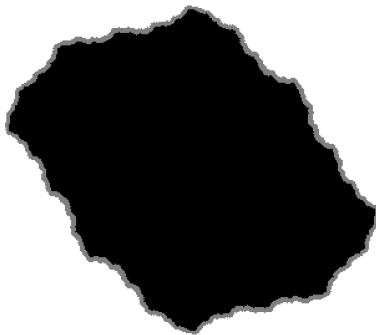
Adaptive approximation

$c = 0.12 + 0.30 i$ level 8



Adaptive approximation

$c = 0.12 + 0.30 i$ level 9



Adaptive approximation

$c = 0.12 + 0.30 i$ level 10



Adaptive approximation

$c = 0.12 + 0.30 i$ level 11



Adaptive approximation

$c = 0.12 + 0.30 i$ level 12



Adaptive approximation

$c = 0.12 + 0.30 i$ level 13



Adaptive approximation

$c = 0.12 + 0.30 i$ level 14



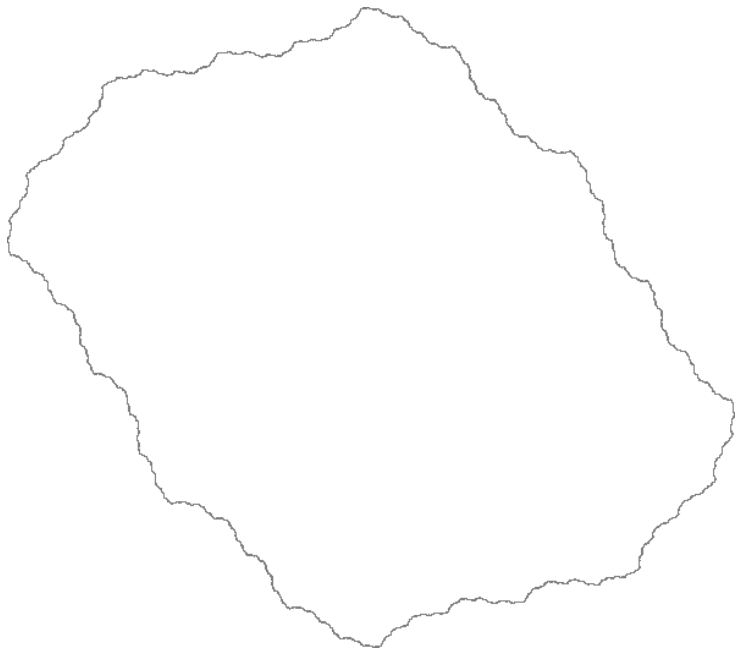
Adaptive approximation

$$c = 0.12 + 0.30 i$$



Adaptive approximation

$$c = 0.12 + 0.30 i$$



Adaptive approximation

$$c = -0.12 + 0.60i \quad \text{level 0}$$



Adaptive approximation

$$c = -0.12 + 0.60i \quad \text{level 1}$$



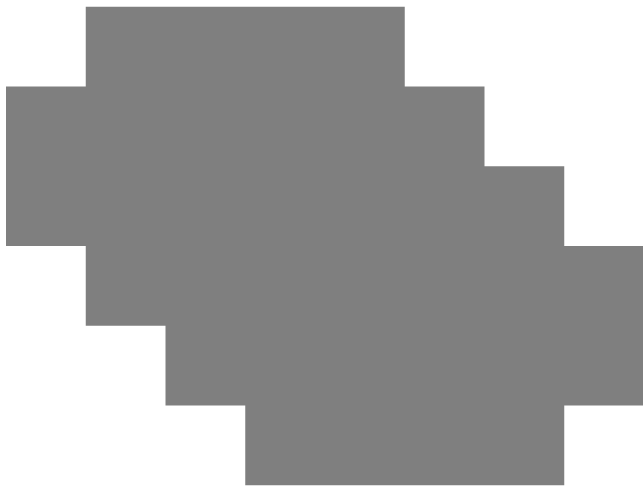
Adaptive approximation

$c = -0.12 + 0.60i$ level 2



Adaptive approximation

$c = -0.12 + 0.60i$ level 3



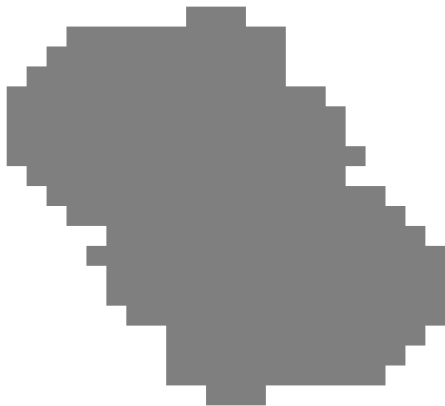
Adaptive approximation

$c = -0.12 + 0.60i$ level 4



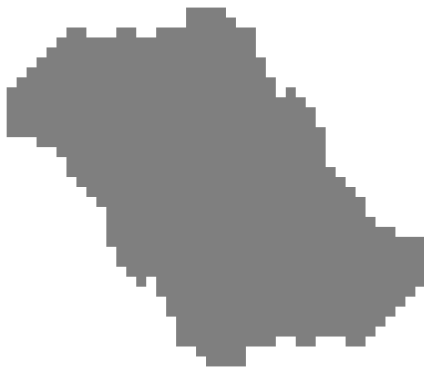
Adaptive approximation

$c = -0.12 + 0.60i$ level 5



Adaptive approximation

$c = -0.12 + 0.60i$ level 6



Adaptive approximation

$c = -0.12 + 0.60i$ level 7



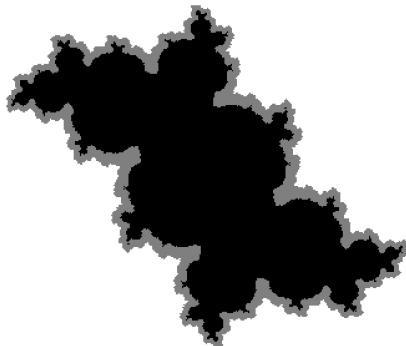
Adaptive approximation

$c = -0.12 + 0.60i$ level 8



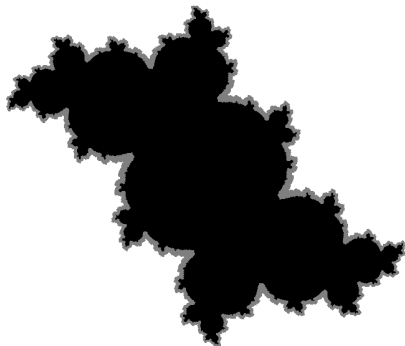
Adaptive approximation

$c = -0.12 + 0.60i$ level 9



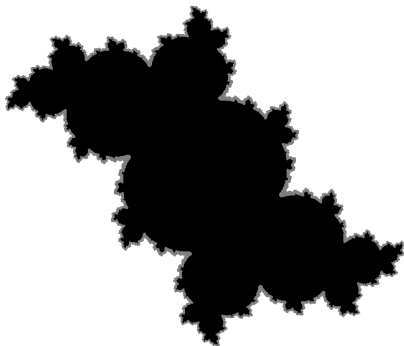
Adaptive approximation

$c = -0.12 + 0.60i$ level 10



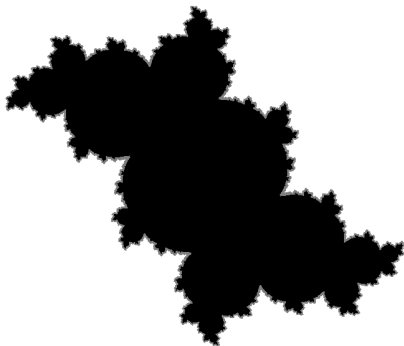
Adaptive approximation

$c = -0.12 + 0.60i$ level 11



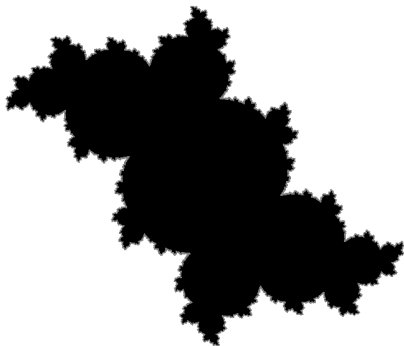
Adaptive approximation

$c = -0.12 + 0.60i$ level 12



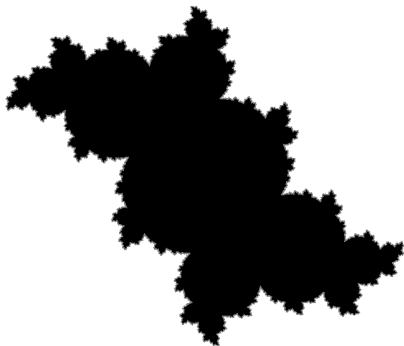
Adaptive approximation

$c = -0.12 + 0.60i$ level 13



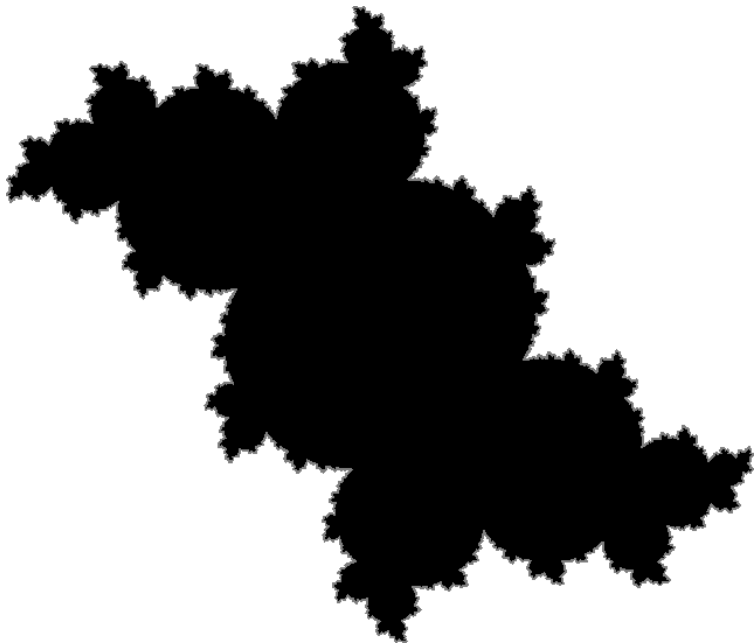
Adaptive approximation

$c = -0.12 + 0.60i$ level 14



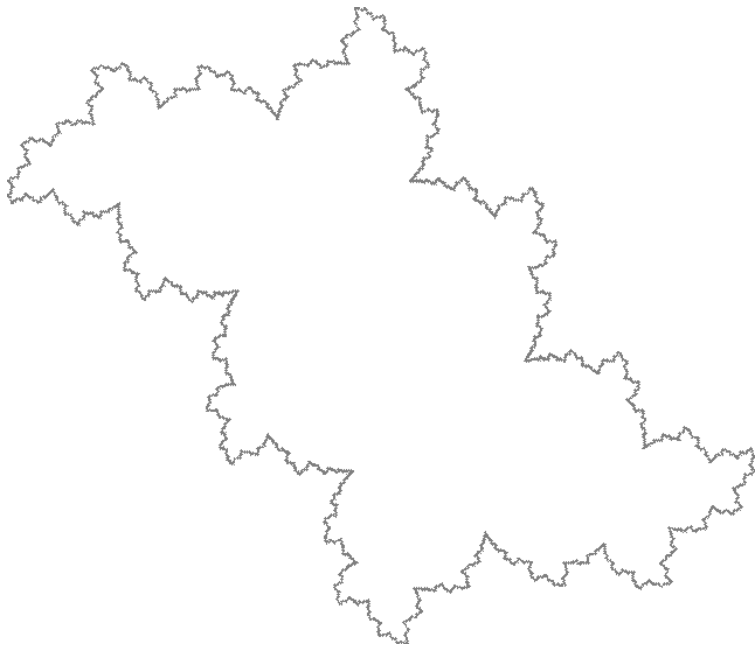
Adaptive approximation

$$c = -0.12 + 0.60i$$



Adaptive approximation

$$c = -0.12 + 0.60i$$



Adaptive approximation

$$c = -0.12 + 0.74i \quad \text{level 0}$$



Adaptive approximation

$$c = -0.12 + 0.74i \quad \text{level 1}$$



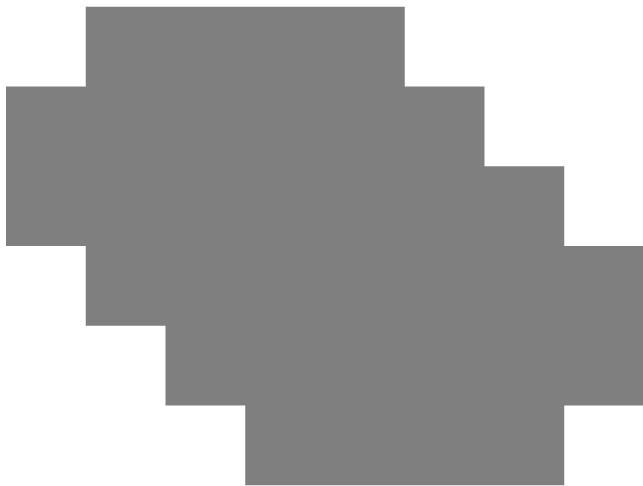
Adaptive approximation

$c = -0.12 + 0.74 i$ level 2



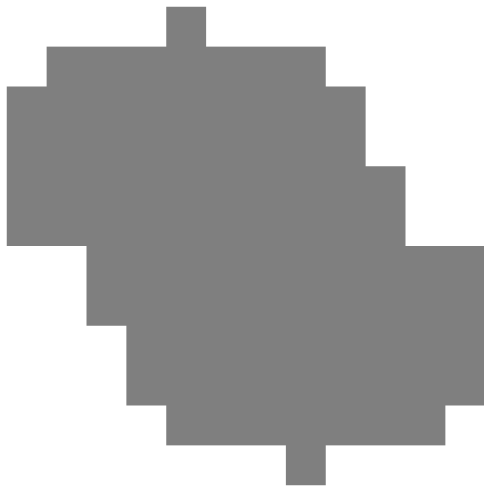
Adaptive approximation

$c = -0.12 + 0.74 i$ level 3



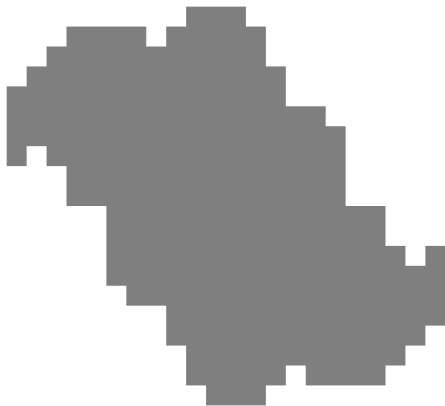
Adaptive approximation

$c = -0.12 + 0.74 i$ level 4



Adaptive approximation

$c = -0.12 + 0.74 i$ level 5



Adaptive approximation

$c = -0.12 + 0.74 i$ level 6



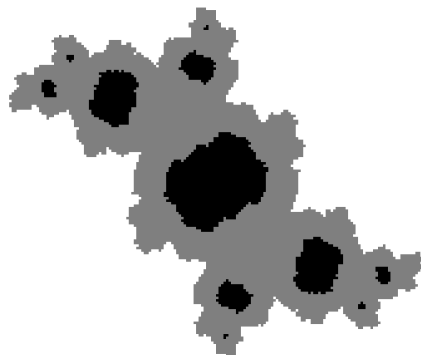
Adaptive approximation

$c = -0.12 + 0.74i$ level 7



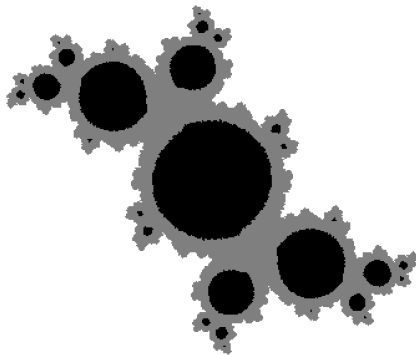
Adaptive approximation

$c = -0.12 + 0.74i$ level 8



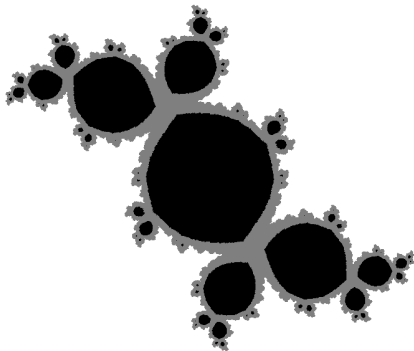
Adaptive approximation

$c = -0.12 + 0.74 i$ level 9



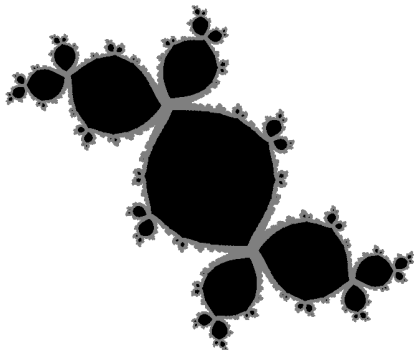
Adaptive approximation

$c = -0.12 + 0.74 i$ level 10



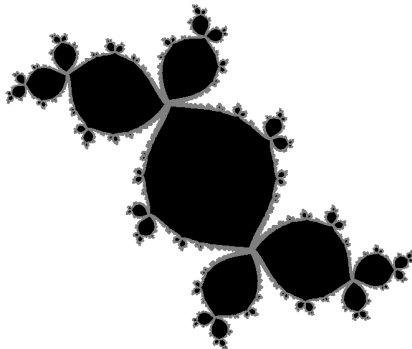
Adaptive approximation

$c = -0.12 + 0.74 i$ level 11



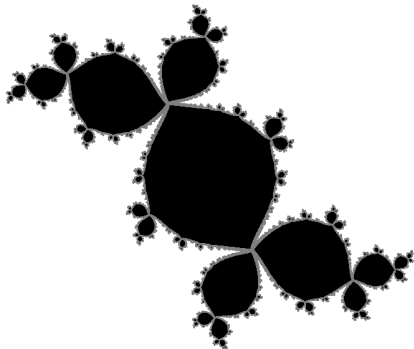
Adaptive approximation

$c = -0.12 + 0.74 i$ level 12



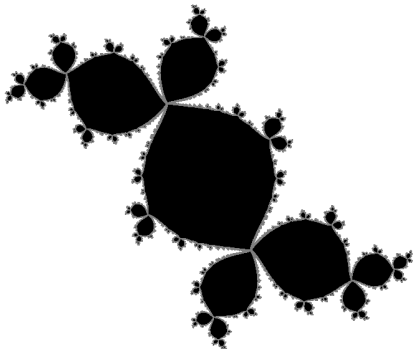
Adaptive approximation

$c = -0.12 + 0.74 i$ level 13



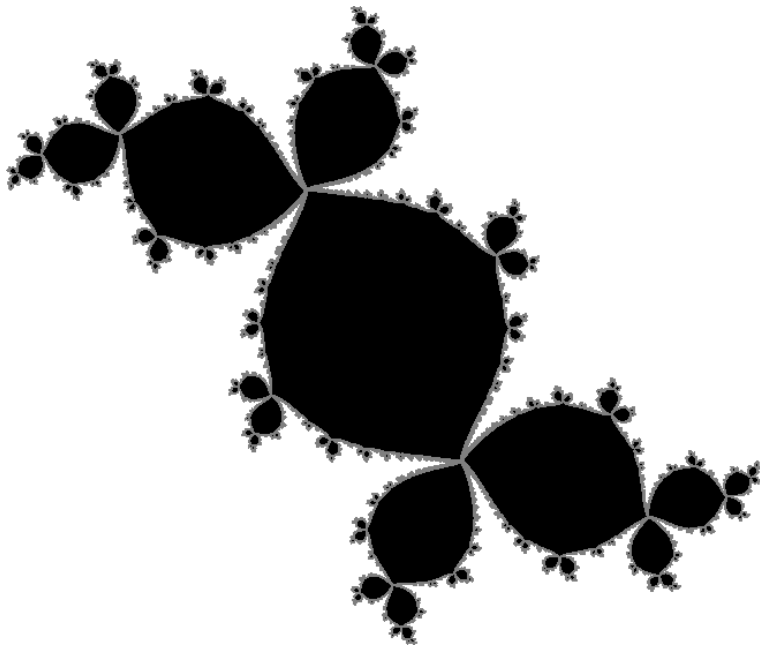
Adaptive approximation

$c = -0.12 + 0.74 i$ level 14



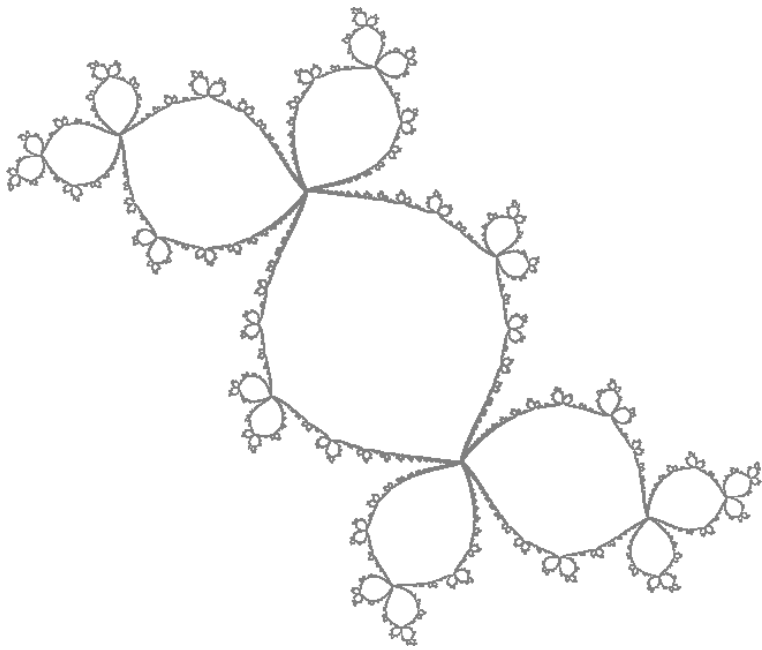
Adaptive approximation

$$c = -0.12 + 0.74 i$$



Adaptive approximation

$$c = -0.12 + 0.74 i$$



Adaptive approximation

$c = i$ level 0



Adaptive approximation

$c = i$ level 1



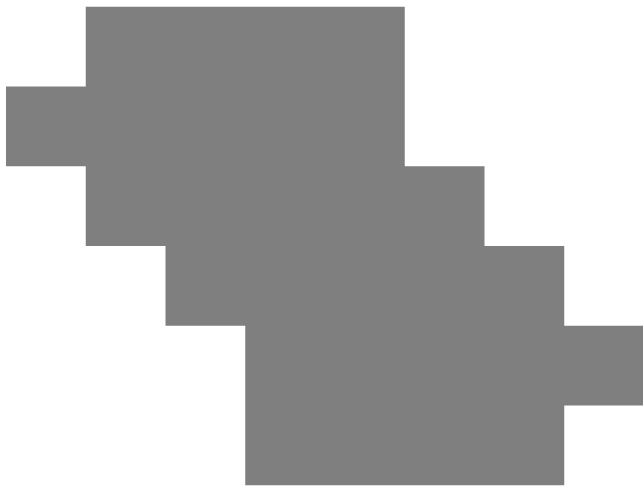
Adaptive approximation

$c = i$ level 2



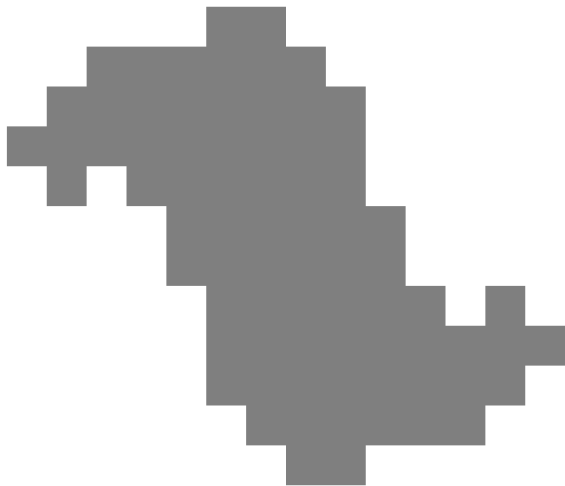
Adaptive approximation

$c = i$ level 3



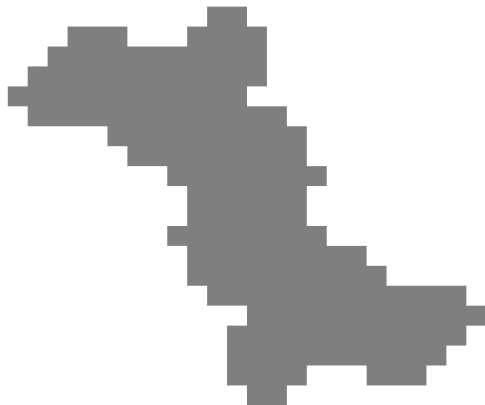
Adaptive approximation

$c = i$ level 4



Adaptive approximation

$c = i$ level 5



Adaptive approximation

$c = i$ level 6



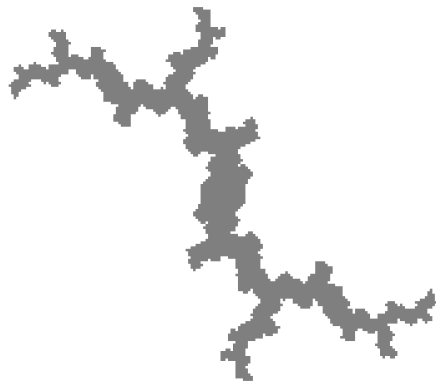
Adaptive approximation

$c = i$ level 7



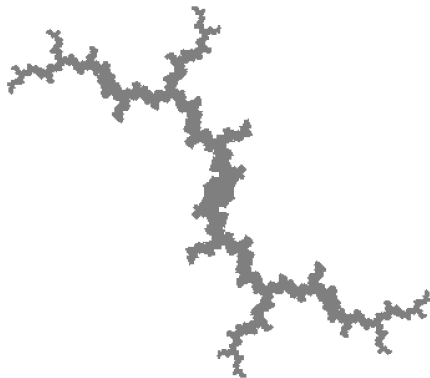
Adaptive approximation

$c = i$ level 8



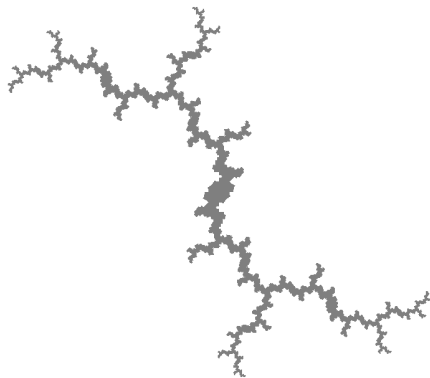
Adaptive approximation

$c = i$ level 9



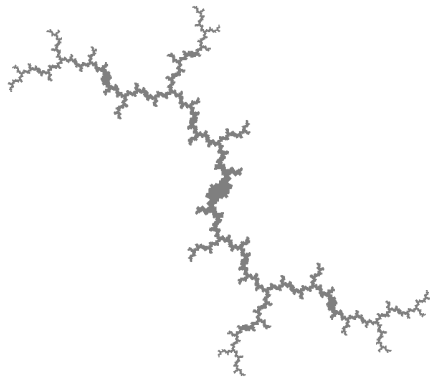
Adaptive approximation

$c = i$ level 10



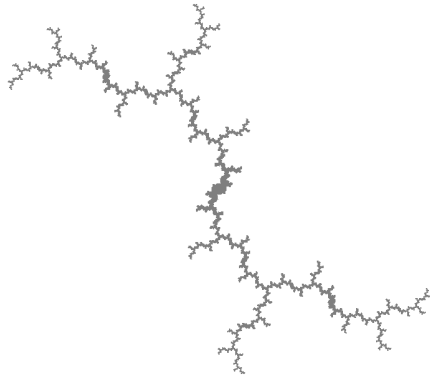
Adaptive approximation

$c = i$ level 11



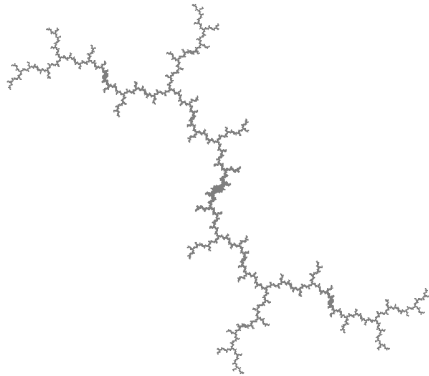
Adaptive approximation

$c = i$ level 12



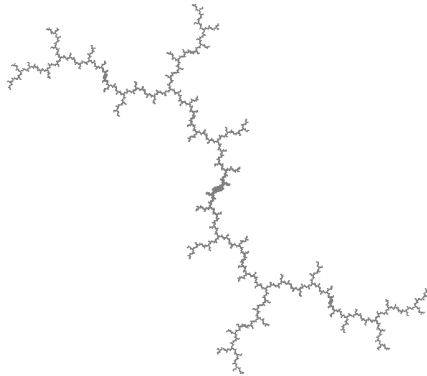
Adaptive approximation

$c = i$ level 13



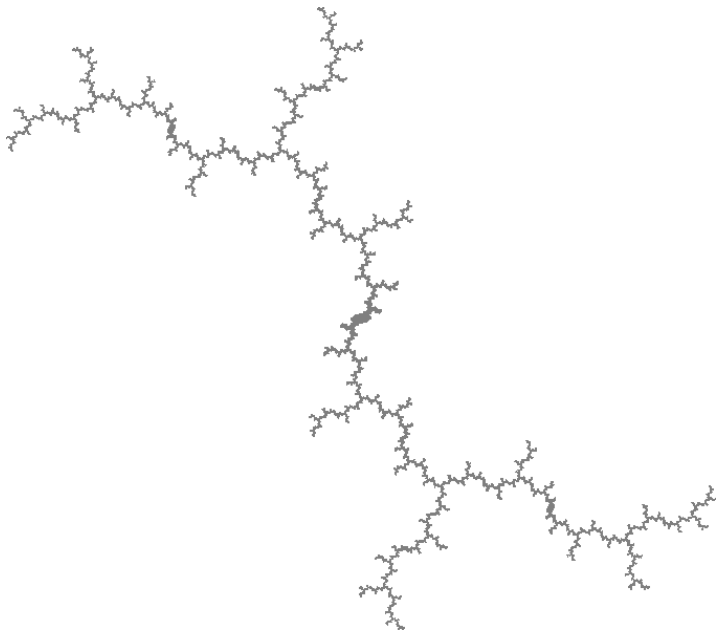
Adaptive approximation

$c = i$ level 14



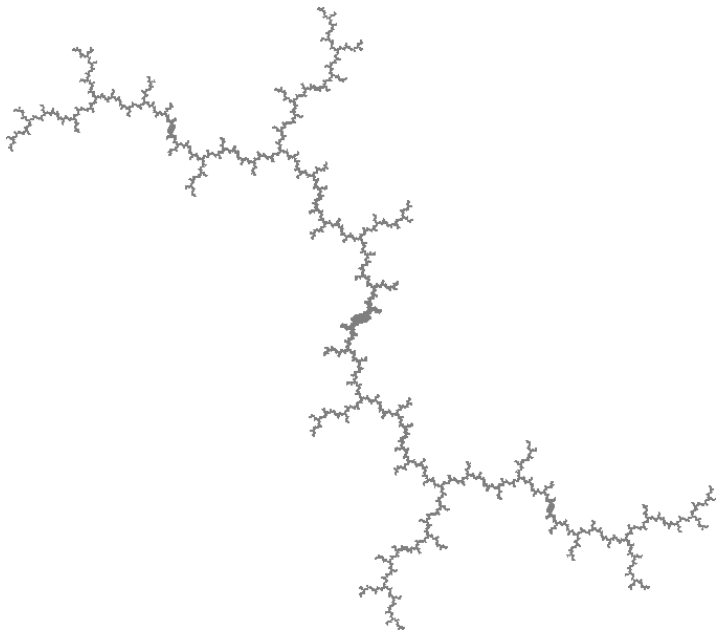
Adaptive approximation

$$c = i$$



Adaptive approximation

$$c = i$$



Adaptive approximation

$$c = -0.25 + 0.74i \quad \text{level 0}$$



Adaptive approximation

$c = -0.25 + 0.74 i$ level 1



Adaptive approximation

$c = -0.25 + 0.74 i$ level 2



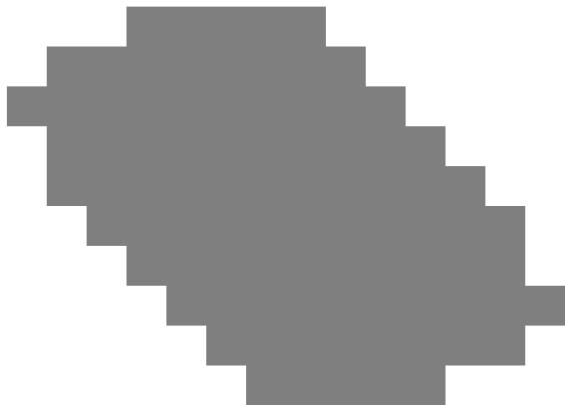
Adaptive approximation

$c = -0.25 + 0.74 i$ level 3



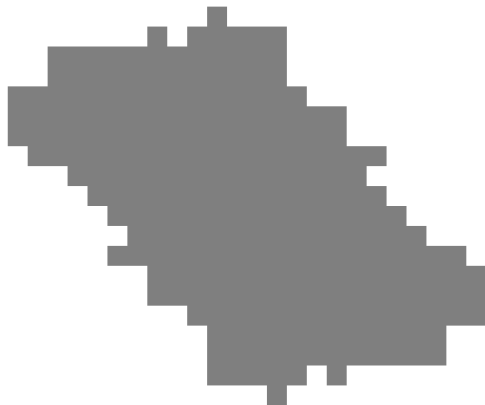
Adaptive approximation

$c = -0.25 + 0.74 i$ level 4



Adaptive approximation

$c = -0.25 + 0.74 i$ level 5



Adaptive approximation

$c = -0.25 + 0.74 i$ level 6



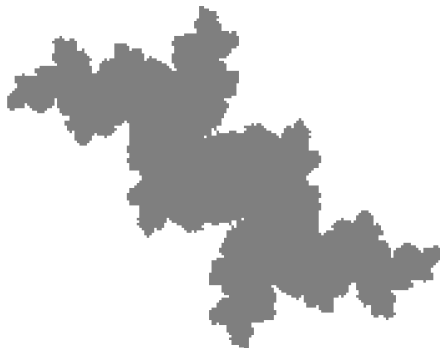
Adaptive approximation

$c = -0.25 + 0.74i$ level 7



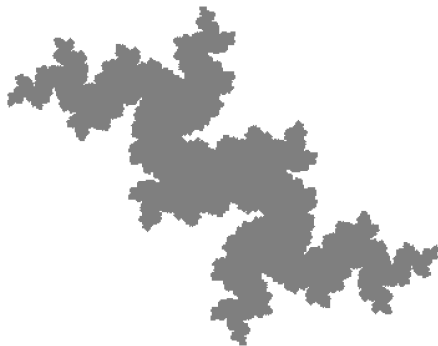
Adaptive approximation

$c = -0.25 + 0.74i$ level 8



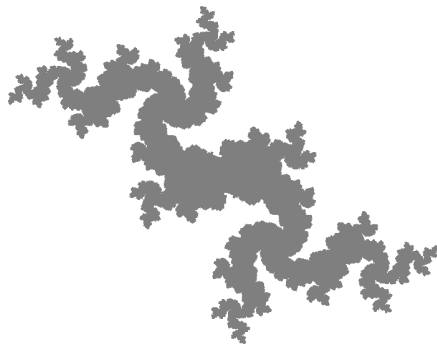
Adaptive approximation

$c = -0.25 + 0.74 i$ level 9



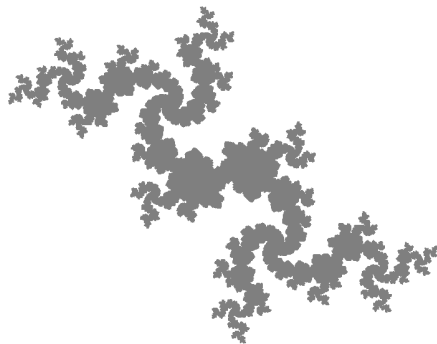
Adaptive approximation

$c = -0.25 + 0.74 i$ level 10



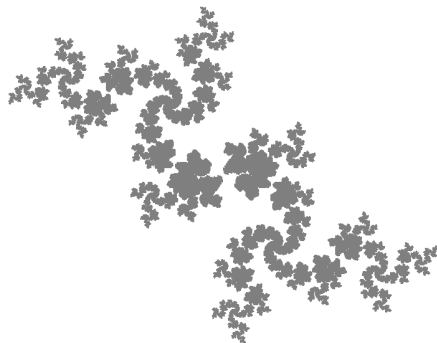
Adaptive approximation

$c = -0.25 + 0.74 i$ level 11



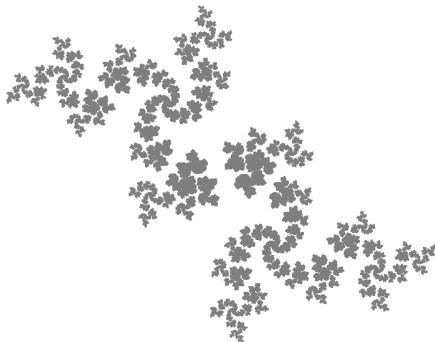
Adaptive approximation

$c = -0.25 + 0.74 i$ level 12



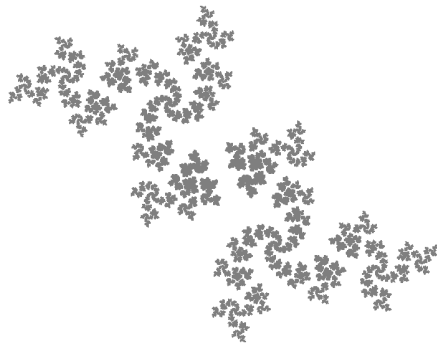
Adaptive approximation

$c = -0.25 + 0.74 i$ level 13



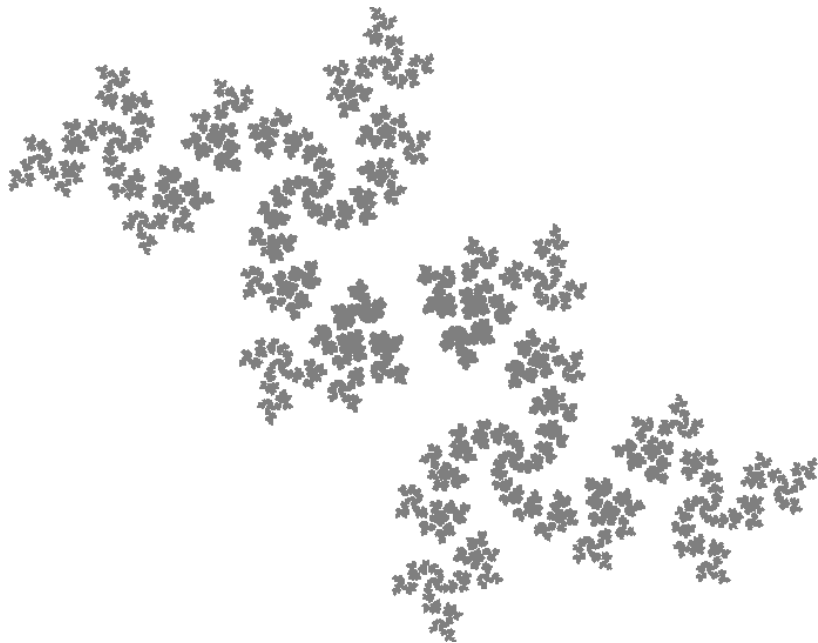
Adaptive approximation

$c = -0.25 + 0.74 i$ level 14



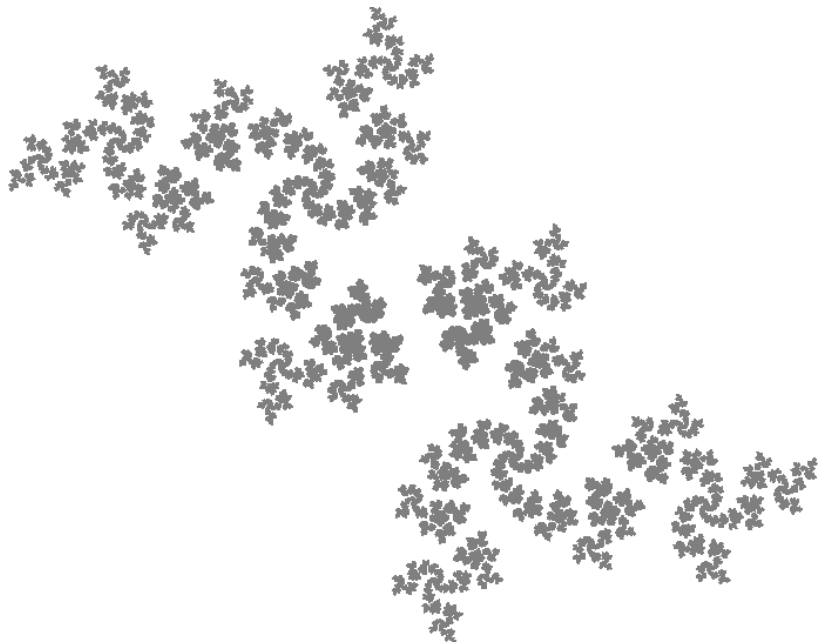
Adaptive approximation

$$c = -0.25 + 0.74 i$$



Adaptive approximation

$$c = -0.25 + 0.74 i$$



Applications

- ▶ Image generation
- ▶ Point and box classification
- ▶ Fractal dimension of Julia set
- ▶ Area of filled Julia set
- ▶ Diameter of Julia set

- ▶ Image generation

- large images

- smaller images with anti-aliasing

- ▶ Point and box classification

- quadtrees traversal + one function evaluation if gray

- ▶ Fractal dimension of Julia set

- upper bound

$$\dim_H = 1 + \frac{|c|^2}{4 \log 2} + \dots \quad (\text{Ruelle})$$

- ▶ Area of filled Julia set

- lower and upper bounds

$$\pi(1 - |p_1(c)|^2 - 3|p_2(c)|^2 - 5|p_3(c)|^2 - \dots) \quad (\text{Milnor})$$

- ▶ Diameter of Julia set

- lower and upper bounds

Area of filled Julia sets after Milnor

Inverse Böttcher map $\psi: \mathbb{C} \setminus \mathbb{D} \rightarrow \mathbb{C} \setminus K$

$$\psi(w^2) = \psi(w)^2 + c$$

Laurent series near ∞

$$\psi(w) = w \left(1 + \frac{a_2}{w^2} + \frac{a_4}{w^4} + \frac{a_6}{w^6} + \dots \right)$$

$$a_2 = -\frac{c}{2} \quad a_{2n} = \frac{1}{2}(a_n - a_n^2) - \sum_{\substack{2 \leq j < n \\ j \text{ even}}} a_j a_{2n-j} \quad a_{2n+1} = 0$$

Gronwall's area theorem

$$\text{area}(K) = \pi(1 - |a_2|^2 - 3|a_4|^2 - 5|a_6|^2 - \dots)$$

Truncating series gives upper bounds

series converges slowly

Quadtree gives both lower and upper bounds

Area of filled Julia sets after Milnor

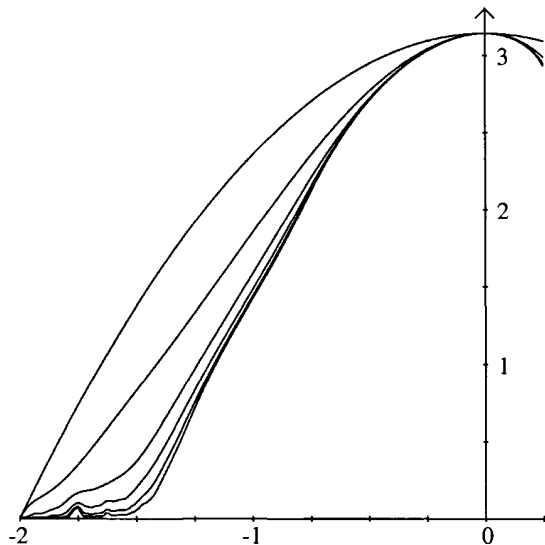
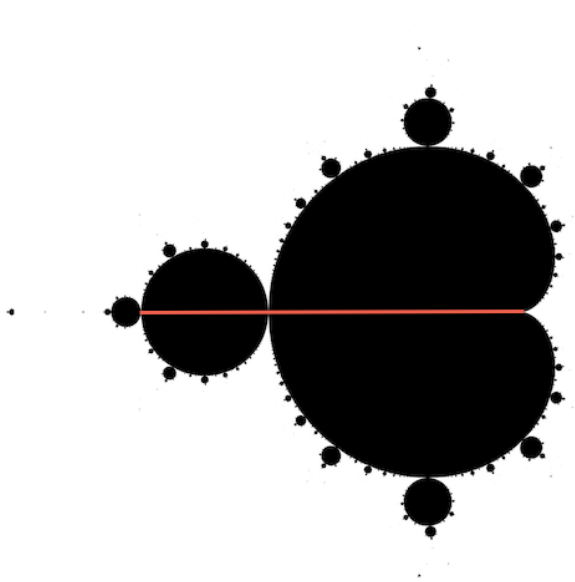


Figure 45. Upper bounds for the area of the filled Julia set for $f_c(z) = z^2 + c$ in the range $-2 \leq c \leq .25$.

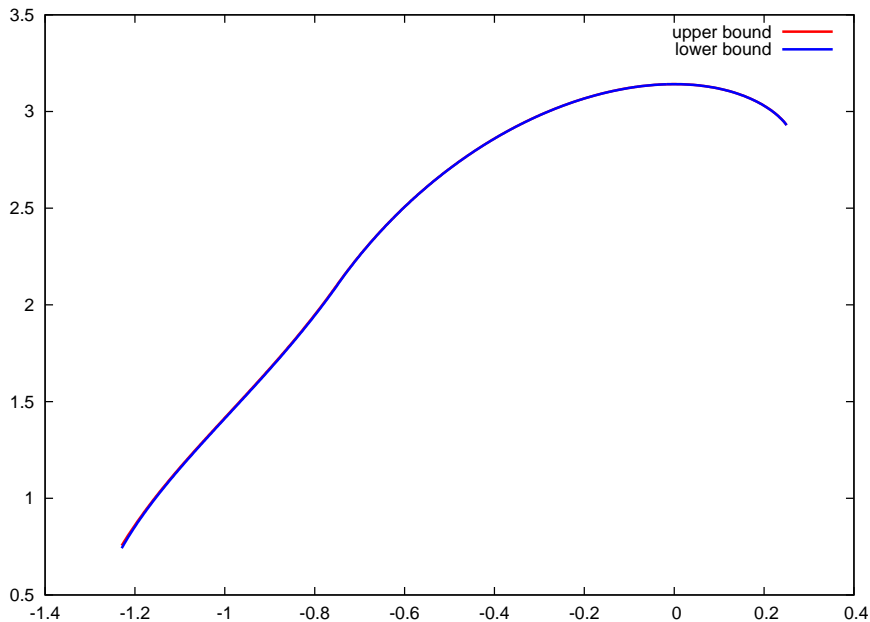
Area of filled Julia set $-1.25 \leq c \leq 0.25$



Area of filled Julia set

$-1.25 \leq c \leq 0.25$

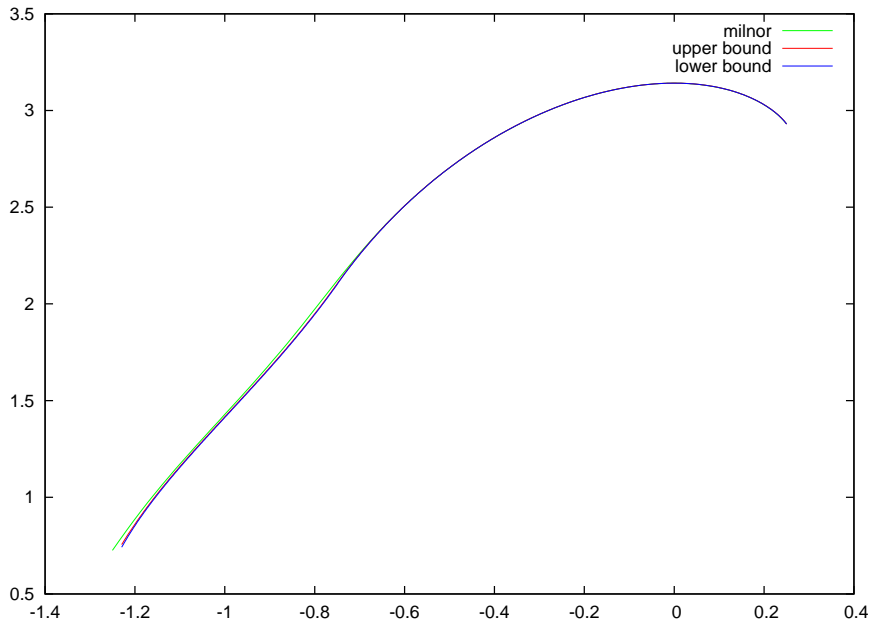
level 19



Area of filled Julia set

$-1.25 \leq c \leq 0.25$

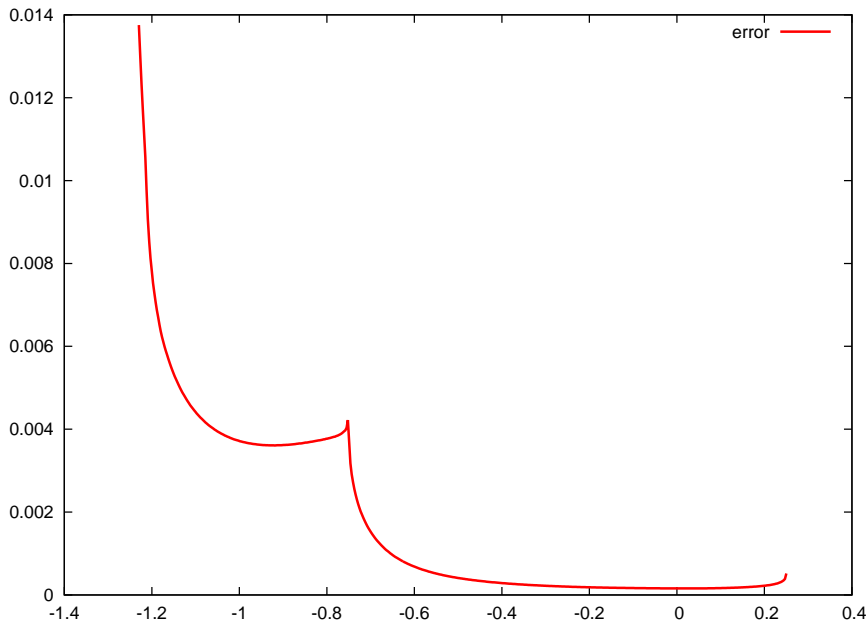
level 19



Area of filled Julia set

$-1.25 \leq c \leq 0.25$

level 19



Limitations

- ▶ Memory

- ▶ Need to explore $\Omega \supseteq [-R, R] \times [-R, R]$

Limitations

- ▶ Memory

- depth of quadtree and size of cell graph limited by available memory
 - currently spatial resolution $\approx 4 \times 10^{-6}$
 - cannot reach 20 levels

- ▶ Need to explore $\Omega \supseteq [-R, R] \times [-R, R]$

- even if region of interest is smaller

- limited amount of zoom

- limitation inherent to using cell mapping because f is transitive on J

- ▶ Escape radius

- ▶ Bounding box

- ▶ Escape radius

$$R = \frac{1 + |a_d| + \cdots + |a_0|}{|a_d|}$$

is an escape radius for $f(z) = a_d z^d + \cdots + a_0$

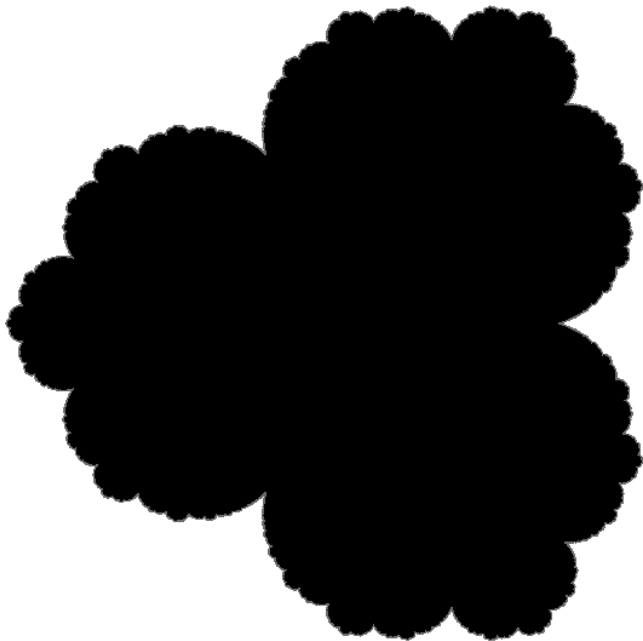
(Douady)

- ▶ Bounding box

needs interval arithmetic with directed rounding

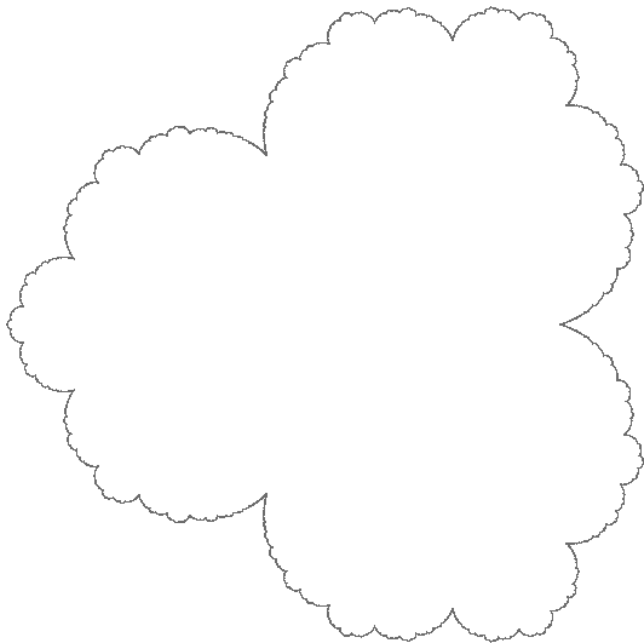
Cubic Julia set

$$z^3 + 0.38$$



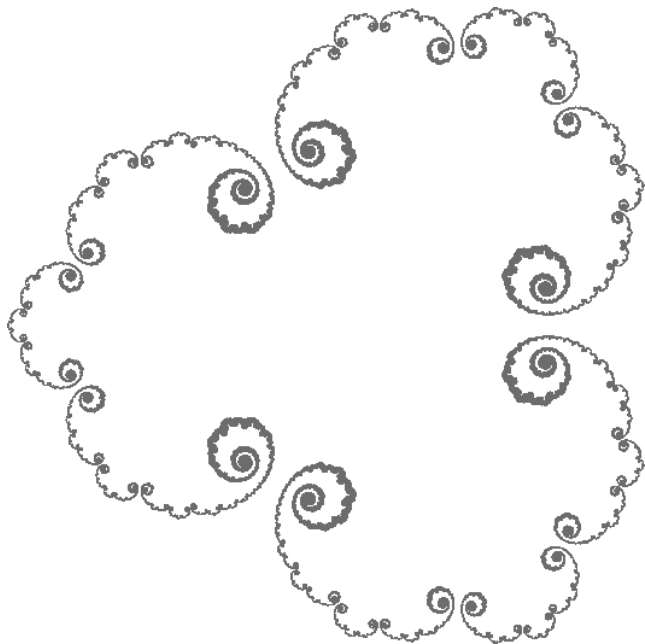
Cubic Julia set

$$z^3 + 0.38$$



Cubic Julia set

$$z^3 + 0.41$$



Cubic Julia set

$$z^3 - 3a^2 + b$$

level 0



Cubic Julia set

$$z^3 - 3a^2 + b$$

level 1



Cubic Julia set

$$z^3 - 3a^2 + b$$

level 2



Cubic Julia set

$$z^3 - 3a^2 + b$$

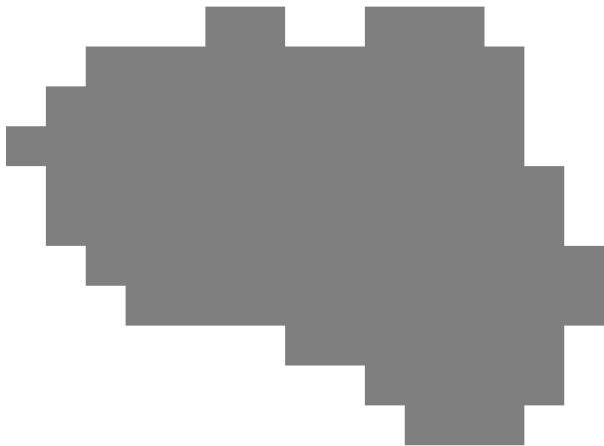
level 3



Cubic Julia set

$$z^3 - 3a^2 + b$$

level 4



Cubic Julia set

$$z^3 - 3a^2 + b$$

level 5



Cubic Julia set

$$z^3 - 3a^2 + b$$

level 6



Cubic Julia set

$$z^3 - 3a^2 + b$$

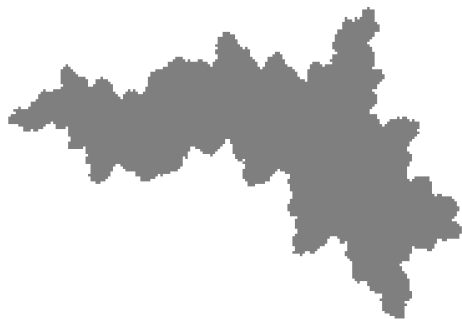
level 7



Cubic Julia set

$$z^3 - 3a^2 + b$$

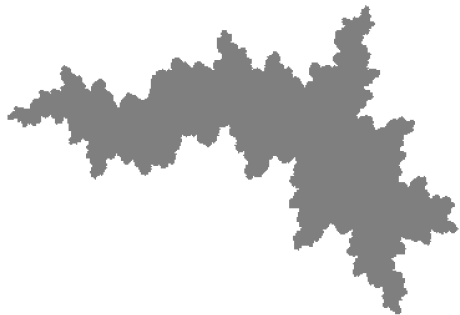
level 8



Cubic Julia set

$$z^3 - 3a^2 + b$$

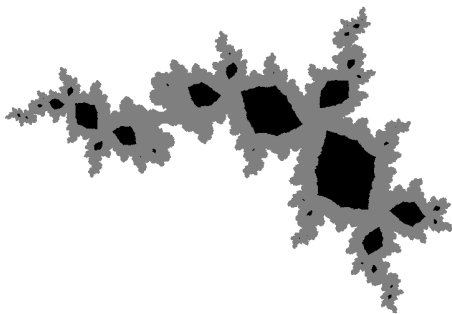
level 9



Cubic Julia set

$$z^3 - 3a^2 + b$$

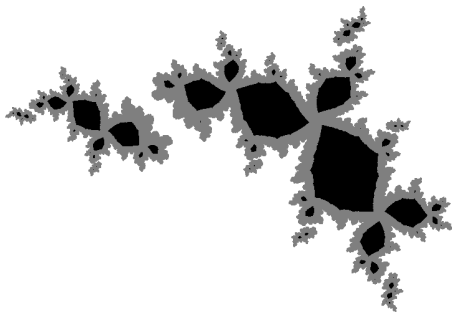
level 10



Cubic Julia set

$$z^3 - 3a^2 + b$$

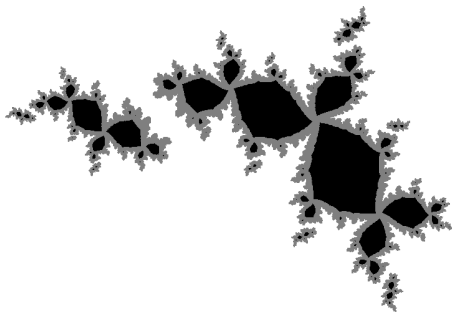
level 11



Cubic Julia set

$$z^3 - 3a^2 + b$$

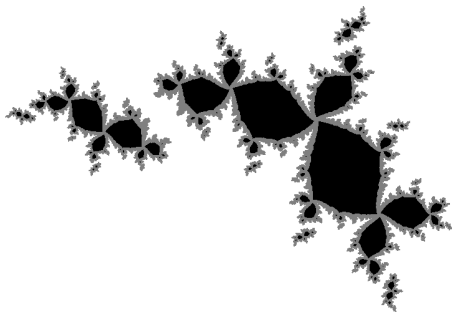
level 12



Cubic Julia set

$$z^3 - 3a^2 + b$$

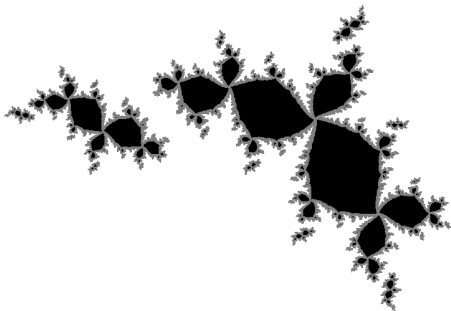
level 13



Cubic Julia set

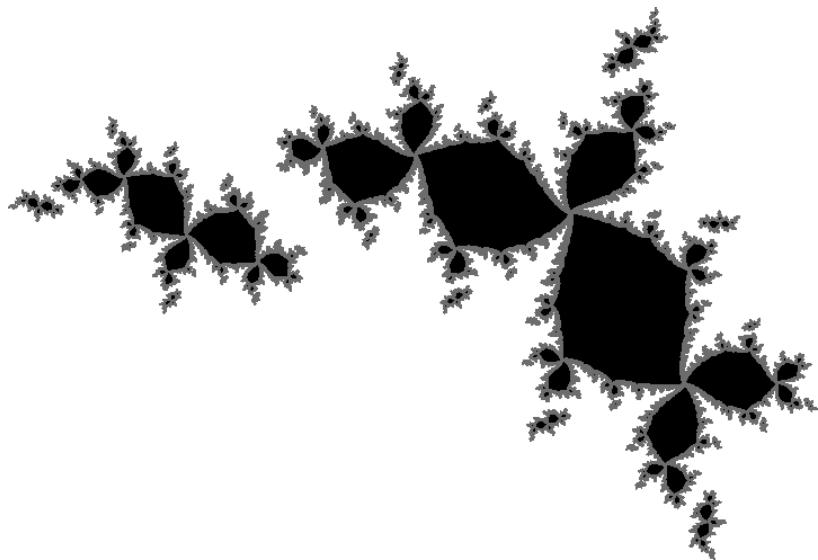
$$z^3 - 3a^2 + b$$

level 14



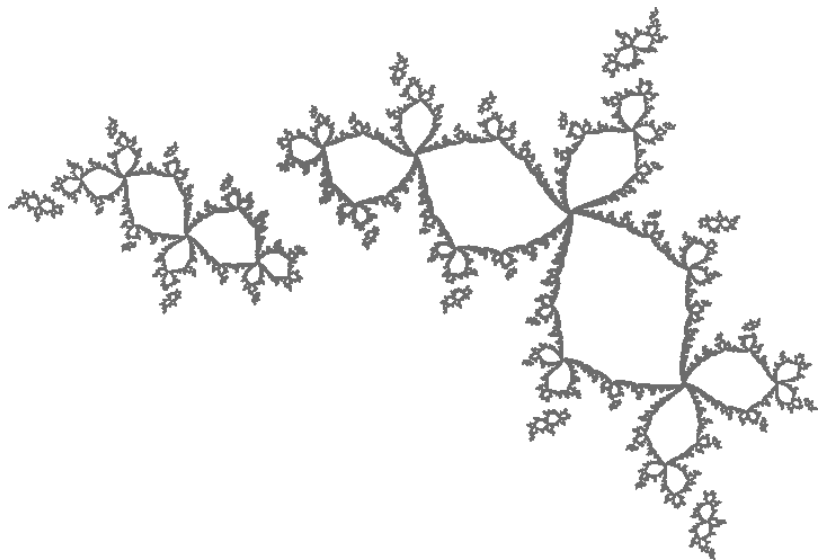
Cubic Julia set

$$z^3 - 3a^2 + b$$



Cubic Julia set

$$z^3 - 3a^2 + b$$



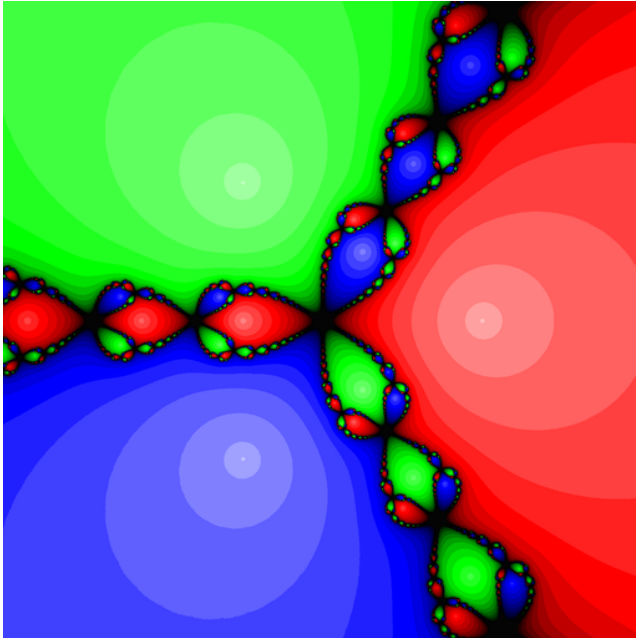
- ▶ Which points converge to which root?
- ▶ Points that do not converge form the Julia set
- ▶ No escape radius
- ▶ Need to find explicit attracting regions around roots?

Cayley (1879)

Future work

Newton's method

$$z^3 = 1$$

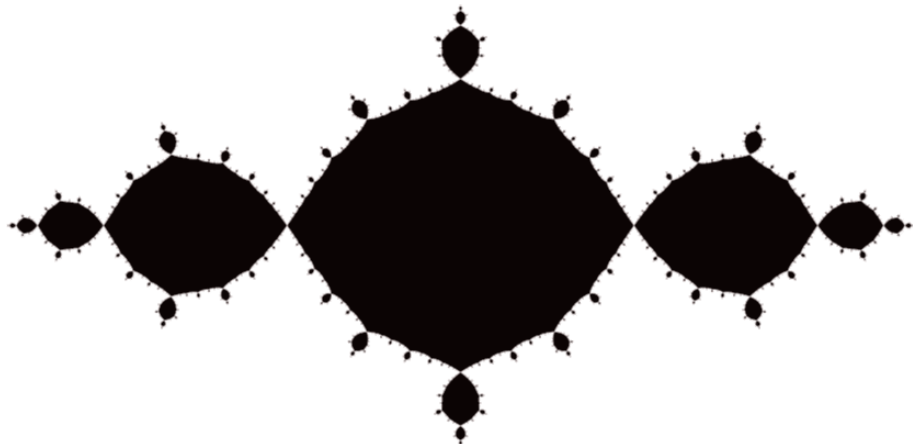


Joachim von zur Gathen and Jürgen Gerhard

Julia set panorama

```
http://monge.visgrafimpa.br/panorama/viewer/index.html?  
img=../julia-256GP/julia.xml
```

Images of Julia sets that you can trust



Thanks!

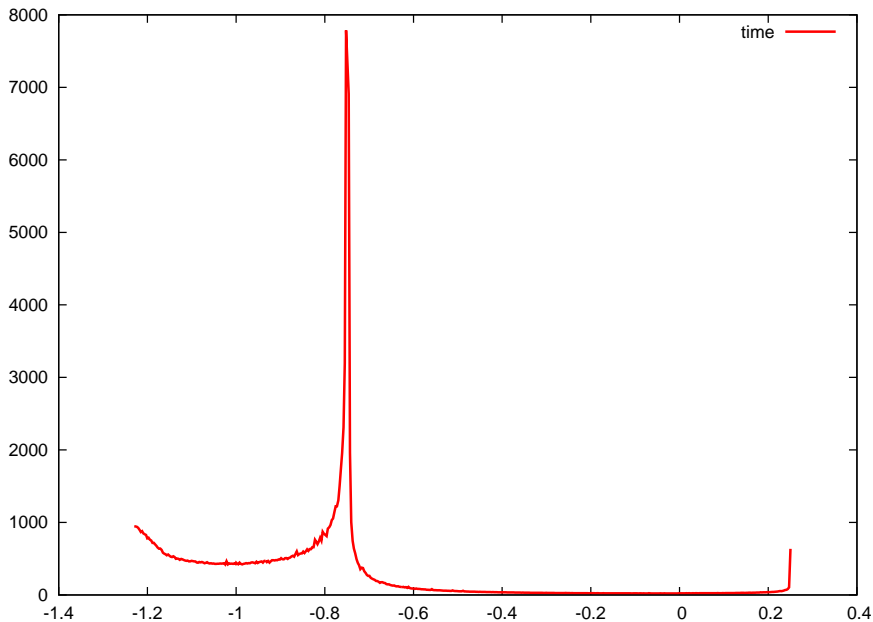
Related work

- ▶ M. Braverman and M. Yampolsky. *Computability of Julia sets*, volume 23 of *Algorithms and Computation in Mathematics*. Springer-Verlag, 2009.
- ▶ M. Dellnitz and A. Hohmann. A subdivision algorithm for the computation of unstable manifolds and global attractors. *Numerische Mathematik*, 75(3):293–317, 1997.
- ▶ C. S. Hsu. *Cell-to-cell mapping: A method of global analysis for nonlinear systems*. Springer-Verlag, 1987.
- ▶ J. Milnor. *Dynamics in one complex variable*, volume 160 of *Annals of Mathematics Studies*. Princeton University Press, third edition, 2006.
- ▶ R. E. Moore. *Interval Analysis*. Prentice-Hall, 1966.
- ▶ R. Rettinger and K. Weihrauch. The computational complexity of some Julia sets. In *Proceedings of the 35th Annual ACM Symposium on Theory of Computing*, pages 177–185. ACM, 2003.
- ▶ D. Saupe. Efficient computation of Julia sets and their fractal dimension. *Phys. D*, 28(3):358–370, 1987.

Area of filled Julia set

$-1.25 \leq c \leq 0.25$

level 19



$$(x, y) \mapsto (x^2 - y^2 + a, 2xy + b)$$

```
function f(xmin,xmax,ymin,ymax)
    local x2min,x2max=isqr(xmin,xmax)
    local y2min,y2max=isqr(ymin,ymax)
    local xymin,xymax=imul(xmin,xmax,ymin,ymax)
    return x2min-y2max+a,x2max-y2min+a,2*xymin+b,2*xymax+b
end
```

```
function imul(xmin,xmax,ymin,ymax)
    local mm=xmin*ymin
    local mM=xmin*ymax
    local Mm=xmax*ymin
    local MM=xmax*ymax
    local m,M=mm,mm
    if m>mM then m=mM elseif M<mM then M=mM end
    if m>Mm then m=Mm elseif M<Mm then M=Mm end
    if m>MM then m=MM elseif M<MM then M=MM end
    return m,M
end
```

$$(x, y) \mapsto (x^2 - y^2 + a, 2xy + b)$$

```
function f(xmin,xmax,ymin,ymax)
    local x2min,x2max=isqr(xmin,xmax)
    local y2min,y2max=isqr(ymin,ymax)
    local xymin,xymax=imul(xmin,xmax,ymin,ymax)
    return x2min-y2max+a,x2max-y2min+a,2*xymin+b,2*xymax+b
end
```

```
function isqr(xmin,xmax)
    local u=xmin^2
    local v=xmax^2
    if xmin<=0 and 0<=xmax then
        if u<v then return 0,v else return 0,u end
    else
        if u<v then return u,v else return v,u end
    end
end
```

$$(x, y) \mapsto (x^3 - 3xy^2 + a, -y^3 + 3x^2y + b)$$

```
function f(xmin,xmax,ymin,ymax)
    local x2min,x2max=isqr(xmin,xmax)
    local y2min,y2max=isqr(ymin,ymax)
    local xy2min,xy2max=imul(xmin,xmax,y2min,y2max)
    local x2ymin,x2ymax=imul(x2min,x2max,ymin,ymax)
    local x3min,x3max=icub(xmin,xmax)
    local y3min,y3max=icub(ymin,ymax)
    return x3min-3*xy2max+a, x3max-3*xy2min+a,
           -y3max+3*x2ymin+b,-y3min+3*x2ymax+b
end

function icub(xmin,xmax)
    return xmin^3,xmax^3
end
```