

-1-

MATH 110 - Homework #5 - Solutions

Section 6.1:

② $V = \mathbb{C}^3$ with standard inner product

$$x = (2, 1+i, i), y = (2-i, 2, 1+2i)$$

$$\begin{aligned}\langle x, y \rangle &= 2 \cdot (2+i) + (1+i) \cdot 2 + i(1-2i) \\ &= 8 + 5i\end{aligned}$$

$$\|x\| = \sqrt{\langle x, x \rangle} = \sqrt{7}$$

$$\|y\| = \sqrt{\langle y, y \rangle} = \sqrt{14}$$

$$\|x+y\| = \sqrt{\langle x+y, x+y \rangle} = \sqrt{37}$$

$$\text{So } |\langle x, y \rangle| = \sqrt{89} \leq \|x\| \|y\| = \sqrt{98}$$

and

$$\|x+y\| = \sqrt{37} \leq \|x\| + \|y\| = \sqrt{7} + \sqrt{14}$$

⑧

a) $\langle (a,b), (c,d) \rangle = ac - bd$ is not an inner product

since $\langle (1,1), (1,1) \rangle = 0$ and $(1,1) \neq 0$. (Property (4) is violated)

b)

$$\langle A, B \rangle = \text{tr}(A+B) \quad A, B \in M_{2 \times 2}(\mathbb{R})$$

If $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$, then $\langle A, A \rangle = 0$ and $A \neq 0$

⑨ Let V be a finite dimensional vector space and $\beta = \{x_1, \dots, x_n\}$ be a basis for V .

$$\text{Suppose } \langle x_i, y \rangle = 0 \quad i=1 \dots n$$

Because β is a basis, we can write $y = a_1 x_1 + \dots + a_n x_n$, $a_i \in F$.

then

$$\begin{aligned} \langle y, y \rangle &= \langle a_1 x_1 + \dots + a_n x_n, y \rangle \\ &= a_1 \underbrace{\langle x_1, y \rangle}_{0} + \dots + a_n \underbrace{\langle x_n, y \rangle}_{0} = 0 \end{aligned}$$

$$\text{So } y = 0$$

■

⑩

Let $T: V \rightarrow V$ be linear operator, $\sqrt{ }$ inner product space.

Suppose $\|T(x)\| = \|x\|$.

In order to show that T is one-to-one, it suffices to show

that $N(T) = \{0\}$ (i.e., $Tx = 0 \Rightarrow x = 0$)

But if $Tx = 0$, then $\|Tx\| = 0 = \|x\|$,

But $\|x\| = \sqrt{\langle x, x \rangle} = 0 \Rightarrow \langle x, x \rangle = 0 \Rightarrow x = 0$

■

Section 6.2

(2) (a)

$$V = \mathbb{R}^3, S = \left\{ \underbrace{(1,0,1)}_{v_1}, \underbrace{(0,1,1)}_{v_2}, \underbrace{(1,3,3)}_{v_3} \right\}$$

$$\text{Gram-Schmidt: } v_1 = \omega_1$$

$$v_2 = \omega_2 - \frac{\langle \omega_2, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1 = (0,1,1) - \frac{1}{2} (1,0,1) = \left(-\frac{1}{2}, 1, \frac{1}{2} \right)$$

$$v_3 = \omega_3 - \frac{\langle \omega_3, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1 - \frac{\langle \omega_3, v_2 \rangle}{\langle v_2, v_2 \rangle} v_2$$

$$= (1,3,3) - \frac{4}{2} (1,0,1) - \frac{4}{3/2} \left(-\frac{1}{2}, 1, \frac{1}{2} \right)$$

$$= \left(\frac{1}{3}, \frac{1}{3}, -\frac{1}{3} \right)$$

Normalizing, we get orthonormal basis : $\left\{ \frac{1}{\sqrt{2}} (1,0,1), \sqrt{\frac{2}{3}} \left(-\frac{1}{2}, 1, \frac{1}{2} \right), \sqrt{3} \left(\frac{1}{3}, \frac{1}{3}, -\frac{1}{3} \right) \right\}$

Fourier coefficients of $x = (1,1,2)$: $a_1 = \frac{3}{\sqrt{2}}$, $a_2 = \frac{3}{2} \sqrt{\frac{2}{3}}$, $a_3 = 0$

(c) $V = P_2(\mathbb{R})$, $S = \left\{ 1, x, x^2 \right\}$ $\langle f, g \rangle = \int_0^1 f(t)g(t) dt$

$$v_1 = 1$$

$$v_2 = x - \frac{1}{2}$$

$$v_3 = x^2 - \frac{\langle x^2, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1 - \frac{\langle x^2, v_2 \rangle}{\langle v_2, v_2 \rangle} v_2 = x^2 - \frac{1}{3} - \frac{\left(\frac{1}{4} - \frac{1}{6} \right)}{\left(\frac{1}{3} - \frac{1}{4} \right)} \left(x - \frac{1}{2} \right)$$

$$= x^2 - x + \frac{1}{6}$$

orthonormal basis:

$$\left\{ 1, \sqrt{12} \left(x - \frac{1}{2} \right), \sqrt{\frac{360}{211}} \left(x^2 - x + \frac{1}{6} \right) \right\}$$

(4) $S = \left\{ \underbrace{(1,0,i)}_{v_1}, \underbrace{(1,2,1)}_{v_2} \right\} \subseteq \mathbb{C}^3$. $\langle x, y \rangle = x_1 \bar{y}_1 + x_2 \bar{y}_2 + x_3 \bar{y}_3$

$$S^\perp = \left\{ v \in \mathbb{C}^3 / \langle v, v_1 \rangle = 0, \langle v, v_2 \rangle = 0 \right\}$$

for $v = (a, b, c)$, we have $v \in S^\perp \Leftrightarrow a \cdot 1 + b \cdot 0 + c(-i) = 0$

$$a + 2b + c = 0$$

Solving the system we find:

$$a = ic, \quad b = -\left(\frac{i+1}{2}\right)c$$

$$\therefore S^\perp = \left\{ (a, b, c) \in \mathbb{C}^3 / a = ic, b = -\left(\frac{i+1}{2}\right)c \right\}$$

$$= \left\{ c \left(i, -\left(\frac{i+1}{2}\right), 1 \right), c \in \mathbb{C} \right\}$$

■

⑦ Suppose $\{w_1 \dots w_n\}$ is orthogonal, $w_i \neq 0$.

Let $\{v_1 \dots v_n\}$ be the vectors obtained by Gram-Schmidt.

We will show that $v_i = w_i$ by induction.

Proceeding by G-S, we set $v_1 = w_1$.

Now suppose $v_1 = w_1, \dots, v_{k-1} = w_{k-1}$

we must show that $v_k = w_k$.

By G-S,

$$v_k = w_k - \sum_{j=1}^{k-1} \frac{\langle w_k, v_j \rangle}{\langle v_j, v_j \rangle} v_j \quad \text{But since } v_1 = w_1, \dots, v_{k-1} = w_{k-1}$$

and $\{w_1 \dots w_{k-1}\}$ is orthogonal, $\langle w_k, v_j \rangle = 0 \quad \forall j = 1 \dots k-1$.

$$\text{So } v_k = w_k \quad \blacksquare$$

⑧ $V = C[-1,1]$, $\langle f, g \rangle = \int_{-1}^1 f(t)g(t) dt$

Let $W = P_2(\mathbb{R}) \subseteq C[-1,1]$ subspace, $\beta = \{1, x, x^2\}$.

a) Applying G-S to β , we get : $v_1 = 1$

$$v_2 = x - \int_1^1 t dt = x$$

$$\begin{aligned} v_3 &= x^2 - \frac{1}{2} \int_{-1}^1 t^2 dt - \left(\int_{-1}^1 t^3 dt \right) x \\ &= x^2 - \frac{1}{3} \quad \left(\cancel{\int_{-1}^1 t^3 dt} \right) \end{aligned}$$

$$\therefore \left\{ 1, x, x^2 - \frac{1}{3} \right\}$$

(b) Just normalize the vectors

$$\mathcal{B} = \left\{ \sqrt{\frac{1}{2}}, \sqrt{\frac{3}{2}}x, \sqrt{\frac{45}{8}}\left(x^2 - \frac{1}{3}\right) \right\}$$

(c) The closest second-degree polynomial to $h(t) = e^t$ is the orthogonal projection of $h(t)$ on $W = P_2(\mathbb{R})$.

The orthogonal projection of $h(t)$ on W is given by

$$\begin{aligned} u &= \langle h(t), \frac{1}{\sqrt{2}} \rangle \frac{1}{\sqrt{2}} + \langle h(t), \sqrt{\frac{3}{2}}x \rangle \sqrt{\frac{3}{2}}x \\ &\quad + \langle h(t), \sqrt{\frac{45}{8}}\left(x^2 - \frac{1}{3}\right) \rangle \sqrt{\frac{45}{8}}\left(x^2 - \frac{1}{3}\right) = \\ &= \frac{1}{2}\langle h(t), 1 \rangle + \frac{3}{2}\langle h(t), x \rangle x + \frac{45}{8}\langle h(t), x^2 - \frac{1}{3} \rangle \left(x^2 - \frac{1}{3}\right) \end{aligned}$$

from now on it's just calculus...

Section 6.3

(3)

$$\textcircled{a} \quad V = \mathbb{R}^2, \quad T(a,b) = (2a+b, a-3b), \quad x = (3,5)$$

Recall: $\langle Tu, x \rangle = \langle u, T^*x \rangle$,
 $T^*x = \overline{g(e_1)}e_1 + \overline{g(e_2)}e_2$, where $g(u) = \langle Tu, x \rangle$

$$\therefore g(e_1) = \langle Te_1, x \rangle = \langle (2,1), (3,5) \rangle = 11$$

$$g(e_2) = \langle Te_2, x \rangle = \langle (1,-3), (3,5) \rangle = -12$$

$$\therefore T^*x = \underline{(11, -12)}$$

$$\textcircled{b} \quad V = \mathbb{C}^2, \quad T(z_1, z_2) = (2z_1 + iz_2, (1-i)z_1), \quad x = (3-i, 1+2i)$$

$$g(u) = \langle Tu, x \rangle$$

$$\begin{aligned} g(e_1) &= \langle (2, (1-i)), (3-i, 1+2i) \rangle = 2(3+i) + (1-i)(1-2i) \\ &= 6 + 2i + 1 - 3i - 2 \\ &= 5 - i \end{aligned}$$

$$g(e_2) = \langle (i, 0), (3-i, 1+2i) \rangle$$

$$= i(3+i) = -1 + 3i$$

$$T^*x = \overline{g(e_1)}e_1 + \overline{g(e_2)}e_2 = (5+i, -1-3i) \quad //$$

(8)

$T: V \rightarrow V$ linear operator, V f. dimensional.

T is invertible, hence $N(T) = \{0\}$ ($\Leftrightarrow Tu = 0 \Rightarrow u = 0$)

To show that T^* is invertible, it suffices to show that $R(T^*) = V$ (T^* onto)

But $R(T^*) = V$ iff $R(T^*)^\perp = \{0\}$.

therefore, to show that T^* is invertible it suffices to show that $R(T^*)^\perp = \{0\}$.

Let then $v \in R(T^*)^\perp$. This means that

$$\langle v, T^*u \rangle = 0 \quad \forall u \in V.$$

$$\text{But } \langle v, T^*u \rangle = \langle Tu, u \rangle, \text{ so}$$

$$\langle Tu, u \rangle = 0 \quad \forall u \in V$$

$$\Rightarrow Tu = 0 \Rightarrow u = 0 \quad \text{since } N(T) = \{0\}.$$

so $R(T^*)^\perp = \{0\}$ and T^* is invertible.

To see that $(T^*)^{-1} = (\bar{T}^{-1})^*$, note that, for all $u, v \in V$,

$$\begin{aligned} \langle (\bar{T}^{-1})^* T^* u, v \rangle &= \langle T^* u, \bar{T}^{-1} v \rangle \\ &= \langle u, T \bar{T}^{-1} v \rangle = \langle u, v \rangle. \end{aligned}$$

Since this holds for all $v \in V$, we must have

$$(\bar{T}^{-1})^* T^* u = u \quad \forall u \in V \Rightarrow (\bar{T}^{-1})^* T^* = \text{Id}, \text{ or}$$

$$(\bar{T}^{-1})^* = (T^*)^{-1}$$

⑯

✓ inner product space. Let $y, z \in V$.

Define $T: V \rightarrow V$ by $T(x) = \langle x, y \rangle z \quad \forall x \in V$.

Clearly $T(x_1 + cx_2) = \langle x_1 + cx_2, y \rangle z = \langle x_1, y \rangle z + c \langle x_2, y \rangle z$
 $= T(x_1) + cT(x_2)$, so T is linear.
 T^* must satisfy $\langle Tx, v \rangle = \langle x, T^*v \rangle$.

$$\begin{aligned} \text{But } \langle Tx, v \rangle &= \langle \langle x, y \rangle z, v \rangle = \langle x, y \rangle \langle z, v \rangle \\ &= \langle x, \overline{\langle z, v \rangle} y \rangle = \langle x, \langle v, z \rangle y \rangle. \end{aligned}$$

$$\text{so } [T^* = \langle v, z \rangle y] \quad \text{AV}$$