## 2D Computer Graphics

Diego Nehab<br>Summer 2020

IMPA

## Path Representation

## SVG PATH COMMANDS



## OUR REPRESENTATION

Input from SVG commands

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path_data = shape:as_path_data()
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Content visible using iterators

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```
path_data:iterate{
    begin_contour = function(self, x0, y0) end
    end_open_contour = function(self, x0, y0) end
    end_closed_contour = function(self, x0, y0) end
    linear_segment = function(self, x0, y0, x1, y1) end
    quadratic_segment = function(self, x0, y0, x1, y1, x2, y2) end
    rational_quadratic_segment = function(self, x0, y0, x1, y1, w1, x2, y2) end
    cubic_segment = function(self, x0, y0, x1, y1, x2, y2, x3, y3) end
}
```


## EXAMPLE OF FILTER

## Transform a path and forward results on

```
function filter.make_input_path_f_xform(xf, forward)
    local px, py-previous cursor
    local xformer = {}
    function xformer:begin_contour(x0, y0)
        px, py = xf:apply(x0, y0)
        forward:begin_contour(px, py)
    end
    function xformer:end_closed_contour(x0, yo)
        forward:end_closed_contour(px, py)
    end
    function xformer:linear_segment(x0, y0, x1, y1)
        x1, y1 = xf:apply(x1,y1)
        forward:linear_segment(px, py, x1, y1)
        px, py = x1, y1
    end
    function xformer:rational_quadratic_segment(x0, y0, x1, y1, w1, x2, y2)
        x1, y1, w1 = xf:apply(x1, y1, w1)
        x2, y2 = xf:apply(x2,y2)
        forward:rational_quadratic_segment(px, py, x1, y1, w1, x2, y2)
        px, py = x2, y2
    end
    return xformer
end
```


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Provided filter.make_input_path_f_xform transforms path Implement monotonize to break into monotonic segments Implement accelerate to convert and store in your representation Chain transformation, monotonization, and acceleration

```
path_xf = shape:get_xf():transform(cur_xf)
shape:as_path_data(): iterate(
    filter.make_input_path_f_xform(path_xf,
        monotonize(
        accelerate(accel)))
```

FLOAtING-POINT AND ROOT-FINDING

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Except, in binary...

## BINARY FLOATING-POINT

$$
(-1)^{s} \times\left(1 . b_{-1} b_{-2} b_{-3} \cdots b_{-t}\right)_{2} \times 2^{e-z} \quad z=2^{w-1}-1
$$



One sign bit
w exponent bits
$t$ fraction bits

## Representation details

$$
(-1)^{s} \times\left(1 . b_{-1} b_{-2} b_{-3} \cdots b_{-t}\right)_{2} \times 2^{e-z} \quad z=2^{w-1}-1
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Normalized representation for mantissa m

- Ensures unique representation for mantissa

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1_{2} \leq m<10_{2}
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Excess encoding for exponent e

- Allows for positive and negative exponents
- Therefore large and small magnitudes
- Subtract $z=2^{w-1}-1$ from encoded exponent


## Special values

Largest representable exponent is reserved

- $m=0$ represents $\pm \operatorname{lnf}$ (Infinity)
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Other special operations

$$
\begin{array}{rlrl}
x \div \ln f & = \pm 0 & 0 \div 0 & =\mathrm{NaN} \\
\ln f \times \ln f & =\ln f & \operatorname{lnf}-\ln f & =\mathrm{NaN} \\
x \div 0 & = \pm \ln f & \operatorname{lnf} \div \operatorname{lnf} & =\mathrm{NaN} \\
\ln f+\ln f & =\ln f & \operatorname{lnf} \times 0 & =\mathrm{NaN}
\end{array}
$$

## DENORMALIZATION

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(-1)^{s} \times\left(1 . b_{-1} b_{-2} b_{-3} \cdots b_{-t}\right)_{2} \times 2^{e-z} \quad z=2^{w-1}-1
$$

Same number of values for each interval $\left[2^{i}, 2^{i+1}\right]$

| $\longleftrightarrow 0$ | 1 | 2 | 3 | 4 |
| :--- | :--- | :--- | :--- | :--- |

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## SUMMARY OF REPRESENTATION

normalized
$\pm$ not $0 \cdots 0$ or $1 \cdots 1 \quad$ any
de-normalized

not $0 \cdots 0$
zero


NaN

| $\pm 1 \cdots 1$ | not $0 \cdots 0$ |
| :---: | :---: |

## COMMON FLOATING-POINT FORMATS

Single precision Double precision

| Total bits | 32 | 64 |
| :--- | :---: | :---: |
| Exponent bits | 8 | 11 |
| Fraction bits | 23 | 52 |
| Exponent range | $-126 \ldots 127$ | $-1022 . . .1023$ |
| Smallest magnitude | $\approx 10^{-45}$ | $\approx 10^{-324}$ |
| Decimal range | $\approx\left[-10^{38}, 10^{38}\right]$ | $\approx\left[-10^{308}, 10^{308}\right]$ |
| Decimal precision | 7 | 16 |

## Rounding, OVERFLOW, UNDERFLOW



Let's try to represent 0.1 in floating-point

- Fraction is 0.0001100110011001100...
- No exact representation possible

Errors can grow and dominate results
Problem often happens in practice

## SOURCE OF ARITHMETIC ERRORS

Addition may not be exact even when exponents are equal $\cdot 1.1010+1.0101=1.01111 \times 2^{1} \rightarrow 1.1000 \times 2^{1}$

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- Must pre-shift to match exponents
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Multiplication is even worse

- Even with matching exponents, needs double number of bits!


## Other weirdness

Associative property does not hold!

- $(a+b)+c \neq a+(b+c)$
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Equality operator is basically useless

- Returns true only when exactly equal
- Must use special function


## STANDARD MODEL OF ARITHMETIC

The only guarantee is the following

$$
\begin{array}{cl}
f l(x \odot y)=(x \odot y)\left(1+\delta_{1}\right), & \left|\delta_{1}\right| \leq u=2^{-t} \\
f l(x \odot y)=\frac{x \odot y}{1+\delta_{2}}, & \left|\delta_{2}\right| \leq u \\
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Safe Newton-Raphson

- Combines advantages of both methods


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Very simple method for finding roots of polynomial $p(x)=0, x \in[a, b]$

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What about in Bernstein basis?

## References

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