



First Palis-Balzan International Symposium on
Dynamical Systems

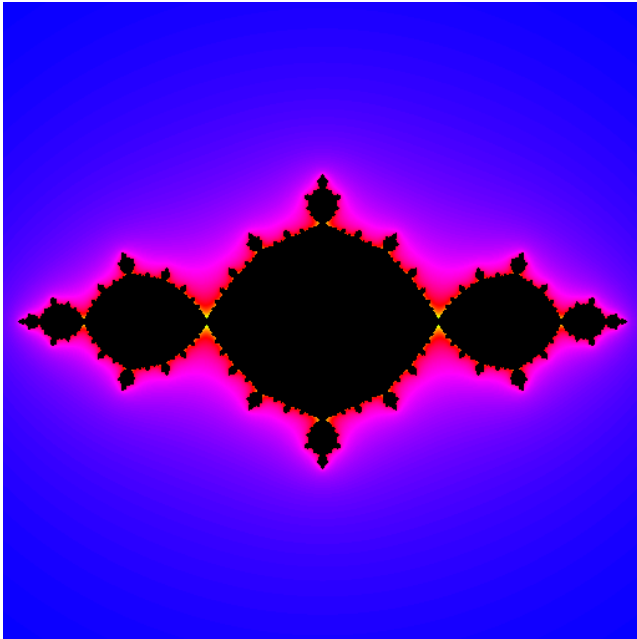
Images of Julia sets that you can trust

Luiz Henrique de Figueiredo
IMPA

with

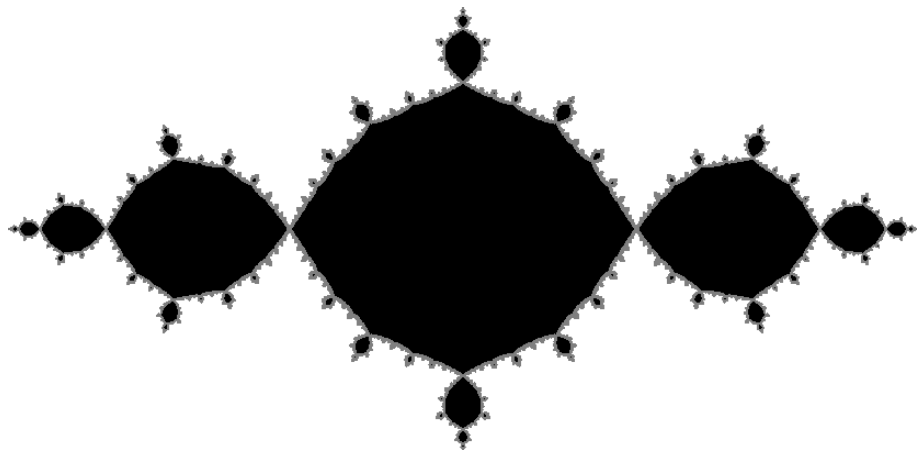
Diego Nehab (IMPA) • Jorge Stolfi (UNICAMP) • João Batista Oliveira (PUCRS)

Can we trust this beautiful image?



Curtis McMullen

Julia sets

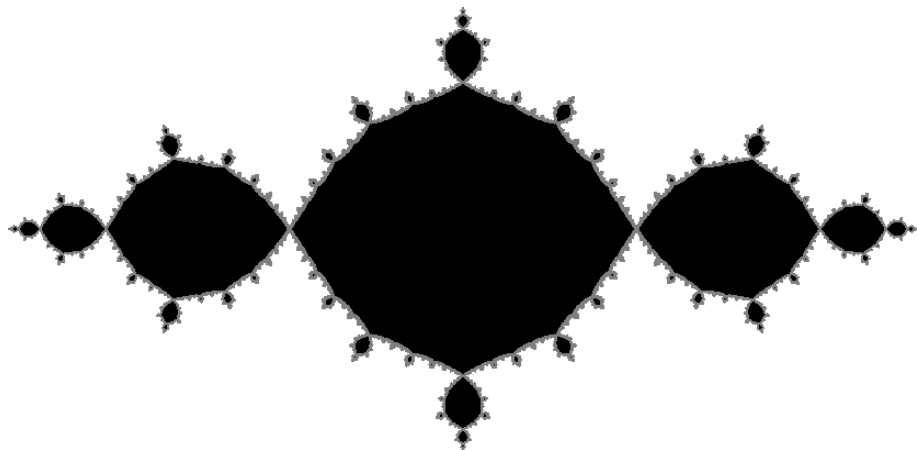


Describe the **dynamics** of $f(z) = z^2 + c$ for $c \in \mathbb{C}$ fixed

$$z_1 = f(z_0), \quad z_2 = f(z_1), \quad \dots, \quad z_n = f(z_{n-1}) = f^n(z_0)$$

What happens with the **orbit** of $z_0 \in \mathbb{C}$ under f ?

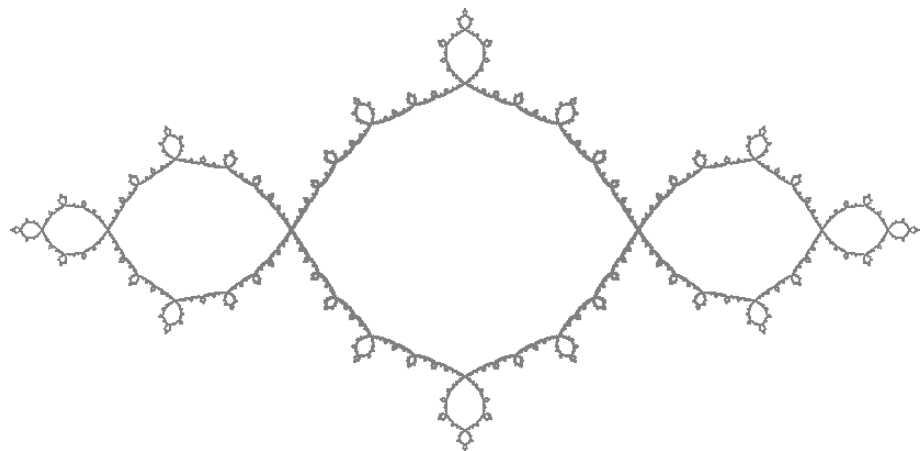
Julia sets



□ unbounded orbits = attraction basin of ∞
■ bounded orbits = filled Julia set

$A(\infty)$
 K

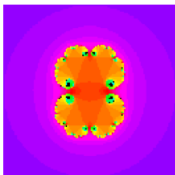
Julia sets



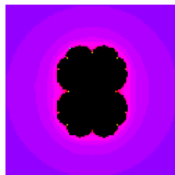
- unbounded orbits = attraction basin of ∞
- bounded orbits = filled Julia set
- common boundary = Julia set

$A(\infty)$
 K
 J

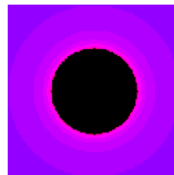
Julia set zoo



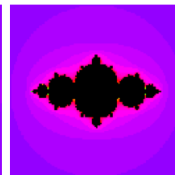
$c = 0.275$



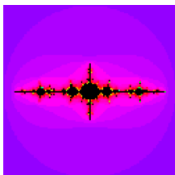
$c = \frac{1}{4}$



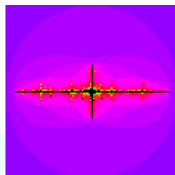
$c = 0$



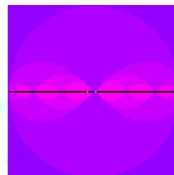
$c = -\frac{3}{4}$



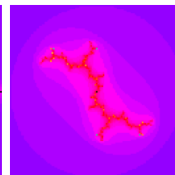
$c = -1.312$



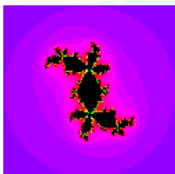
$c = -1.375$



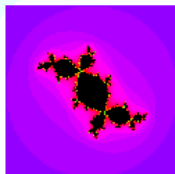
$c = -2$



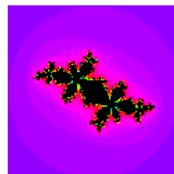
$c = i$



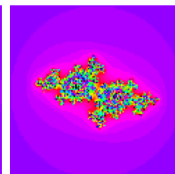
$c = (+0.285, +0.535)$



$c = (-0.125, +0.750)$

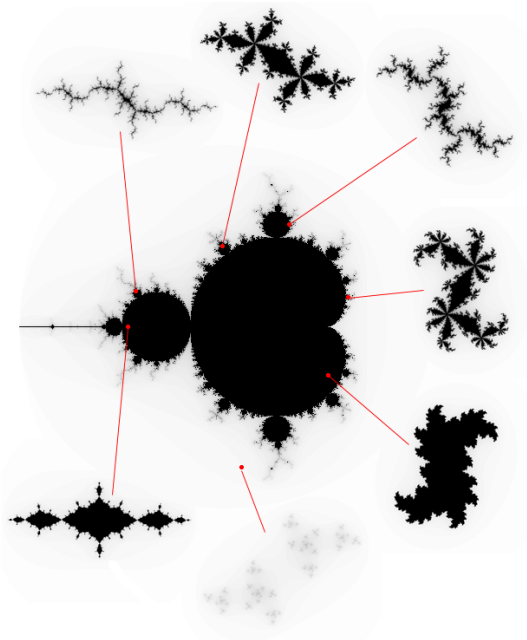


$c = (-0.500, +0.563)$



$c = (-0.687, +0.312)$

Julia set catalog: the Mandelbrot set

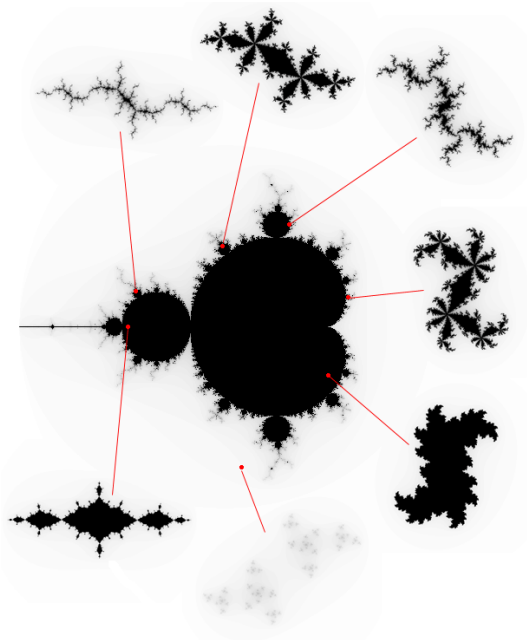


$$c \in \mathcal{M} := 0 \in K_c$$

Julia–Fatou dichotomy

$c \in \mathcal{M} \Rightarrow J_c$ is connected

$c \notin \mathcal{M} \Rightarrow J_c$ is a Cantor set



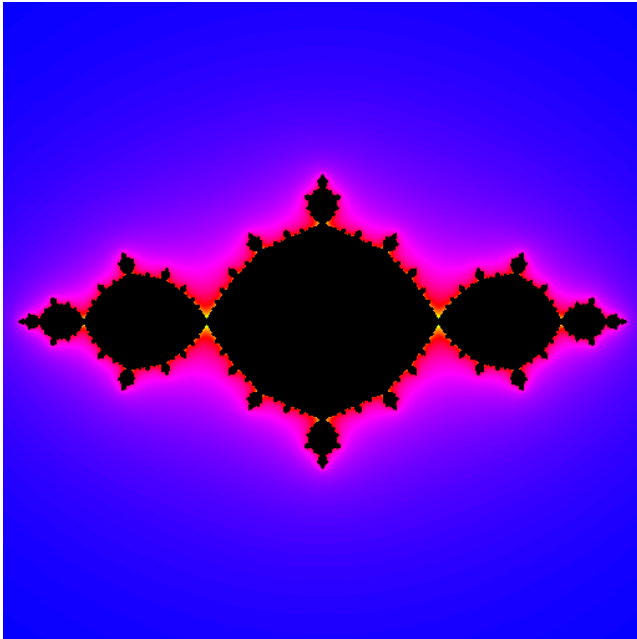
$$c \in \mathcal{M} := 0 \in K_c$$

Julia–Fatou dichotomy

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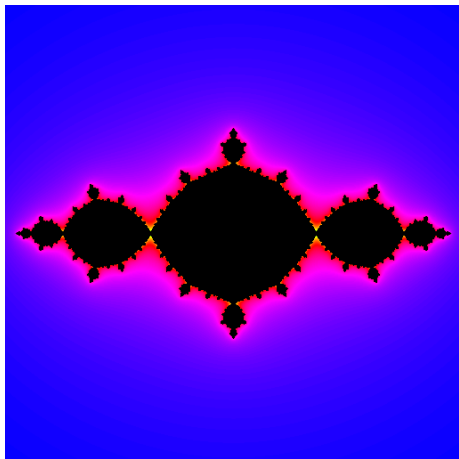
$c \notin \mathcal{M} \Rightarrow J_c$ is a Cantor set

Why distrust this beautiful image?



Curtis McMullen

Why distrust this beautiful image?

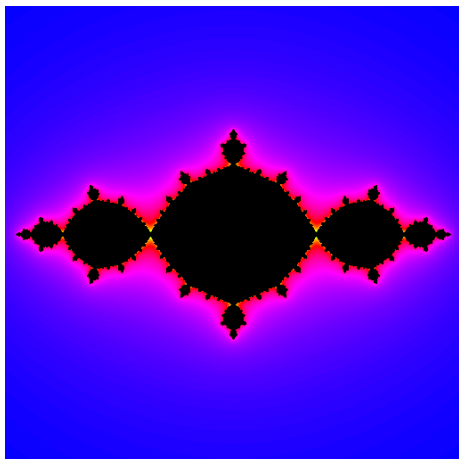


Curtis McMullen

Escape-time algorithm

```
for  $z_0$  in a grid of points in  $\Omega$   
   $z \leftarrow z_0$   
   $n \leftarrow 0$   
  while  $|z| \leq R$  and  $n \leq N$  do  
     $z \leftarrow z^2 + c$   
     $n \leftarrow n + 1$   
  paint  $z_0$  with color  $n$ 
```

Why distrust this beautiful image?



Curtis McMullen

Escape-time algorithm

for z_0 in a grid of points in Ω

$z \leftarrow z_0$

$n \leftarrow 0$

while $|z| \leq R$ and $n \leq N$ do

$z \leftarrow z^2 + c$

$n \leftarrow n + 1$

paint z_0 with color n

escape radius

$$R = \max(|c|, 2) \quad J \subset B(0, R)$$

Why distrust this beautiful image?

- ▶ Spatial sampling
what happens between samples?

Escape-time algorithm

```
for  $z_0$  in a grid of points in  $\Omega$ 
   $z \leftarrow z_0$ 
   $n \leftarrow 0$ 
  while  $|z| \leq R$  and  $n \leq N$  do
     $z \leftarrow z^2 + c$ 
     $n \leftarrow n + 1$ 
  paint  $z_0$  with color  $n$ 
```

escape radius

$$R = \max(|c|, 2) \quad J \subset B(0, R)$$

Why distrust this beautiful image?

- ▶ Spatial sampling
- ▶ Partial orbits
program cannot run forever

Escape-time algorithm

```
for  $z_0$  in a grid of points in  $\Omega$   
   $z \leftarrow z_0$   
   $n \leftarrow 0$   
  while  $|z| \leq R$  and  $n \leq N$  do  
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  paint  $z_0$  with color  $n$ 
```

escape radius

$$R = \max(|c|, 2) \quad J \subset B(0, R)$$

Why distrust this beautiful image?

- ▶ Spatial sampling
- ▶ Partial orbits
- ▶ Floating-point rounding errors
squaring needs double digits

Escape-time algorithm

```
for  $z_0$  in a grid of points in  $\Omega$ 
   $z \leftarrow z_0$ 
   $n \leftarrow 0$ 
  while  $|z| \leq R$  and  $n \leq N$  do
     $z \leftarrow z^2 + c$ 
     $n \leftarrow n + 1$ 
  paint  $z_0$  with color  $n$ 
```

escape radius

$$R = \max(|c|, 2) \quad J \subset B(0, R)$$

Why distrust this beautiful image?

- ▶ Spatial sampling

Compute color on grid points

Cannot be sure behaviour at sample points is typical

Finer grid \Rightarrow more detail

- ▶ Partial orbits

Can only compute partial orbits

Cannot be sure partial orbits are long enough

Longer orbits \Rightarrow more detail

- ▶ Floating-point errors

z^2 needs twice the number of digits that z needs

Do rounding errors during iteration influence classification of points?

Multiple-precision \Rightarrow more detail (deep zoom)

You can trust our method

- ▶ No spatial sampling
- ▶ No orbits
- ▶ No floating-point errors

You can trust our method

- ▶ No spatial sampling

Classify **entire rectangles** in the complex plane

Spatial resolution limited by available memory

Deeper quadtree \Rightarrow more detail

- ▶ No orbits

- ▶ No floating-point errors

You can trust our method

- ▶ No spatial sampling

Classify **entire rectangles** in the complex plane

Spatial resolution limited by available memory

Deeper quadtree \Rightarrow more detail

- ▶ No orbits

Evaluate f once on each cell using interval arithmetic

Perform **no function iteration** at all

Use cell mapping and label propagation in graphs

- ▶ No floating-point errors

You can trust our method

- ▶ No spatial sampling

Classify **entire rectangles** in the complex plane

Spatial resolution limited by available memory

Deeper quadtree \Rightarrow more detail

- ▶ No orbits

Evaluate f once on each cell using interval arithmetic

Perform **no function iteration** at all

Use cell mapping and label propagation in graphs

- ▶ No floating-point errors

All numbers are dyadic fractions with restricted range and precision

Use **error-free fixed-point** arithmetic

Precision depends only on spatial resolution

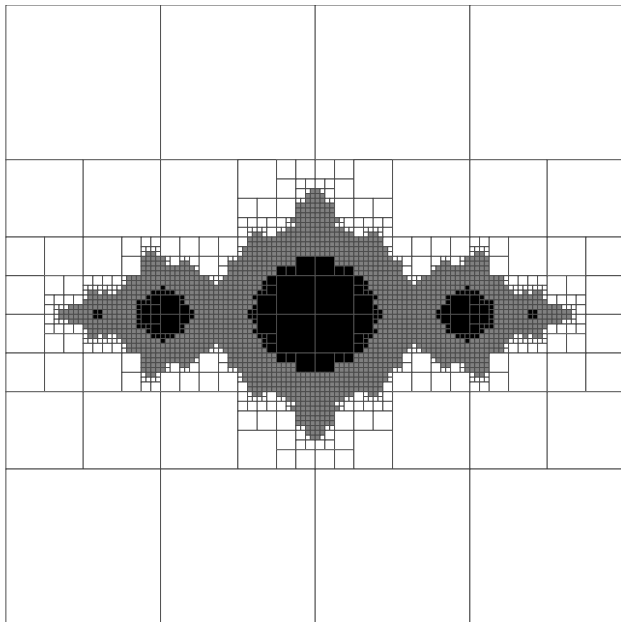
Standard double-precision floating-point enough for huge images

Our algorithm

quadtrees for

$$\Omega = [-R, R] \times [-R, R]$$

- ▶ white rectangles contained in $A(\infty)$
- ▶ black rectangles contained in K
- ▶ gray rectangles contain J



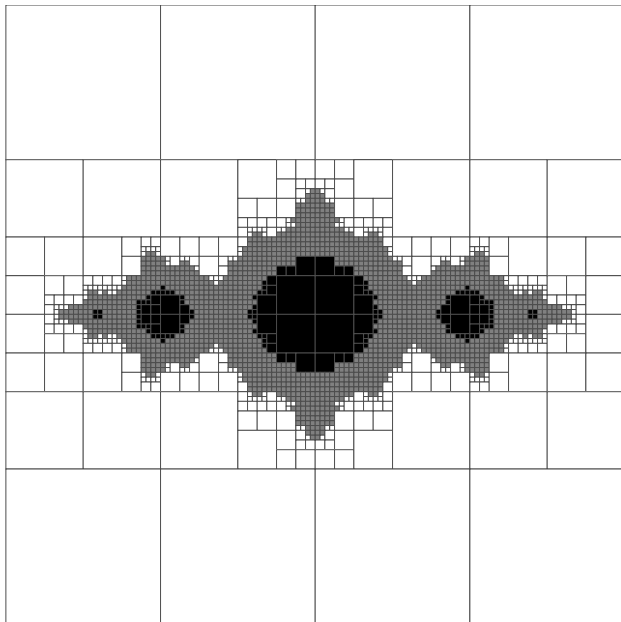
Our algorithm

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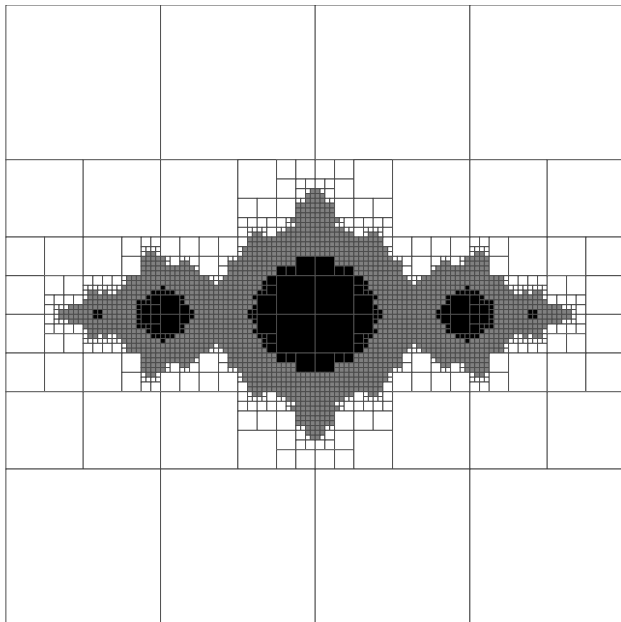
certified decomposition



Our algorithm

quadtrees for
 $\Omega = [-R, R] \times [-R, R]$

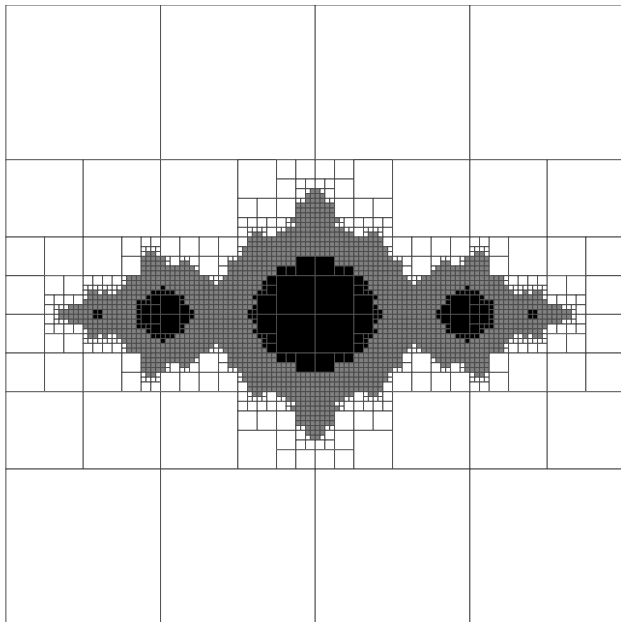
- ▶ refinement
- ▶ cell mapping
- ▶ label propagation



Our algorithm

quadtrees for
 $\Omega = [-R, R] \times [-R, R]$

- ▶ refinement
- ▶ cell mapping
- ▶ label propagation



Quadtree

$c = -1$

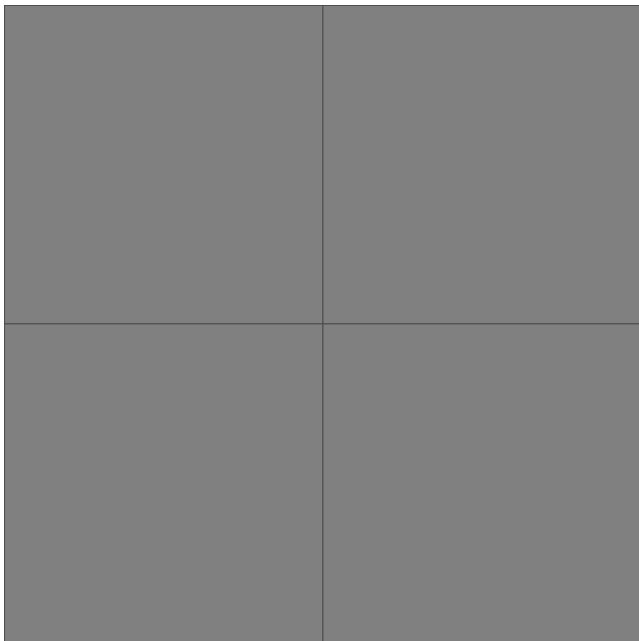
level 0



Quadtree

$c = -1$

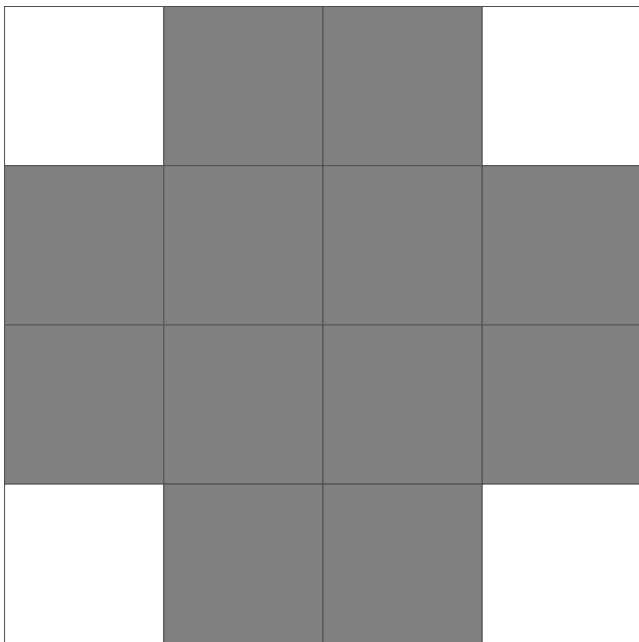
level 1



Quadtree

$c = -1$

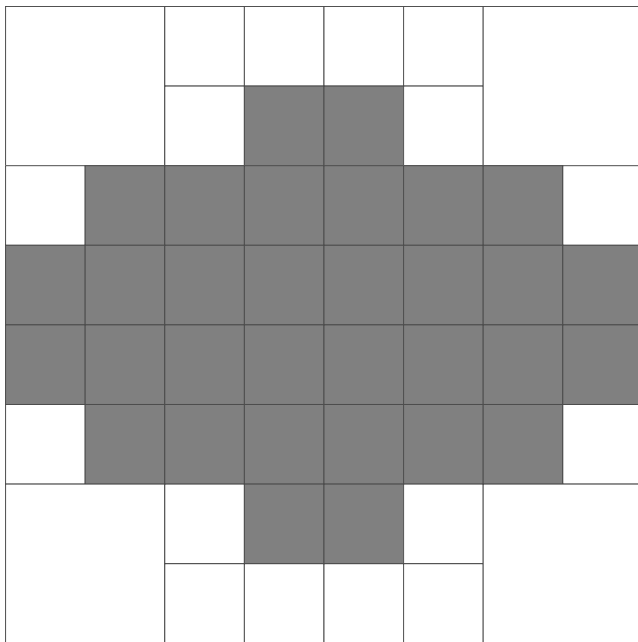
level 2



Quadtree

$c = -1$

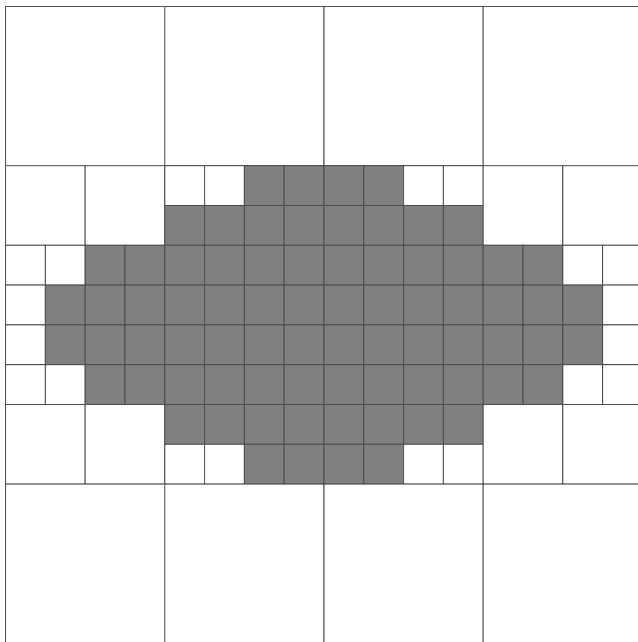
level 3



Quadtree

$c = -1$

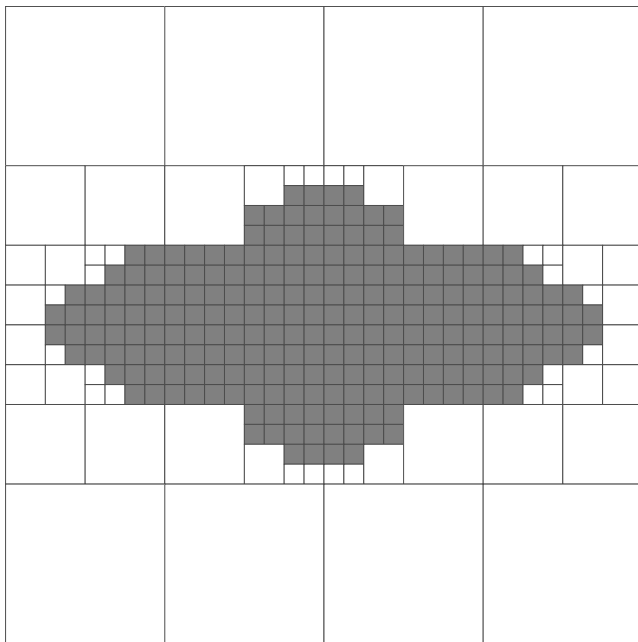
level 4



Quadtree

$c = -1$

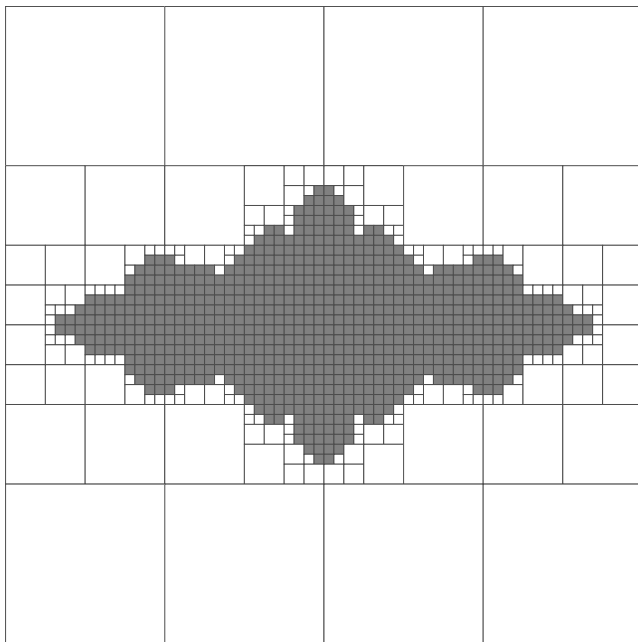
level 5



Quadtree

$c = -1$

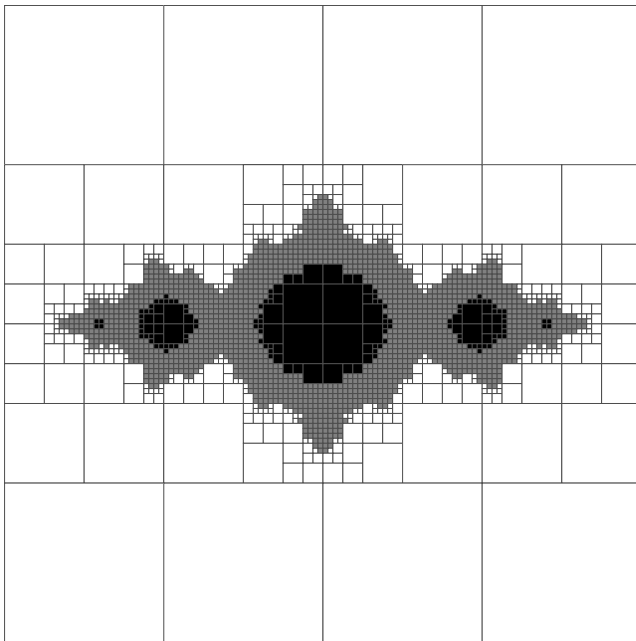
level 6



Quadtree

$c = -1$

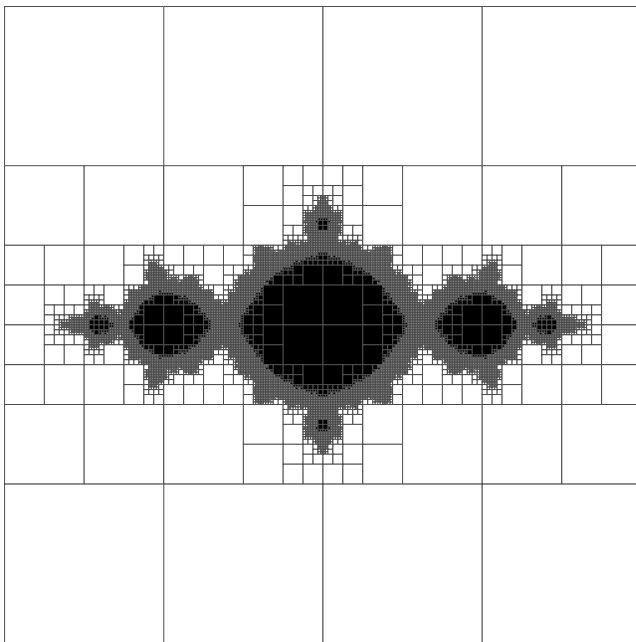
level 7



Quadtree

$c = -1$

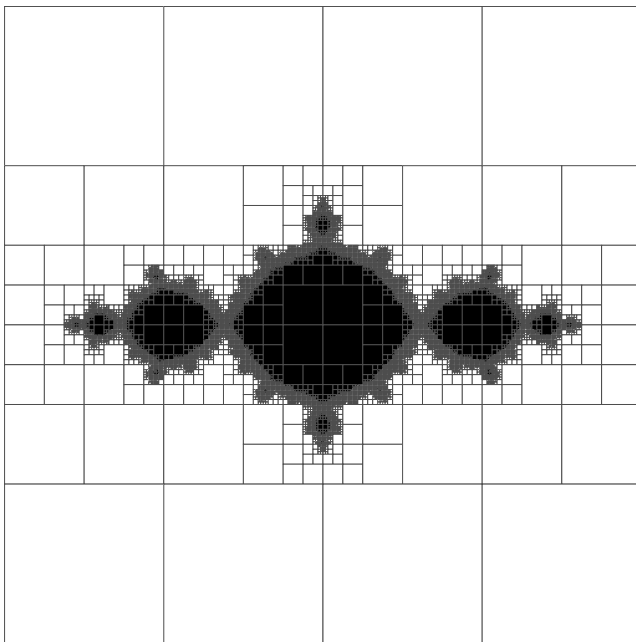
level 8



Quadtree

$c = -1$

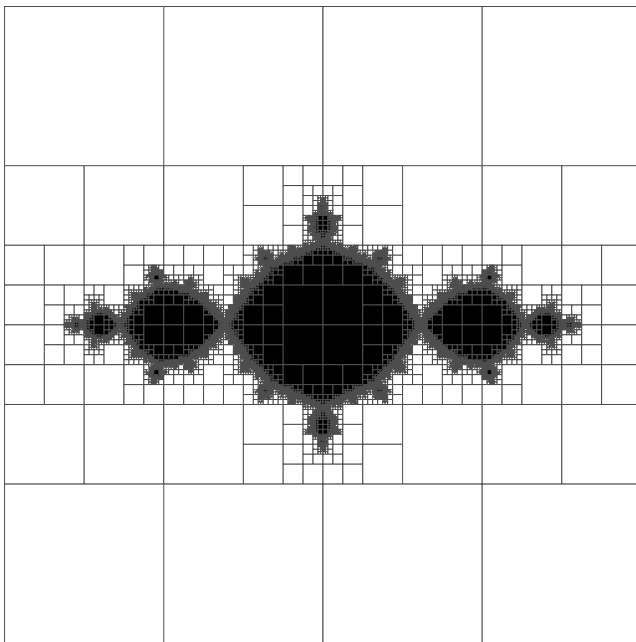
level 9



Quadtree

$c = -1$

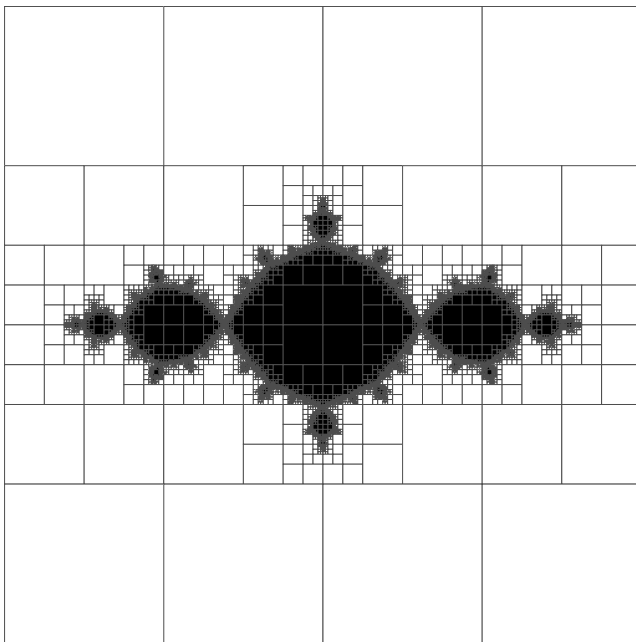
level 10



Quadtree

$c = -1$

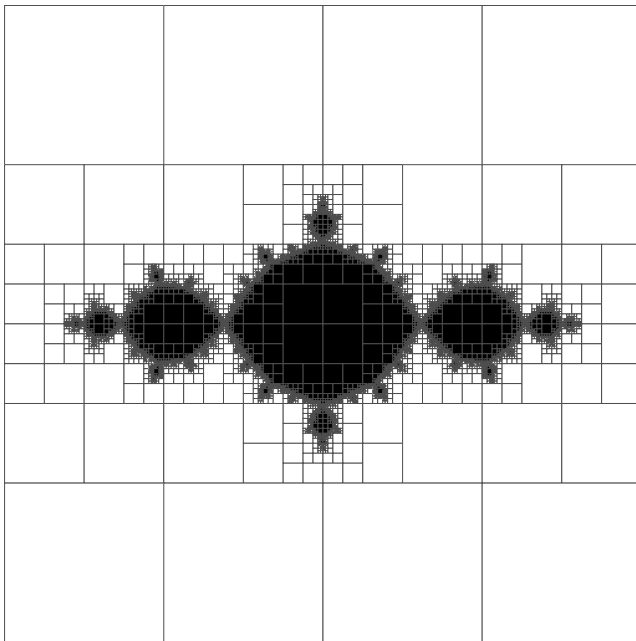
level 11



Quadtree

$c = -1$

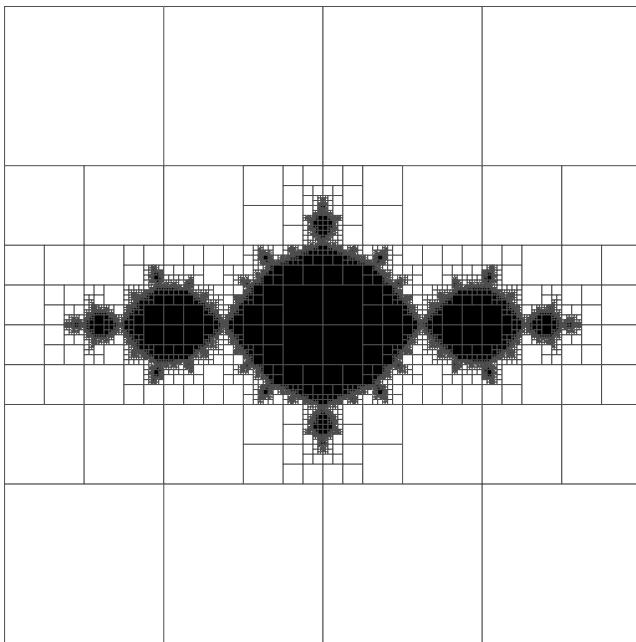
level 12



Quadtree

$c = -1$

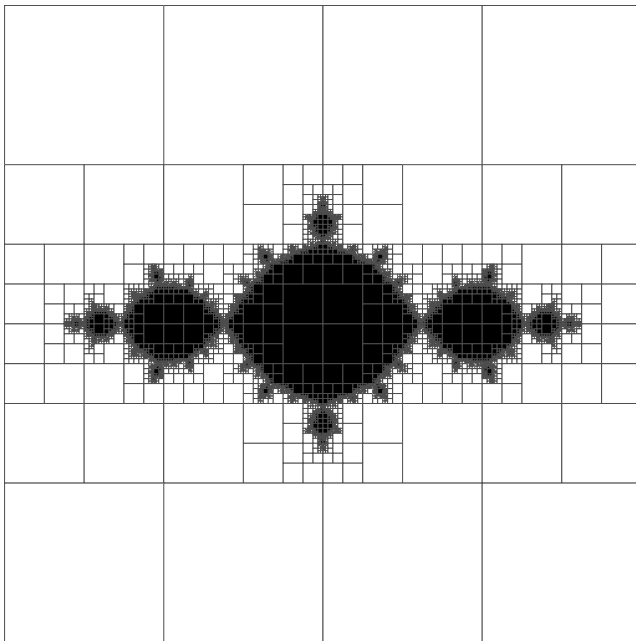
level 13



Quadtree

$c = -1$

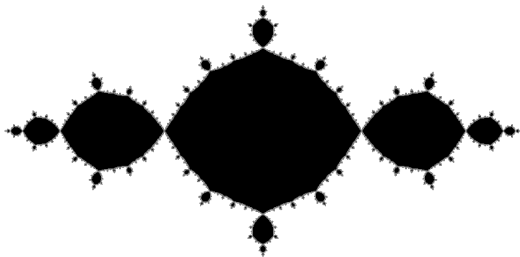
level 14



Adaptive approximation

$c = -1$

level 14



Adaptive approximation

$c = -1$

level 0



Adaptive approximation

$c = -1$

level 1



Adaptive approximation

$c = -1$

level 2



Adaptive approximation

$c = -1$

level 3



Adaptive approximation

$c = -1$

level 4



Adaptive approximation

$c = -1$

level 5



Adaptive approximation

$c = -1$

level 6



Adaptive approximation

$c = -1$

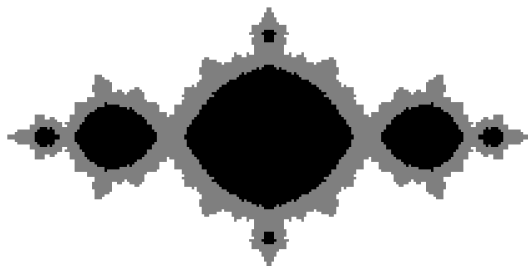
level 7



Adaptive approximation

$c = -1$

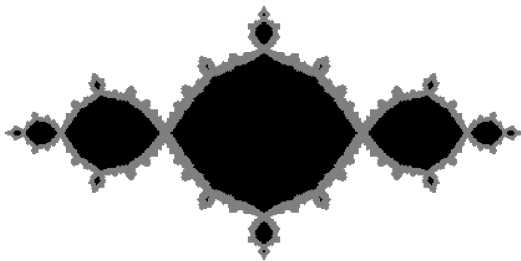
level 8



Adaptive approximation

$c = -1$

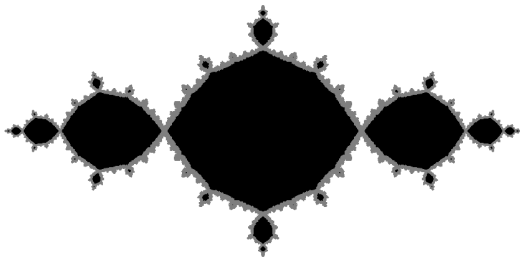
level 9



Adaptive approximation

$c = -1$

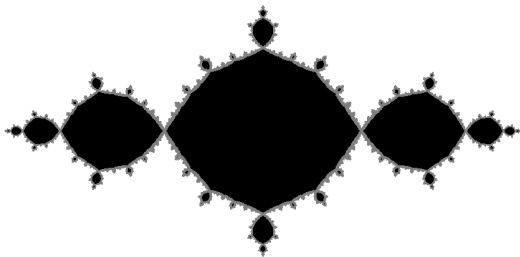
level 10



Adaptive approximation

$c = -1$

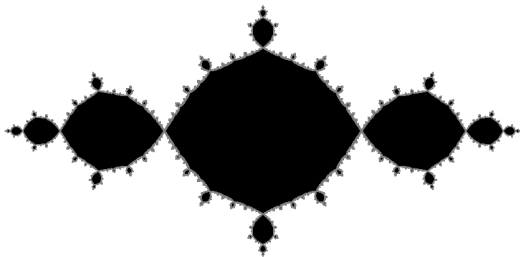
level 11



Adaptive approximation

$c = -1$

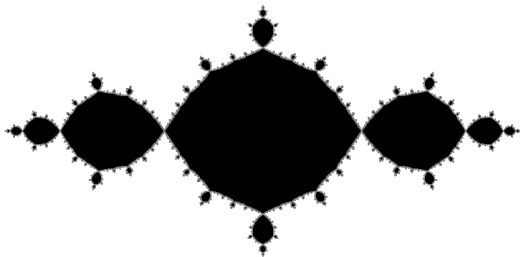
level 12



Adaptive approximation

$c = -1$

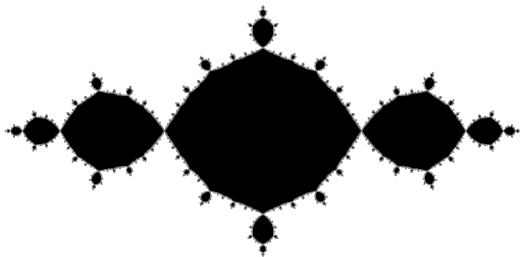
level 13



Adaptive approximation

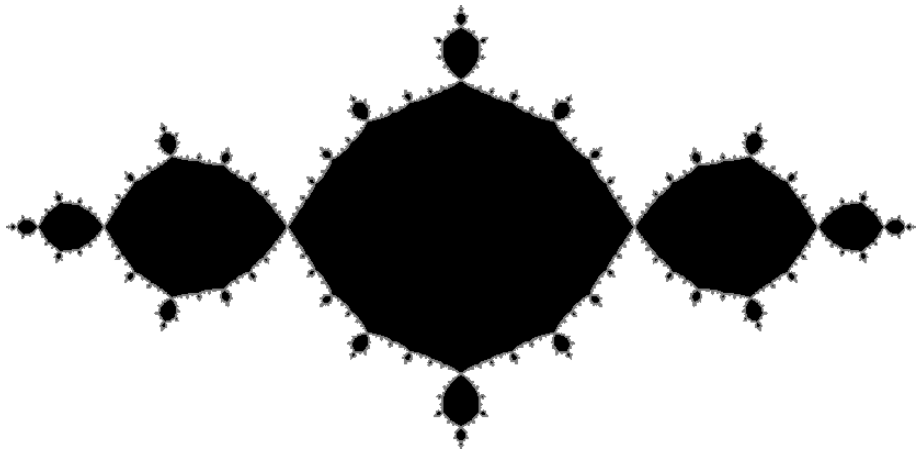
$c = -1$

level 14



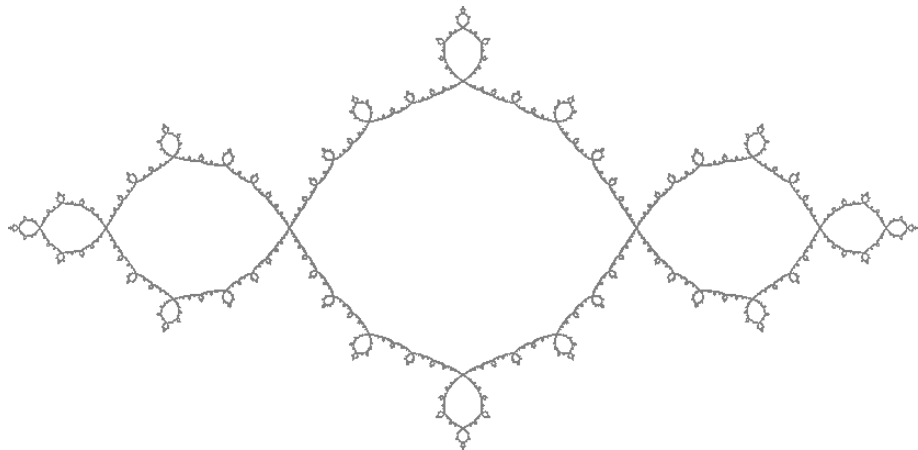
Adaptive approximation

$$c = -1$$



Adaptive approximation

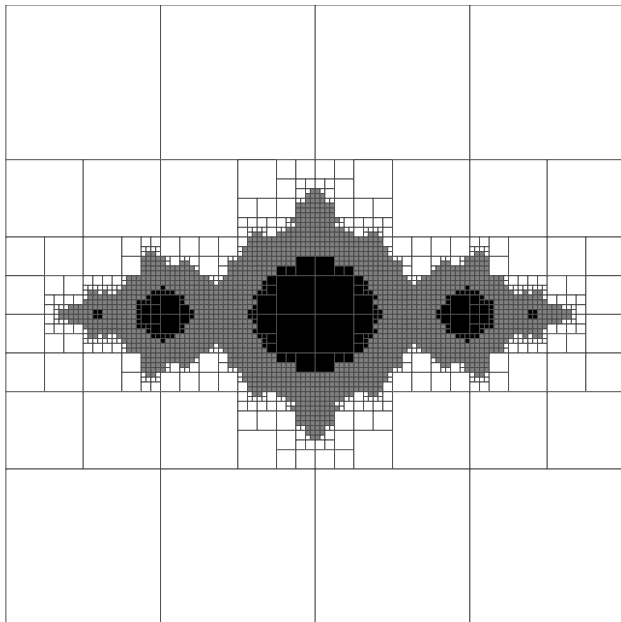
$$c = -1$$



Our algorithm

quadtrees for
 $\Omega = [-R, R] \times [-R, R]$

- ▶ refinement
- ▶ cell mapping
- ▶ label propagation



Cell mapping

Directed graph on the leaves of the quadtree

- ▶ edges emanate from each leaf gray cell q
- ▶ color q white if $f(q)$ is outside $B(0, R)$
- ▶ add edge $q \rightarrow t$ for each leaf cell t that intersects $f(q)$

Cell mapping

Directed graph on the leaves of the quadtree

- ▶ edges emanate from each leaf gray cell q
- ▶ color q white if $f(q)$ is outside $B(0, R)$
- ▶ add edge $q \rightarrow t$ for each leaf cell t that intersects $f(q)$

Conservative estimate of the dynamics

Avoid point sampling

Cell mapping

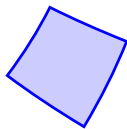
source cell

leaf gray cell



Cell mapping

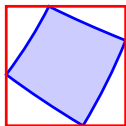
exact image under f



Cell mapping

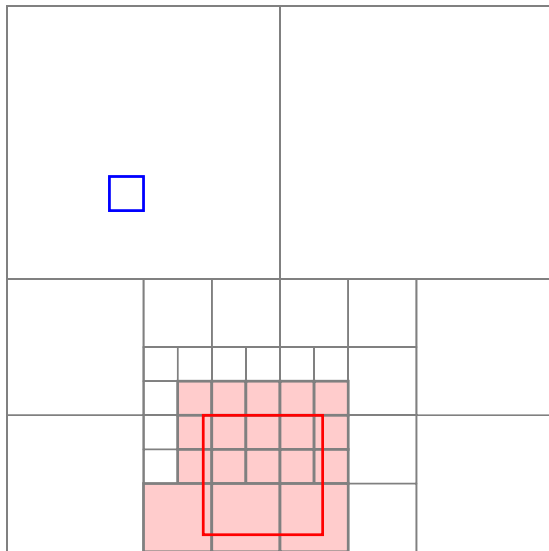
bounding box

interval arithmetic



Cell mapping

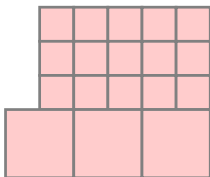
quadtree traversal

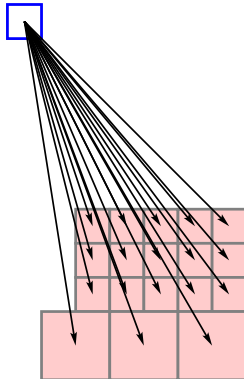


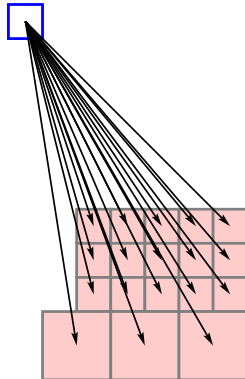
Cell mapping

target cells

contain exact image



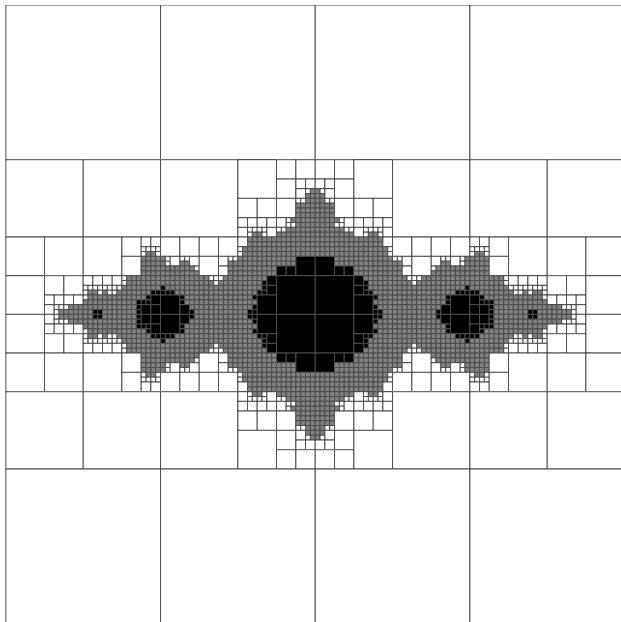




Our algorithm

quadtrees for
 $\Omega = [-R, R] \times [-R, R]$

- ▶ refinement
- ▶ cell mapping
- ▶ label propagation



Label propagation

Propagate white and black to gray cells

- ▶ new white cells
gray cells for which **all** paths end in white cells
- ▶ new black cells
gray cells for which **no** path ends in a white cell

Label propagation

Propagate white and black to gray cells

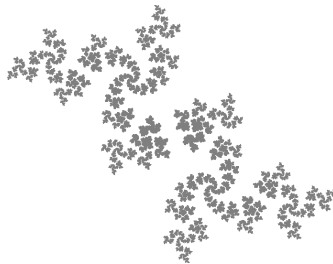
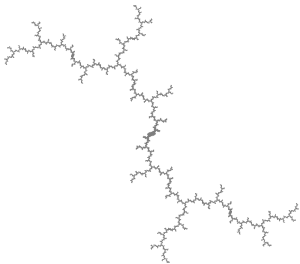
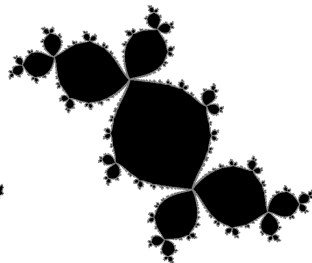
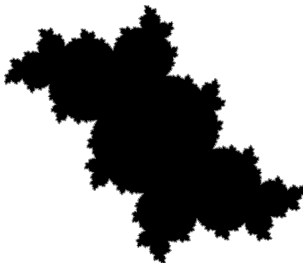
- ▶ new white cells
gray cells for which **all** paths end in white cells
- ▶ new black cells
gray cells for which **no** path ends in a white cell

Graph traversals replace function iteration

Avoid floating-point errors

Adaptive approximation

more examples



Adaptive approximation

$$c = 0.12 + 0.30 i \quad \text{level 0}$$



Adaptive approximation

$$c = 0.12 + 0.30 i \quad \text{level 1}$$



Adaptive approximation

$$c = 0.12 + 0.30 i \quad \text{level 2}$$



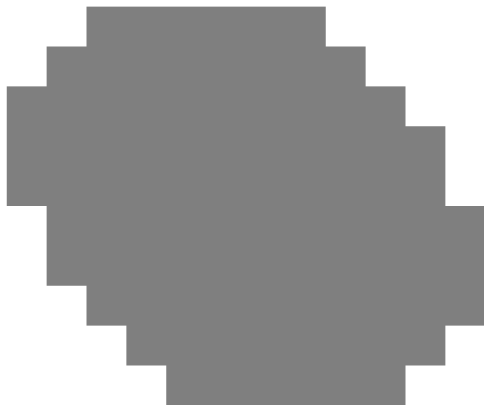
Adaptive approximation

$c = 0.12 + 0.30 i$ level 3



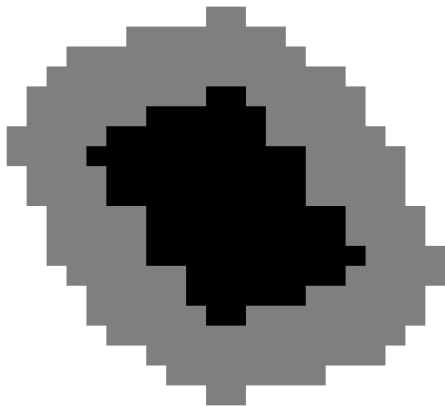
Adaptive approximation

$c = 0.12 + 0.30 i$ level 4



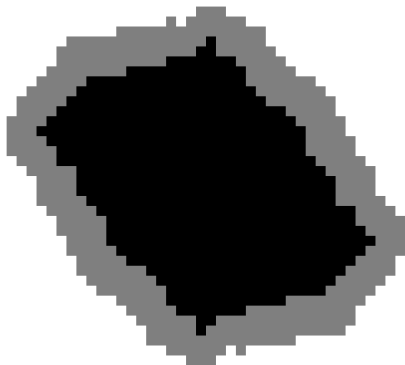
Adaptive approximation

$c = 0.12 + 0.30 i$ level 5



Adaptive approximation

$c = 0.12 + 0.30 i$ level 6



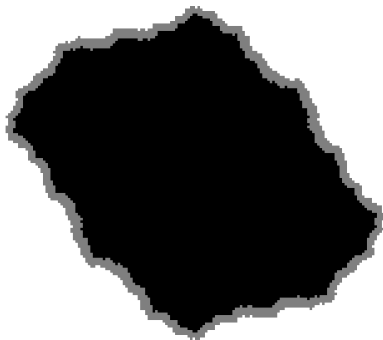
Adaptive approximation

$c = 0.12 + 0.30i$ level 7



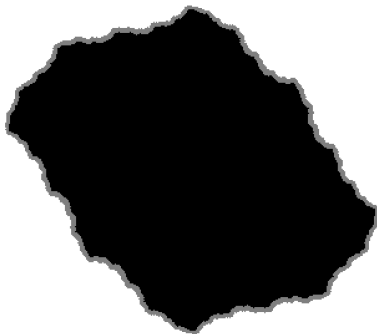
Adaptive approximation

$c = 0.12 + 0.30 i$ level 8



Adaptive approximation

$c = 0.12 + 0.30 i$ level 9



Adaptive approximation

$c = 0.12 + 0.30 i$ level 10



Adaptive approximation

$c = 0.12 + 0.30 i$ level 11



Adaptive approximation

$c = 0.12 + 0.30 i$ level 12



Adaptive approximation

$c = 0.12 + 0.30 i$ level 13



Adaptive approximation

$c = 0.12 + 0.30 i$ level 14



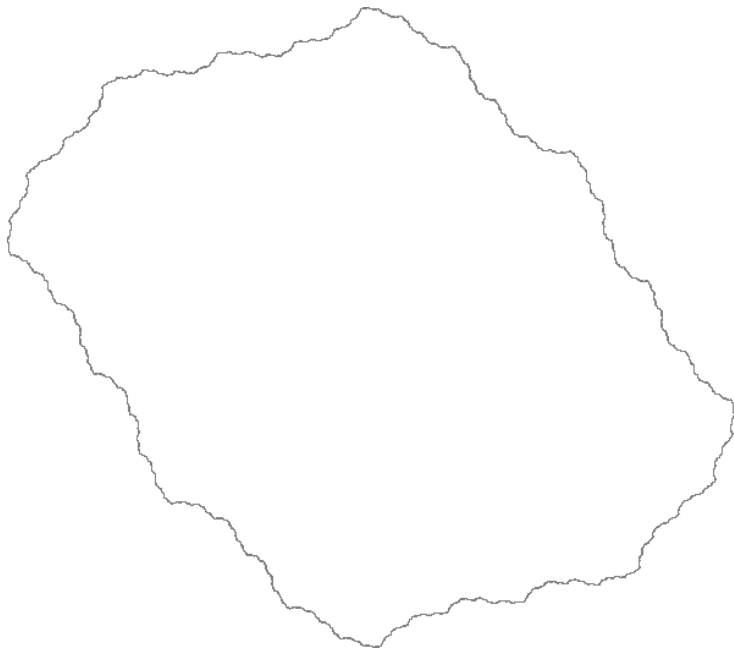
Adaptive approximation

$$c = 0.12 + 0.30i$$



Adaptive approximation

$$c = 0.12 + 0.30i$$



Adaptive approximation

$$c = -0.12 + 0.60i \quad \text{level 0}$$



Adaptive approximation

$c = -0.12 + 0.60i$ level 1



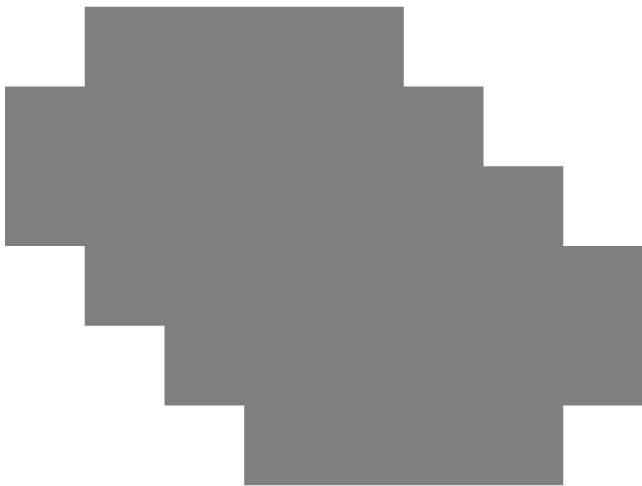
Adaptive approximation

$c = -0.12 + 0.60i$ level 2



Adaptive approximation

$c = -0.12 + 0.60i$ level 3



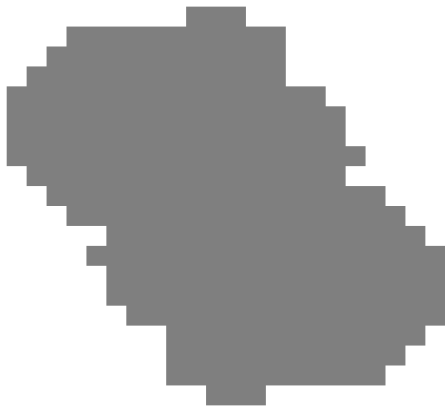
Adaptive approximation

$c = -0.12 + 0.60 i$ level 4



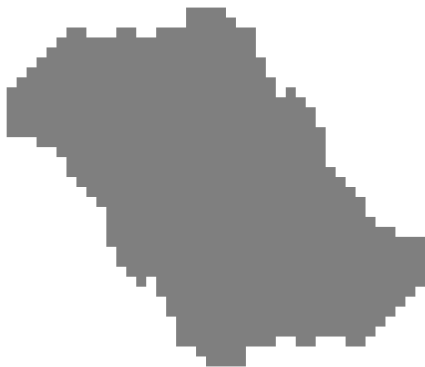
Adaptive approximation

$c = -0.12 + 0.60i$ level 5



Adaptive approximation

$c = -0.12 + 0.60 i$ level 6



Adaptive approximation

$c = -0.12 + 0.60i$ level 7



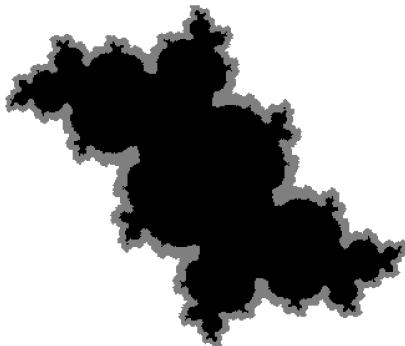
Adaptive approximation

$c = -0.12 + 0.60i$ level 8



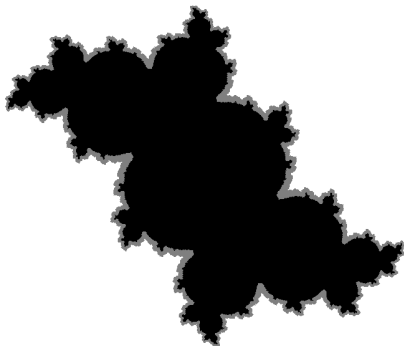
Adaptive approximation

$c = -0.12 + 0.60i$ level 9



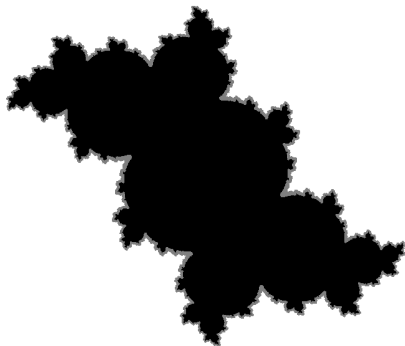
Adaptive approximation

$c = -0.12 + 0.60i$ level 10



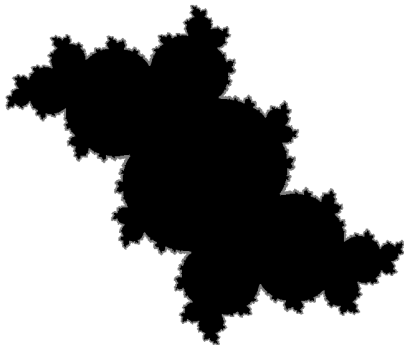
Adaptive approximation

$c = -0.12 + 0.60i$ level 11



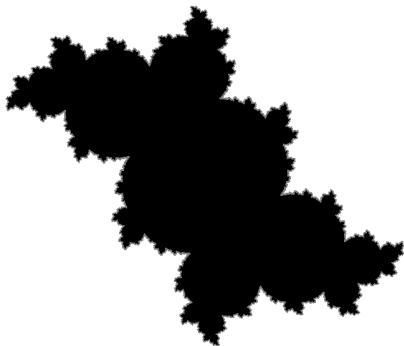
Adaptive approximation

$c = -0.12 + 0.60i$ level 12



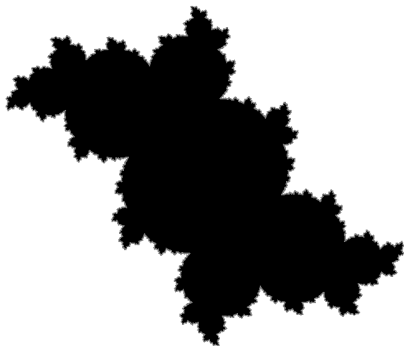
Adaptive approximation

$c = -0.12 + 0.60i$ level 13



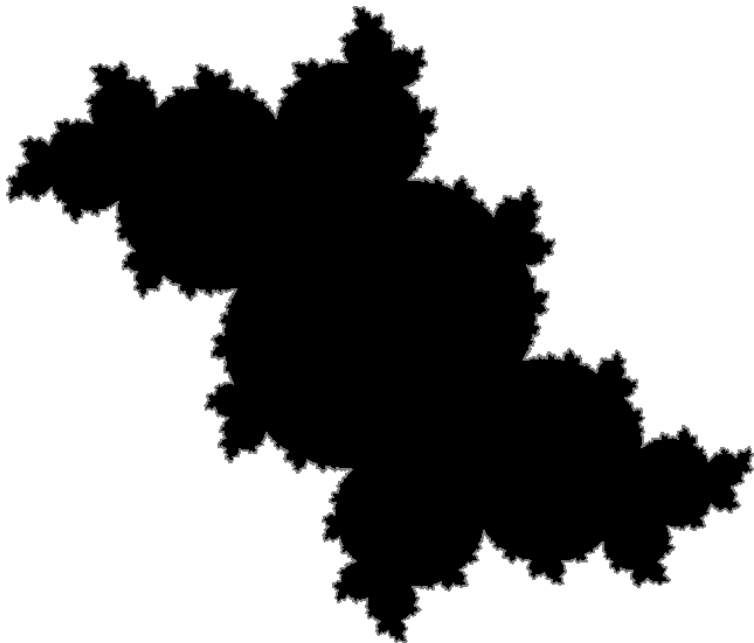
Adaptive approximation

$c = -0.12 + 0.60i$ level 14



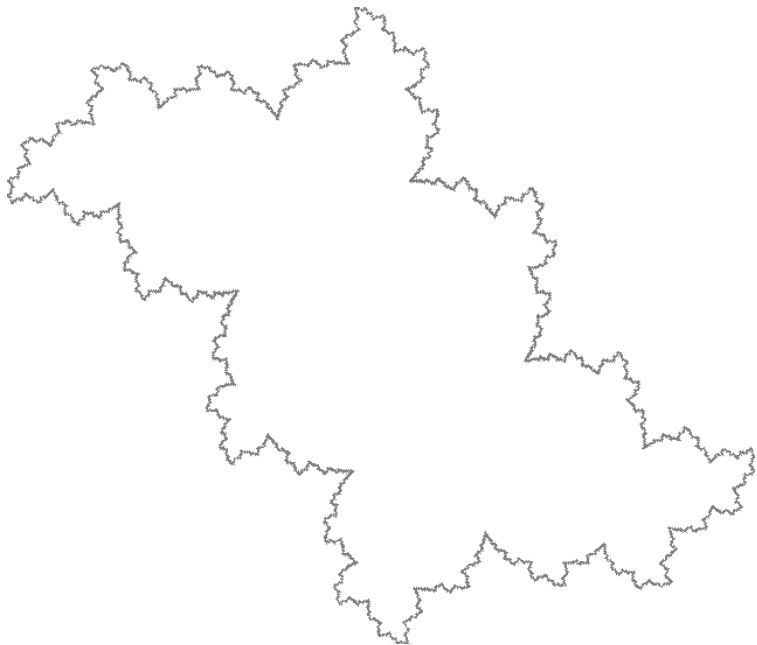
Adaptive approximation

$$c = -0.12 + 0.60i$$



Adaptive approximation

$$c = -0.12 + 0.60i$$



Adaptive approximation

$$c = -0.12 + 0.74 i \quad \text{level 0}$$



Adaptive approximation

$$c = -0.12 + 0.74 i \quad \text{level 1}$$



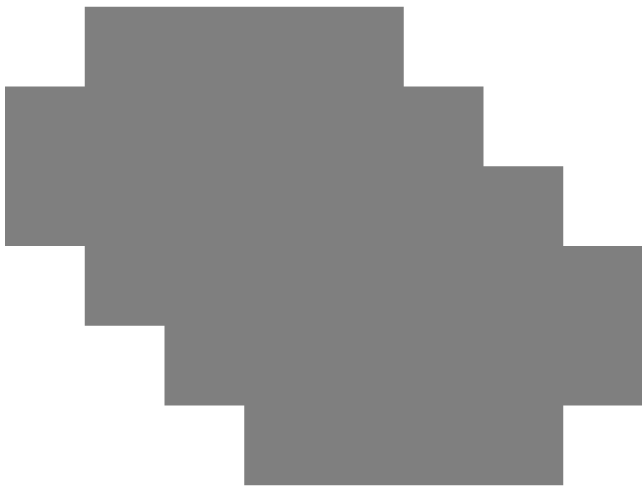
Adaptive approximation

$c = -0.12 + 0.74 i$ level 2



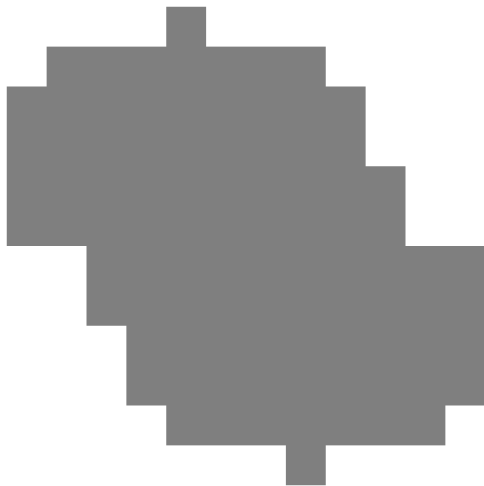
Adaptive approximation

$c = -0.12 + 0.74 i$ level 3



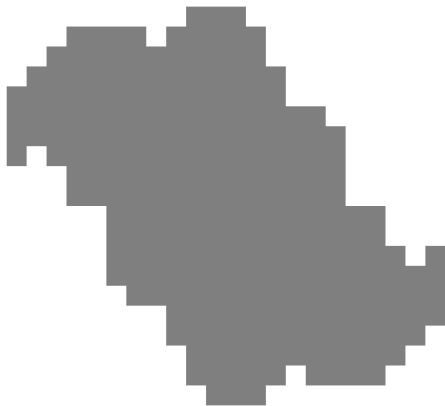
Adaptive approximation

$c = -0.12 + 0.74 i$ level 4



Adaptive approximation

$c = -0.12 + 0.74 i$ level 5



Adaptive approximation

$c = -0.12 + 0.74 i$ level 6



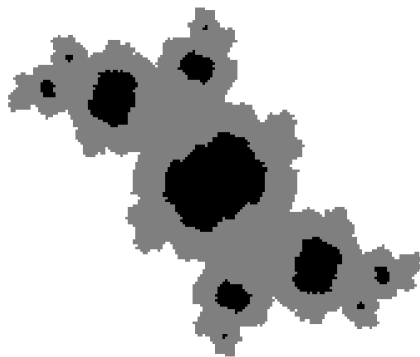
Adaptive approximation

$c = -0.12 + 0.74 i$ level 7



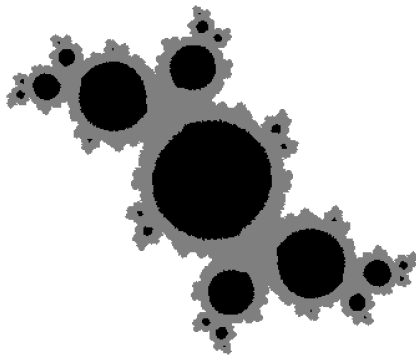
Adaptive approximation

$c = -0.12 + 0.74 i$ level 8



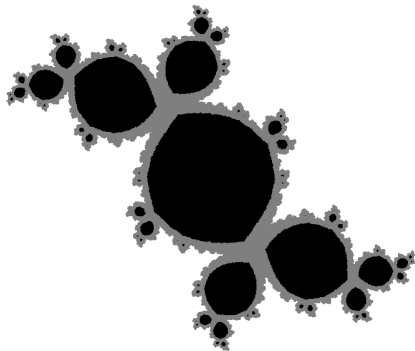
Adaptive approximation

$c = -0.12 + 0.74 i$ level 9



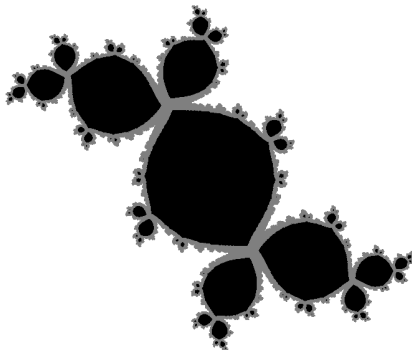
Adaptive approximation

$c = -0.12 + 0.74 i$ level 10



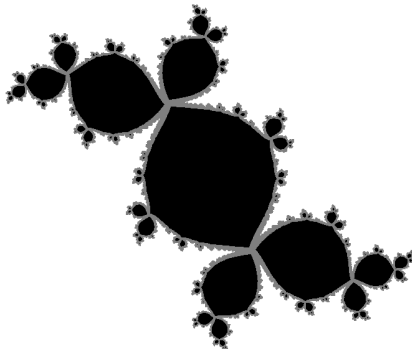
Adaptive approximation

$c = -0.12 + 0.74 i$ level 11



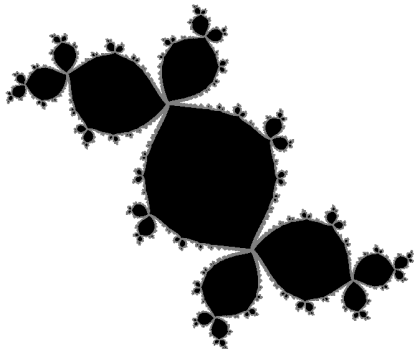
Adaptive approximation

$c = -0.12 + 0.74 i$ level 12



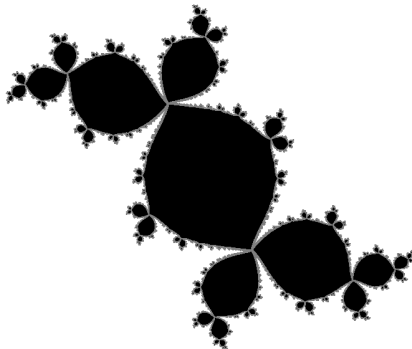
Adaptive approximation

$c = -0.12 + 0.74 i$ level 13



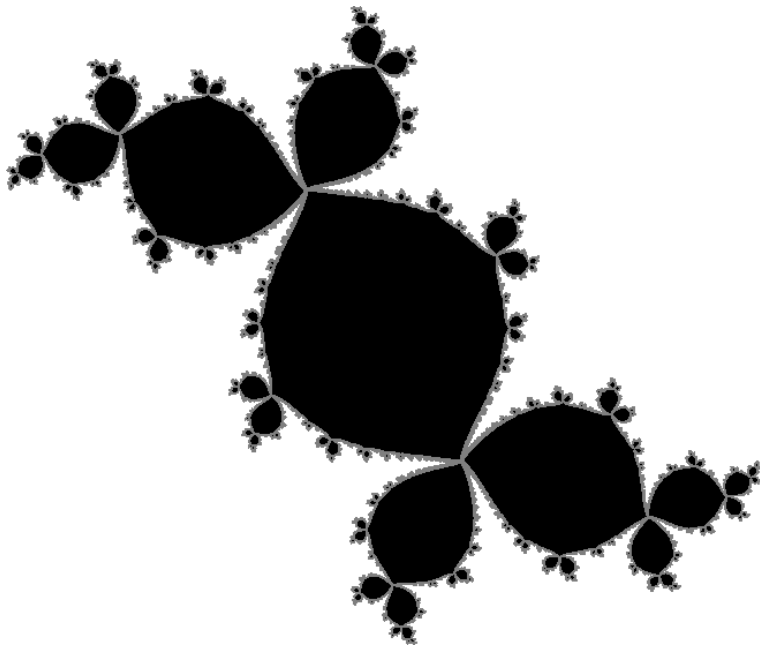
Adaptive approximation

$c = -0.12 + 0.74 i$ level 14



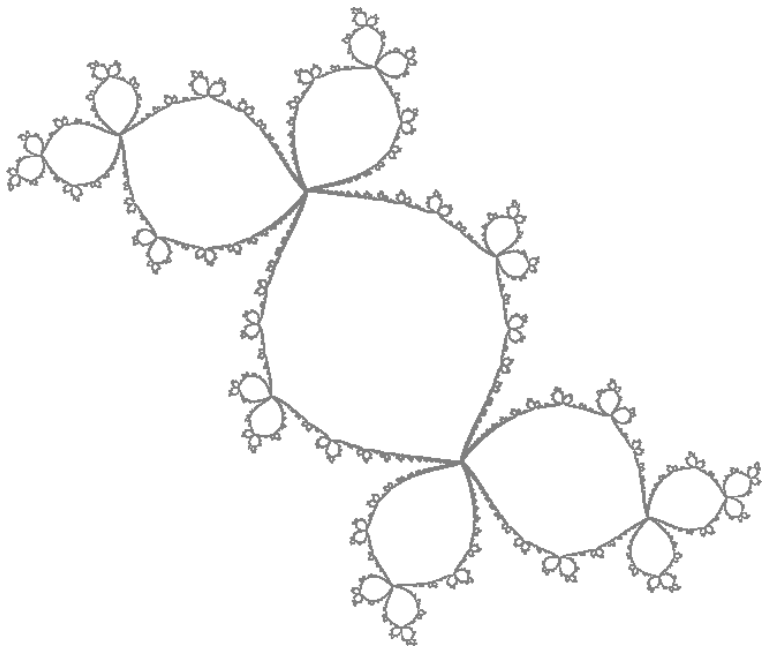
Adaptive approximation

$$c = -0.12 + 0.74 i$$



Adaptive approximation

$$c = -0.12 + 0.74 i$$



Adaptive approximation

$c = i$ level 0



Adaptive approximation

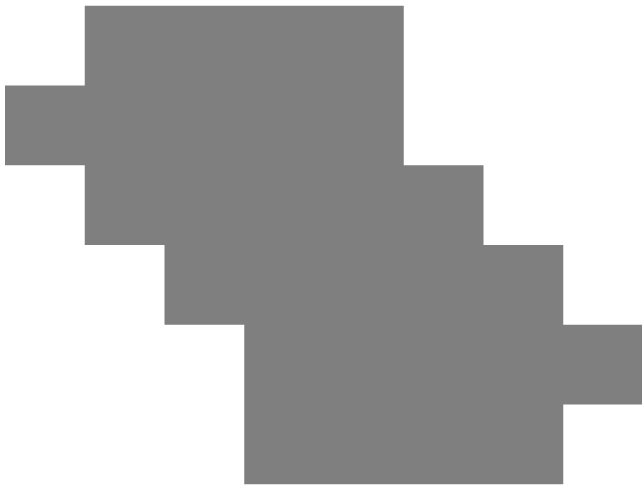
$c = i$ level 1



Adaptive approximation

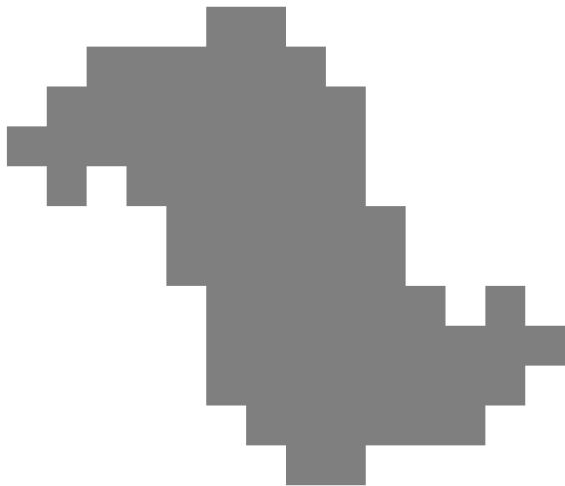
$c = i$ level 2





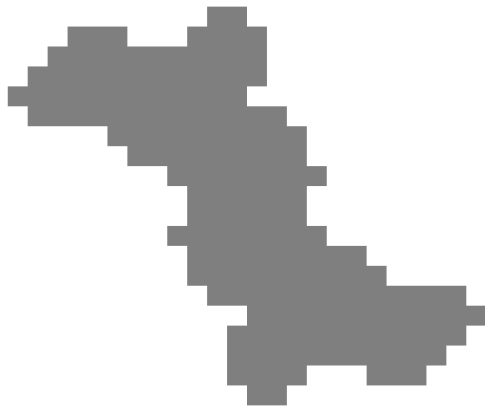
Adaptive approximation

$c = i$ level 4



Adaptive approximation

$c = i$ level 5



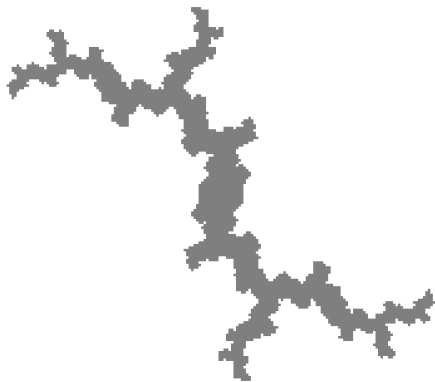
Adaptive approximation

$c = i$ level 6



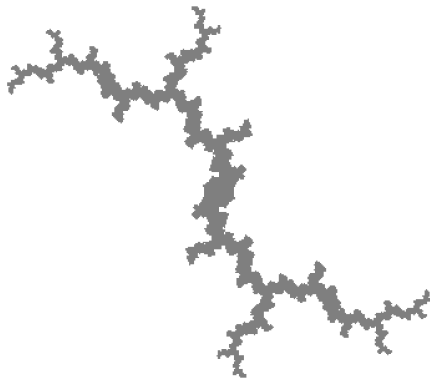
Adaptive approximation

$c = i$ level 8



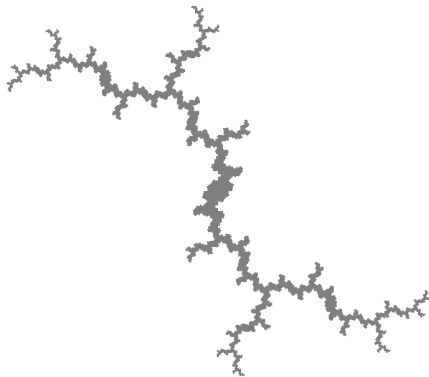
Adaptive approximation

$c = i$ level 9



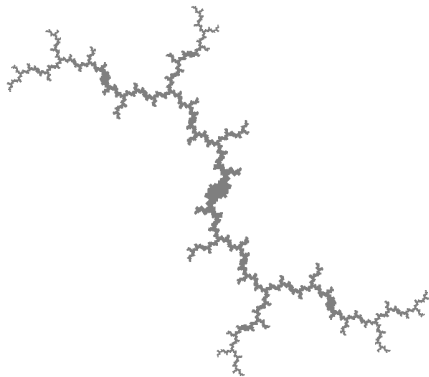
Adaptive approximation

$c = i$ level 10



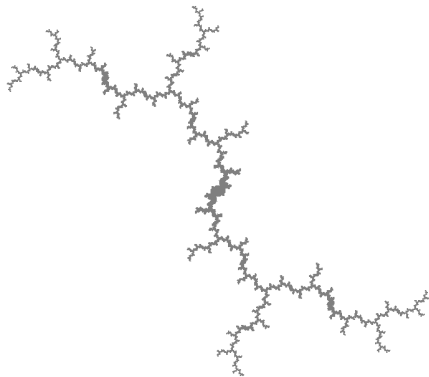
Adaptive approximation

$c = i$ level 11



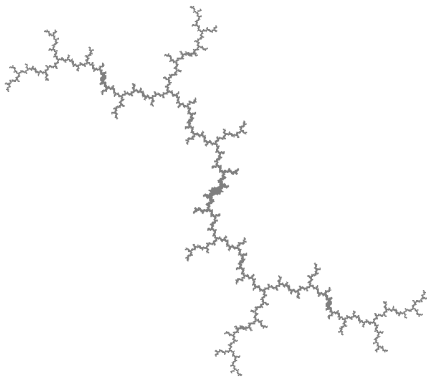
Adaptive approximation

$c = i$ level 12



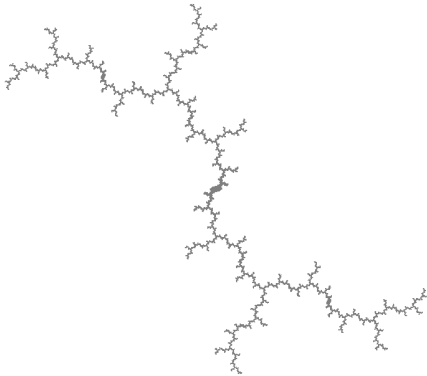
Adaptive approximation

$c = i$ level 13



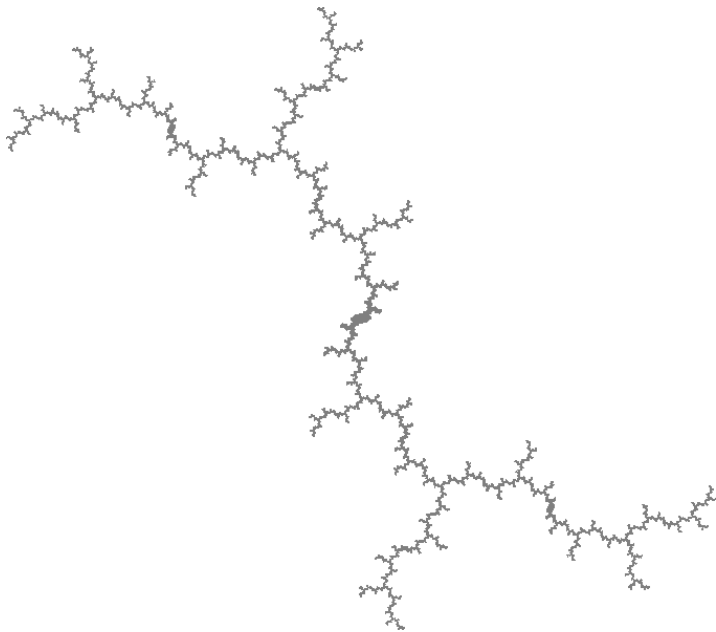
Adaptive approximation

$c = i$ level 14



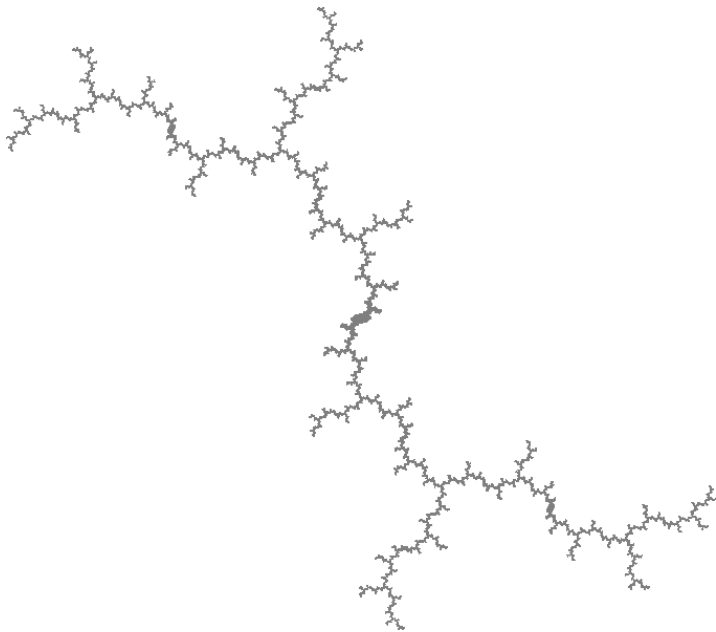
Adaptive approximation

$$c = i$$



Adaptive approximation

$$c = i$$



Adaptive approximation

$$c = -0.25 + 0.74 i \quad \text{level 0}$$



Adaptive approximation

$c = -0.25 + 0.74 i$ level 1



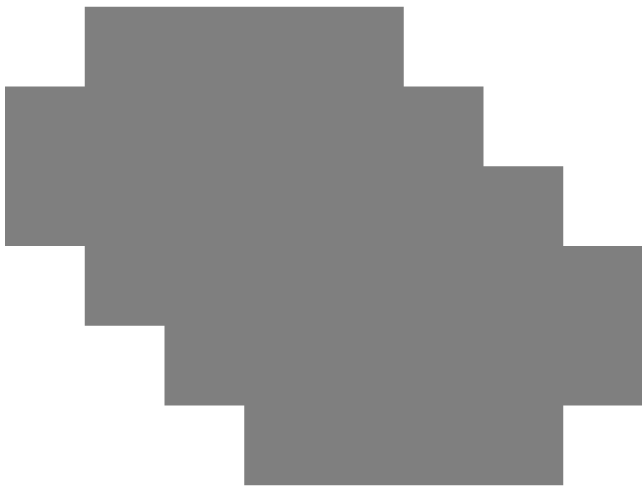
Adaptive approximation

$c = -0.25 + 0.74 i$ level 2



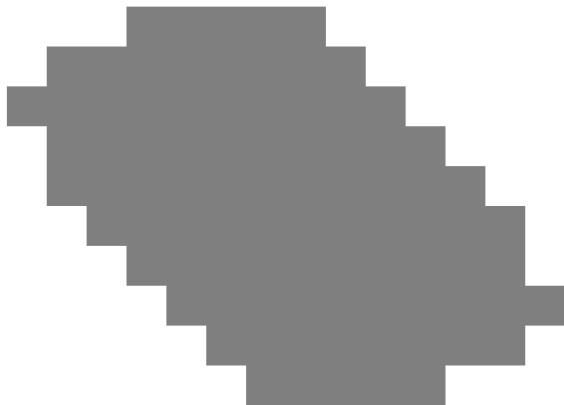
Adaptive approximation

$c = -0.25 + 0.74 i$ level 3



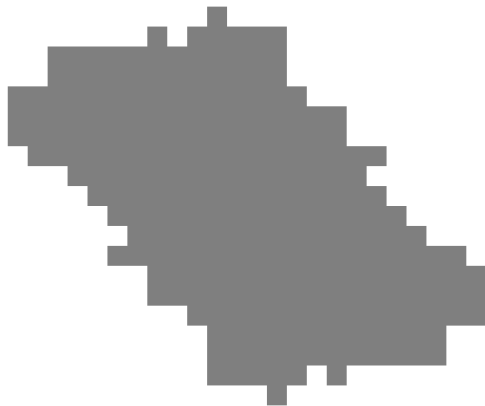
Adaptive approximation

$c = -0.25 + 0.74 i$ level 4



Adaptive approximation

$c = -0.25 + 0.74 i$ level 5



Adaptive approximation

$c = -0.25 + 0.74 i$ level 6



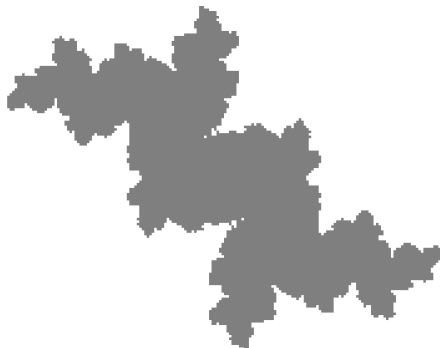
Adaptive approximation

$c = -0.25 + 0.74 i$ level 7



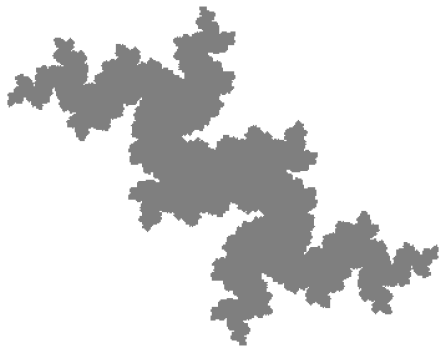
Adaptive approximation

$c = -0.25 + 0.74 i$ level 8



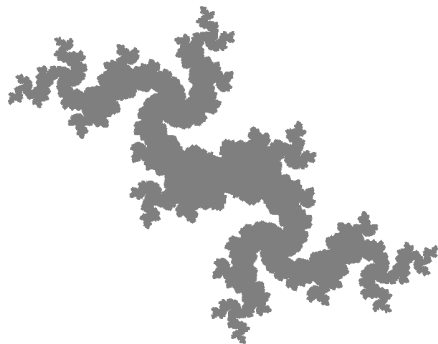
Adaptive approximation

$c = -0.25 + 0.74 i$ level 9



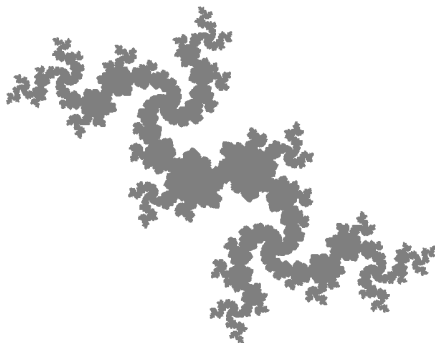
Adaptive approximation

$c = -0.25 + 0.74 i$ level 10



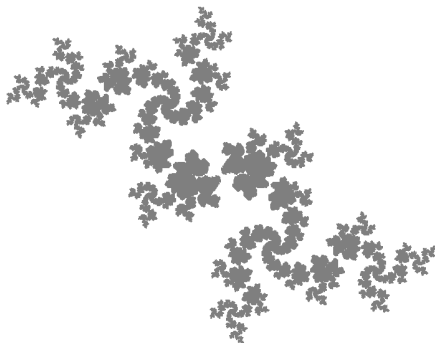
Adaptive approximation

$c = -0.25 + 0.74 i$ level 11



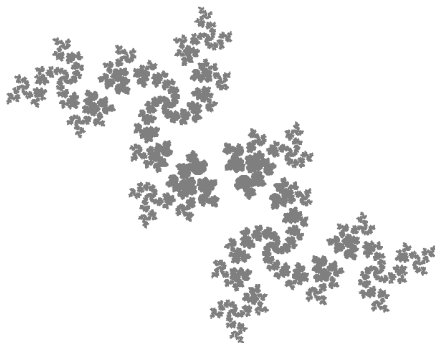
Adaptive approximation

$c = -0.25 + 0.74 i$ level 12



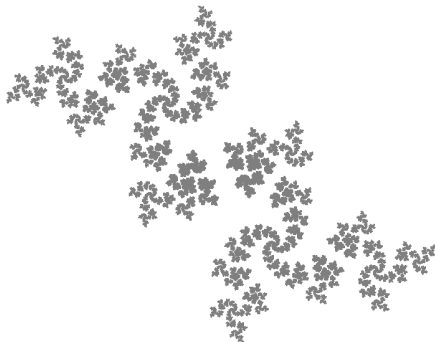
Adaptive approximation

$c = -0.25 + 0.74 i$ level 13



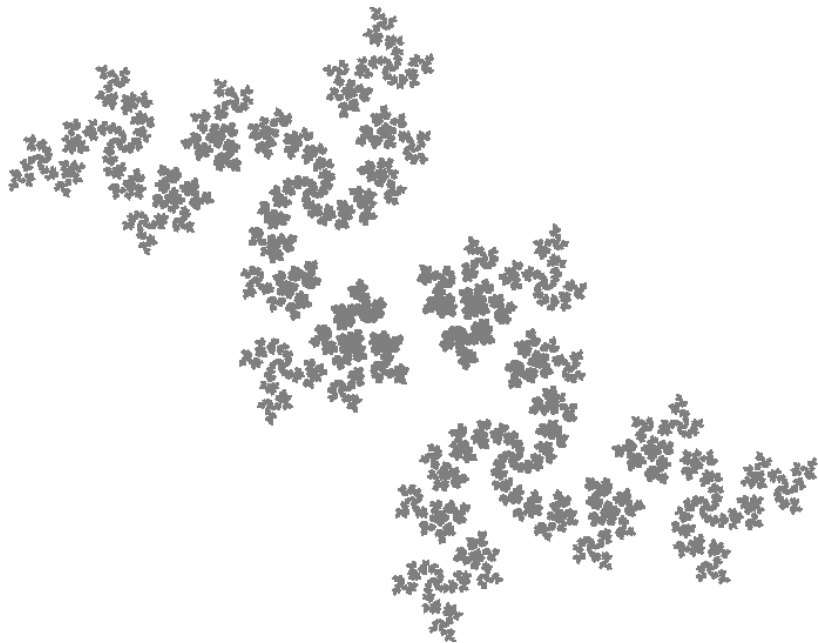
Adaptive approximation

$c = -0.25 + 0.74 i$ level 14



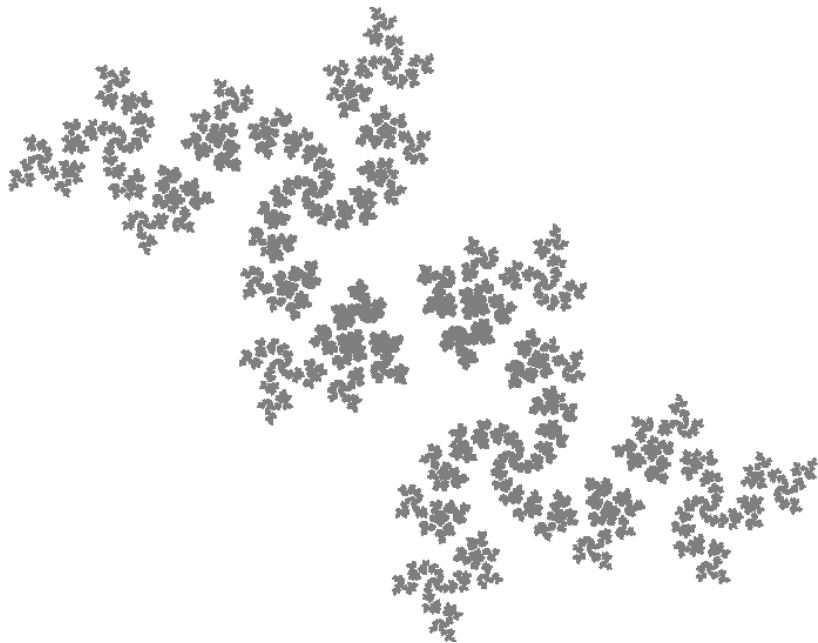
Adaptive approximation

$$c = -0.25 + 0.74 i$$



Adaptive approximation

$$c = -0.25 + 0.74 i$$



Applications

- ▶ Image generation
- ▶ Point and box classification
- ▶ Fractal dimension of Julia set
- ▶ Area of filled Julia set
- ▶ Diameter of Julia set

- ▶ Image generation
large images
smaller images with anti-aliasing
- ▶ Point and box classification
quadtree traversal + one function evaluation if gray
- ▶ Fractal dimension of Julia set
upper bound
- ▶ Area of filled Julia set
lower and upper bounds
- ▶ Diameter of Julia set
lower and upper bounds

$$\dim_H = 1 + \frac{|c|^2}{4 \log 2} + \dots \quad (\text{Ruelle})$$

$$\pi(1 - |p_1(c)|^2 - 3|p_2(c)|^2 - 5|p_1(c)|^2 - \dots) \quad (\text{Milnor})$$

Area of filled Julia set after Milnor

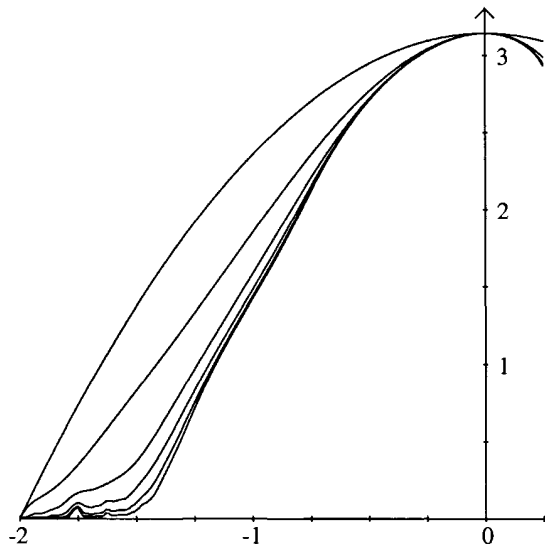
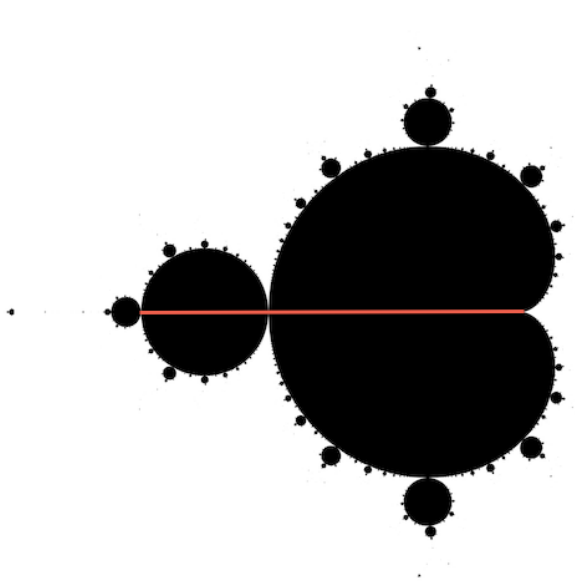


Figure 45. Upper bounds for the area of the filled Julia set for $f_c(z) = z^2 + c$ in the range $-2 \leq c \leq .25$.

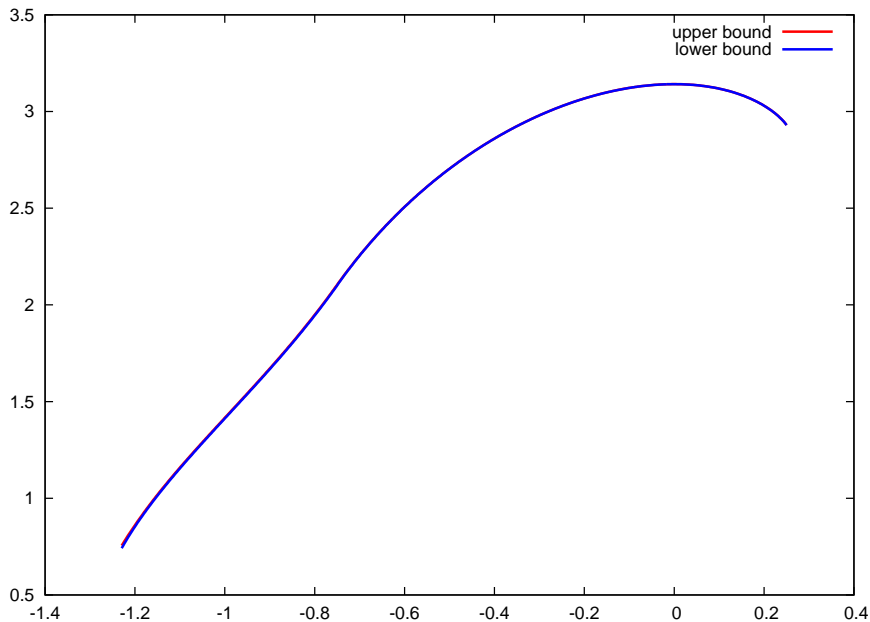
Area of filled Julia set $-1.25 \leq c \leq 0.25$



Area of filled Julia set

$-1.25 \leq c \leq 0.25$

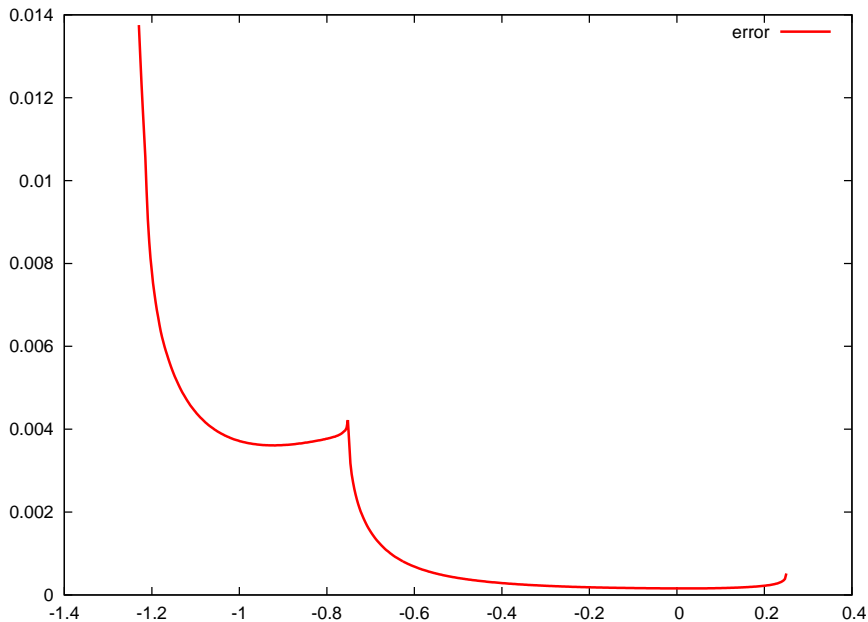
level 19



Area of filled Julia set

$-1.25 \leq c \leq 0.25$

level 19



Limitations

- ▶ Memory
- ▶ Need to explore $\Omega \supseteq [-R, R] \times [-R, R]$
- ▶ No proof of convergence

Limitations

- ▶ Memory

- depth of quadtree and size of cell graph limited by available memory
 - currently spatial resolution $\approx 4 \times 10^{-6}$
 - cannot reach 20 levels

- ▶ Need to explore $\Omega \supseteq [-R, R] \times [-R, R]$

- even if region of interest is smaller

- limited amount of zoom

- limitation inherent to using cell mapping because f is transitive on J

- ▶ No proof of convergence

- do approximations for J always decrease with the resolution?

- ▶ Julia sets for other polynomials

$$R = \frac{1 + |a_d| + \cdots + |a_0|}{|a_d|}$$

is an escape radius for $f(z) = a_d z^d + \cdots + a_0$

(Douady)

- ▶ Julia sets for Newton's method

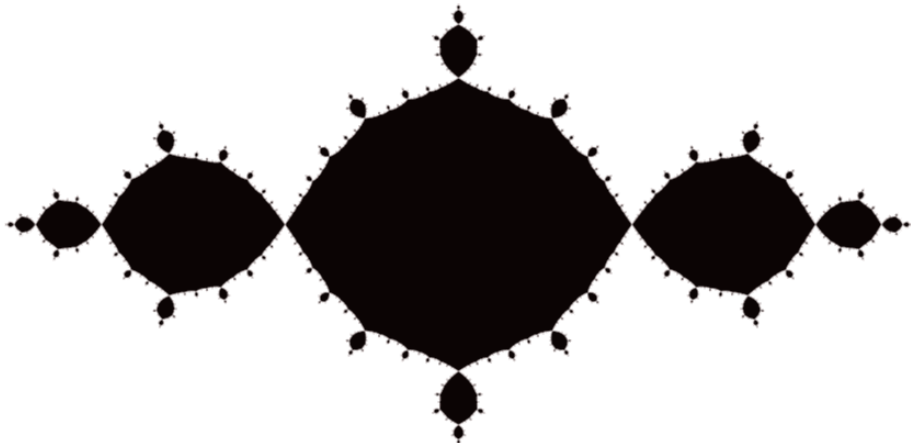
no escape radius

need to find explicit attracting regions around zeros

Julia set panorama

<http://monge.visgraf.impa.br/panorama/julia-256GP/julia.htm>

Images of Julia sets that you can trust



Thanks!



Related work

- ▶ M. Braverman and M. Yampolsky. *Computability of Julia sets*, volume 23 of *Algorithms and Computation in Mathematics*. Springer-Verlag, 2009.
- ▶ M. Dellnitz and A. Hohmann. A subdivision algorithm for the computation of unstable manifolds and global attractors. *Numerische Mathematik*, 75(3):293–317, 1997.
- ▶ C. S. Hsu. *Cell-to-cell mapping: A method of global analysis for nonlinear systems*. Springer-Verlag, 1987.
- ▶ J. Milnor. *Dynamics in one complex variable*, volume 160 of *Annals of Mathematics Studies*. Princeton University Press, third edition, 2006.
- ▶ R. E. Moore. *Interval Analysis*. Prentice-Hall, 1966.
- ▶ R. Rettinger and K. Weihrauch. The computational complexity of some Julia sets. In *Proceedings of the 35th Annual ACM Symposium on Theory of Computing*, pages 177–185. ACM, 2003.
- ▶ D. Saupe. Efficient computation of Julia sets and their fractal dimension. *Phys. D*, 28(3):358–370, 1987.

Area of filled Julia set

$-1.25 \leq c \leq 0.25$

level 19

