## 2D Computer Graphics

Diego Nehab<br>Summer 2019

IMPA

## Geometry and Transformations

## CARTESIAN COORDINATE SYSTEM

Points defined by pair of coordinates

- Signed distances to perpendicular directed lines
- Point where lines cross is the origin


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- Connection between Euclidean geometry and algebra


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Points defined by pair of coordinates

- Signed distances to perpendicular directed lines
- Point where lines cross is the origin

Basis of analytic geometry

- Connection between Euclidean geometry and algebra
- Describe shapes with equations
- E.g., lines and circles


## Problems

Distance between line and point?

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Distance between line and point?
Find intersection between line and circle?

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Find intersection between two circles?

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Distance between line and point?
Find intersection between line and circle?
Find intersection between two circles?
Prove that the medians of a triangle are concurrent?

## Vector Spaces

Set of $V$ of vectors closed by linear combinations

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- Define sum of vectors $v_{1}, v_{2}$ and multiplication by scalars $\alpha$

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v_{1}, v_{2} \in V \Rightarrow \alpha_{1} v_{1}+\alpha_{2} v_{2} \in V
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- That spans V

$$
v \in V \Leftrightarrow \exists \alpha_{1}, \alpha_{2} \mid V=\alpha_{1} V_{1}+\alpha_{2} V_{2}
$$

## LINEAR TRANSFORMATIONS

Coordinates of a vector in a given basis

$$
[v]_{\mathcal{B}}=\left[\begin{array}{l}
\alpha_{1} \\
\alpha_{2}
\end{array}\right] \Leftrightarrow v=\alpha_{1} v_{1}+\alpha_{2} v_{2}
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Linear transformations preserve linear combinations

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Interesting transformations

- Identity, Rotation, Scale, Reflection, Shearing


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General linear group

- Composition, inverse


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- Composition, inverse
- Preserves collinearity, parallelism, concurrency, tangency, ratios of distances along lines


## NORM AND INNER PRODUCT

Dot product, scalar product, standard inner product

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u^{\top} v=u \cdot v=\langle u, v\rangle=u_{x} v_{x}+u_{y} v_{y}
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\langle u, v\rangle=\frac{1}{4}\left(\|u+v\|^{2}-\|u-v\|^{2}\right)
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Let $u$ and $v$ make angles $\alpha$ and $\beta$ with the $x$-axis

$$
\begin{aligned}
\cos (\beta-\alpha) & =\cos (\alpha) \cos (\beta)+\sin (\alpha) \sin (\beta) \\
& =u_{x} /\|u\| v_{x} /\|v\|+u_{y} /\|u\| v_{y} /\|v\| \\
& =\langle u, v\rangle /(\|u\|\|v\|)
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Orthogonal transformations

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- Rigid transformations (isometries), or
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## Affine spaces

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Let $V$ be a vector space with basis $\mathcal{B}=\left\{v_{1}, v_{2}\right\}$ and $o$ a point
Affine space is $A=0+V=\{p \mid p-0 \in V\}$

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Let $V$ be a vector space with basis $\mathcal{B}=\left\{v_{1}, v_{2}\right\}$ and $o$ a point
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- Affine frame $\mathcal{C}=\left\{\mathrm{v}_{1}, \mathrm{~V}_{2} ; \mathrm{o}\right\}$

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p=0+\alpha_{1} V_{1}+\alpha_{2} V_{2}
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$$
p=o+\alpha_{1} v_{1}+\alpha_{2} v_{2}
$$

- Affine coordinates

$$
[p]_{\mathcal{C}}=\left[\begin{array}{c}
\alpha_{1} \\
\alpha_{2} \\
1
\end{array}\right]
$$

## Affine spaces

Let $V$ be a vector space with basis $\mathcal{B}=\left\{v_{1}, v_{2}\right\}$ and $o$ a point Barycentric frame $\mathcal{D}=\left\{a_{0}, a_{1}, a_{2}\right\}=\left\{0,0+v_{1}, o+v_{2}\right\}$

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$$
\begin{aligned}
p & =0+\alpha_{1} v_{1}+\alpha_{2} v_{2} \\
& =\left(1-\alpha_{1}-\alpha_{2}\right) 0+\alpha_{1}\left(0+v_{1}\right)+\alpha_{2}\left(0+v_{2}\right) \\
& =\left(1-\alpha_{1}-\alpha_{2}\right) a_{0}+\alpha_{1} a_{1}+\alpha_{2} a_{2} \\
& =\alpha_{0} a_{0}+\alpha_{1} a_{1}+\alpha_{2} a_{2}, \quad \text { with } \quad \alpha_{0}+\alpha_{1}+\alpha_{2}=1 .
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&=\alpha_{0} a_{0}+\alpha_{1} a_{1}+\alpha_{2} a_{2}, \quad \text { with } \quad \alpha_{0}+\alpha_{1}+\alpha_{2}=1 . \\
& \text { - Barycentric coordinates }[p]_{\mathcal{D}}=\left[\begin{array}{c}
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\alpha_{2}
\end{array}\right]
\end{aligned}
$$

- Displacement vectors $v \in V$ are such that $\sum_{i=0}^{2} \alpha_{i}=0$
- Points $p \in A$ are such that $\sum_{i=0}^{2} \alpha_{i}=1$ (affine combination)


## AFFINE TRANSFORMATIONS

Combination of two arbitrary parallel projections

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Combination of two arbitrary parallel projections
Preserve affine combinations

$$
\begin{aligned}
\alpha_{0}+\alpha_{1}+\alpha_{2} & =1 \Rightarrow \\
T\left(\alpha_{0} a_{0}+\alpha_{1} a_{1}+\alpha_{2} a_{2}\right) & =\alpha_{0} T\left(a_{0}\right)+\alpha_{1} T\left(a_{1}\right)+\alpha_{2} T\left(a_{2}\right)
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Matrix of an affine transformation in affine frame

$$
[T]_{\mathcal{C}}=\left[\begin{array}{ccc}
a_{11} & a_{12} & t_{1} \\
a_{21} & a_{22} & t_{2} \\
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$$
\begin{gathered}
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a_{11} & a_{12} & t_{1} \\
a_{21} & 2_{22} & t_{2} \\
0 & 0 & 1
\end{array}\right]} \\
{[T(p)]_{\mathcal{C}}=[T]_{\mathcal{C}}[p]_{\mathcal{C}}=\left[\begin{array}{ccc}
a_{11} & a_{12} & t_{1} \\
a_{21} & a_{22} & t_{2} \\
0 & 0 & 1
\end{array}\right]\left[\begin{array}{c}
\alpha_{1} \\
\alpha_{2} \\
1
\end{array}\right]=\left[\begin{array}{c}
a_{11} \alpha_{1}+a_{21} \alpha_{2}+t_{1} \\
a_{21} \alpha_{1}+a_{22} \alpha_{2}+t_{2} \\
1
\end{array}\right]}
\end{gathered}
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Interesting transformations

- Translation, rotation, scale


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What about the matrix in barycentric frame $\mathcal{D}=\left\{a_{0}, a_{1}, a_{2}\right\}$

## AFFine geometry

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Visualization of the affine plane

## LINES AND CONICS

Line $a x+b y+c=0$

$$
\begin{gathered}
n^{\top} p=0, \quad \text { with } \\
n^{\top}=\left[\begin{array}{lll}
a & b & c
\end{array}\right] \quad \text { and } \quad p=\left[\begin{array}{c}
x \\
y \\
1
\end{array}\right]
\end{gathered}
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- How does it change with an affine transformation?


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Conic $a x^{2}+2 b x y+c y^{2}+2 d x+2 e y+f=0$

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p^{\top} C p=0, \text { with } \\
C=C^{\top}=\left[\begin{array}{lll}
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b & c & e \\
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## REVISITING PROBLEMS

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Find intersection between line and circle?
Find intersection between two circles?
Prove that the medians of a triangle are concurrent?

Projective points: lines through origin in 3D

- Ideal points

Projective points: lines through origin in 3D

- Ideal points

Projective lines: planes through origin in 3D

- Ideal line or line at infinity

Projective points: lines through origin in 3D

- Ideal points

Projective lines: planes through origin in 3D

- Ideal line or line at infinity

Projective plane

- Affine plane augmented with ideal points

Projective points: lines through origin in 3D

- Ideal points

Projective lines: planes through origin in 3D

- Ideal line or line at infinity

Projective plane

- Affine plane augmented with ideal points

Homogeneous coordinates

- Generalization of affine coordinates

$$
\left[\begin{array}{l}
a \\
b \\
c
\end{array}\right], \quad a, b, c \text { not all zero } \quad\left[\begin{array}{c}
w x \\
w y \\
w
\end{array}\right] \equiv\left[\begin{array}{c}
x \\
y \\
1
\end{array}\right], \quad w \neq 0
$$

## PROJECTIVE TRANSFORMATIONS

Combination of three arbitrary perspective transformations

## PROJECTIVE TRANSFORMATIONS

Combination of three arbitrary perspective transformations
Matrix of a projective transformation

$$
[T]=\left[\begin{array}{lll}
a_{11} & a_{12} & a_{13} \\
a_{21} & a_{22} & a_{23} \\
a_{31} & a_{32} & a_{33}
\end{array}\right]
$$

$$
\left[\begin{array}{lll}
a_{11} & a_{12} & a_{13} \\
a_{21} & a_{22} & a_{23} \\
a_{31} & a_{32} & a_{33}
\end{array}\right]\left[\begin{array}{l}
\alpha_{1} \\
\alpha_{2} \\
\alpha_{3}
\end{array}\right]=\left[\begin{array}{l}
a_{11} \alpha_{1}+a_{21} \alpha_{2}+a_{13} \alpha_{3} \\
a_{21} \alpha_{1}+a_{22} \alpha_{2}+a_{23} \alpha_{3} \\
a_{31} \alpha_{1}+a_{32} \alpha_{2}+a_{33} \alpha_{3}
\end{array}\right]
$$

## PROJECTIVE TRANSFORMATIONS

Combination of three arbitrary perspective transformations
Matrix of a projective transformation

$$
\begin{gathered}
{[T]=\left[\begin{array}{lll}
a_{11} & a_{12} & a_{13} \\
a_{21} & a_{22} & a_{23} \\
a_{31} & a_{32} & a_{33}
\end{array}\right]} \\
{\left[\begin{array}{lll}
a_{11} & a_{12} & a_{13} \\
a_{21} & a_{22} & a_{23} \\
a_{31} & a_{32} & a_{33}
\end{array}\right]\left[\begin{array}{l}
\alpha_{1} \\
\alpha_{2} \\
\alpha_{3}
\end{array}\right]=\left[\begin{array}{l}
a_{11} \alpha_{1}+a_{21} \alpha_{2}+a_{13} \alpha_{3} \\
a_{21} \alpha_{1}+a_{22} \alpha_{2}+a_{23} \alpha_{3} \\
a_{31} \alpha_{1}+a_{32} \alpha_{2}+a_{33} \alpha_{3}
\end{array}\right]}
\end{gathered}
$$

Must be invertible

## PROJECTIVE GEOMETRY

## Projective linear group

- Non-singular linear transformations in $\mathrm{R}^{3}$


## Projective geometry

Projective linear group

- Non-singular linear transformations in $\mathrm{R}^{3}$
- Preserves collinearity, tangency, cross-ratios


## PROJECTIVE GEOMETRY

Projective linear group

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- Maps between any two sets of 4 points non-collinear 3 by 3


## PROJECTIVE GEOMETRY

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All lines meet, even parallel lines

## PROJECTIVE GEOMETRY

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- Maps between any two sets of 4 points non-collinear 3 by 3

All lines meet, even parallel lines
All quadrilaterals are the same

## PROJECTIVE GEOMETRY

Projective linear group

- Non-singular linear transformations in $\mathrm{R}^{3}$
- Preserves collinearity, tangency, cross-ratios
- Maps between any two sets of 4 points non-collinear 3 by 3

All lines meet, even parallel lines
All quadrilaterals are the same
All conics are the same

## References

D. A. Brannan, M. F. Esplen, and J. J. Gray. Geometry. Cambridge University Press, 2011.

