

Improved Algorithms for Volume Rendering and Mesh Processing

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Rio de Janeiro, Brazil

introduction

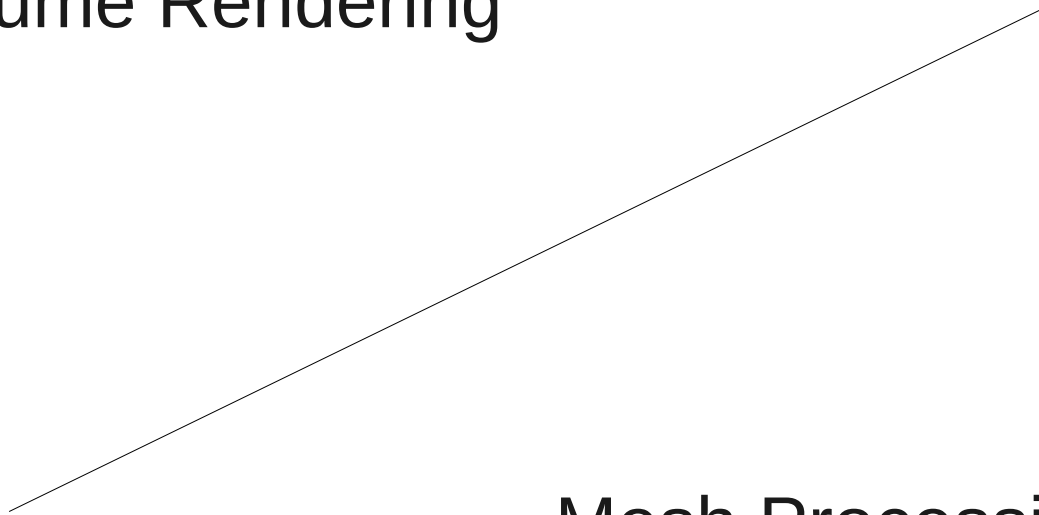
introduction

focus

introduction
volume rendering
mesh processing
conclusion

Volume Rendering

Mesh Processing



introduction

volume rendering

Goal

Better insight of the volume data

Source

MRI/CT acquisition

CFD numerical simulations

Applications

Geo-sciences

Fluid Simulations

Medical Images

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introduction

volume rendering

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Goal

Better insight of the volume data

Motivation

Regular and Irregular [Data](#)

Source

MRI/CT acquisition

Ray-Casting and Cell-Projection [Algorithms](#)

CFD numerical simulations

Volume and Iso-surface [Rendering](#)

GPU [Programming](#)

Applications

[Geo](#)-sciences

Fluid [Simulations](#)

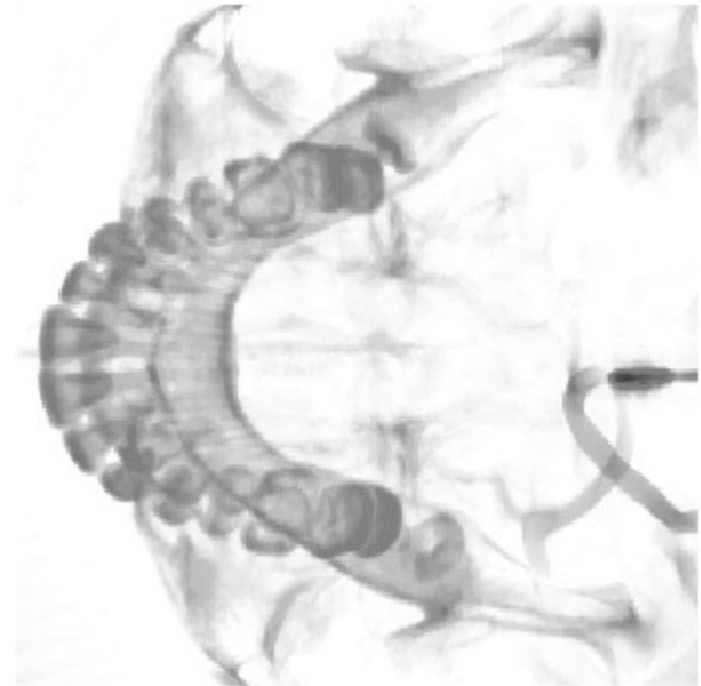
[Medical](#) Images

illustration

regular data rendering

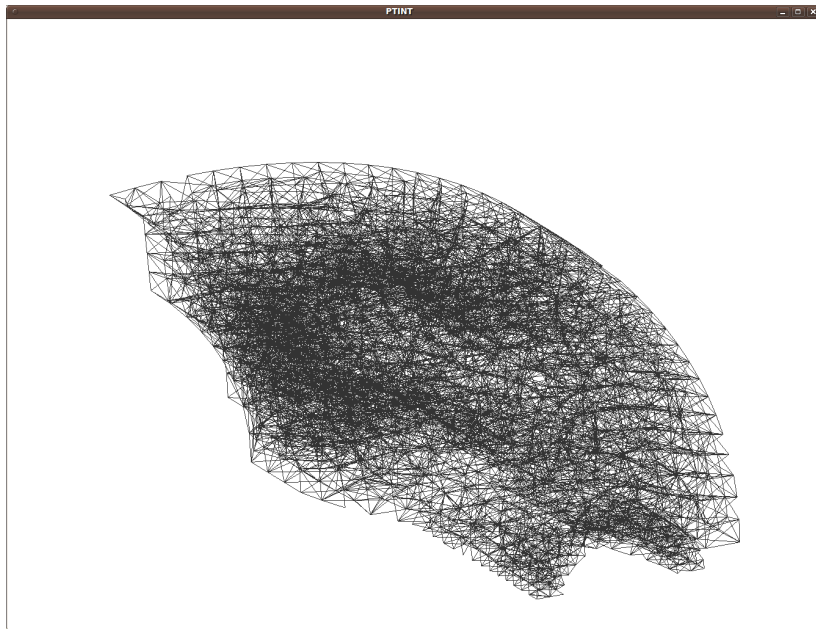


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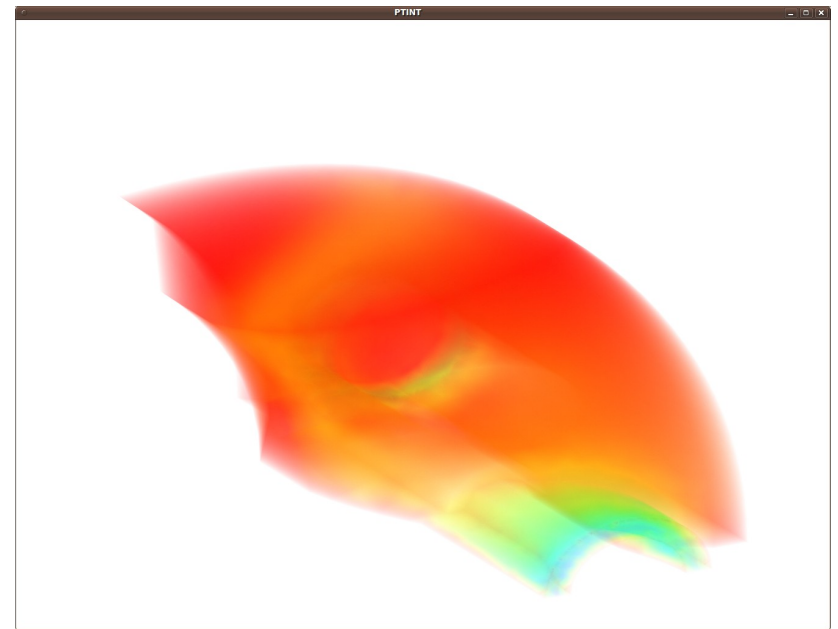


illustration

irregular data rendering



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introduction

mesh processing

Goal

Manipulation of meshed surfaces

Source

Generated by artists

Scanned from real-world objects

Applications

CAD

CG Arts

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introduction

mesh processing

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Goal

Manipulation of meshed surfaces

Motivation

Similarity [Descriptor](#)

Source

[Propagate](#) Mesh Processing

Generated by artists

Scanned from real-world objects

Applications

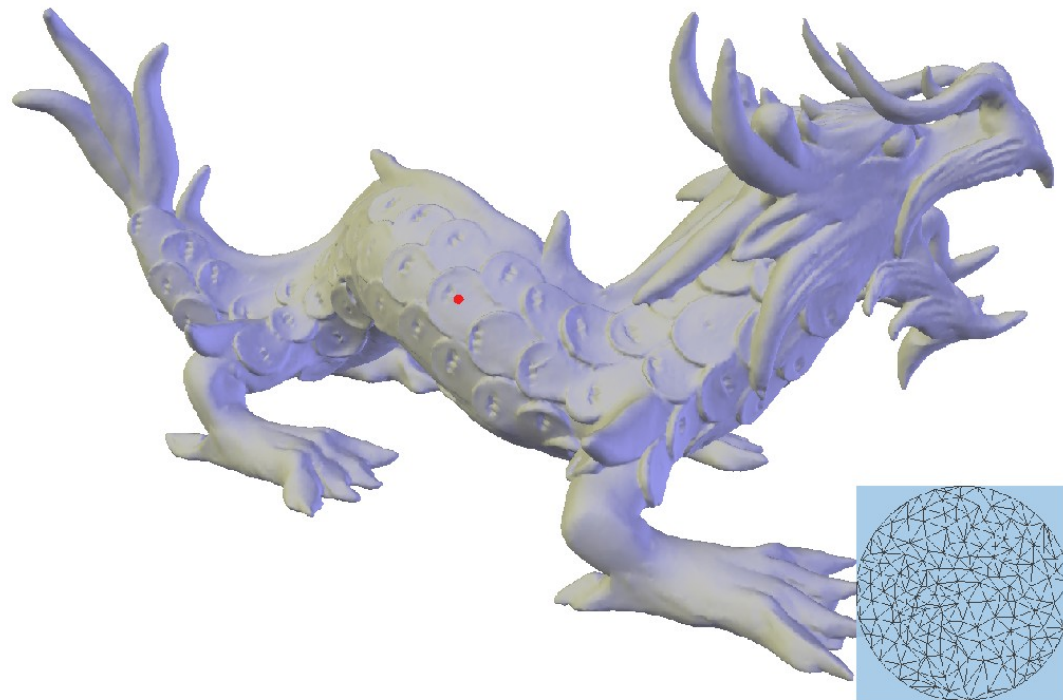
[CAD](#)

[CG Arts](#)

illustration

mesh parameterization

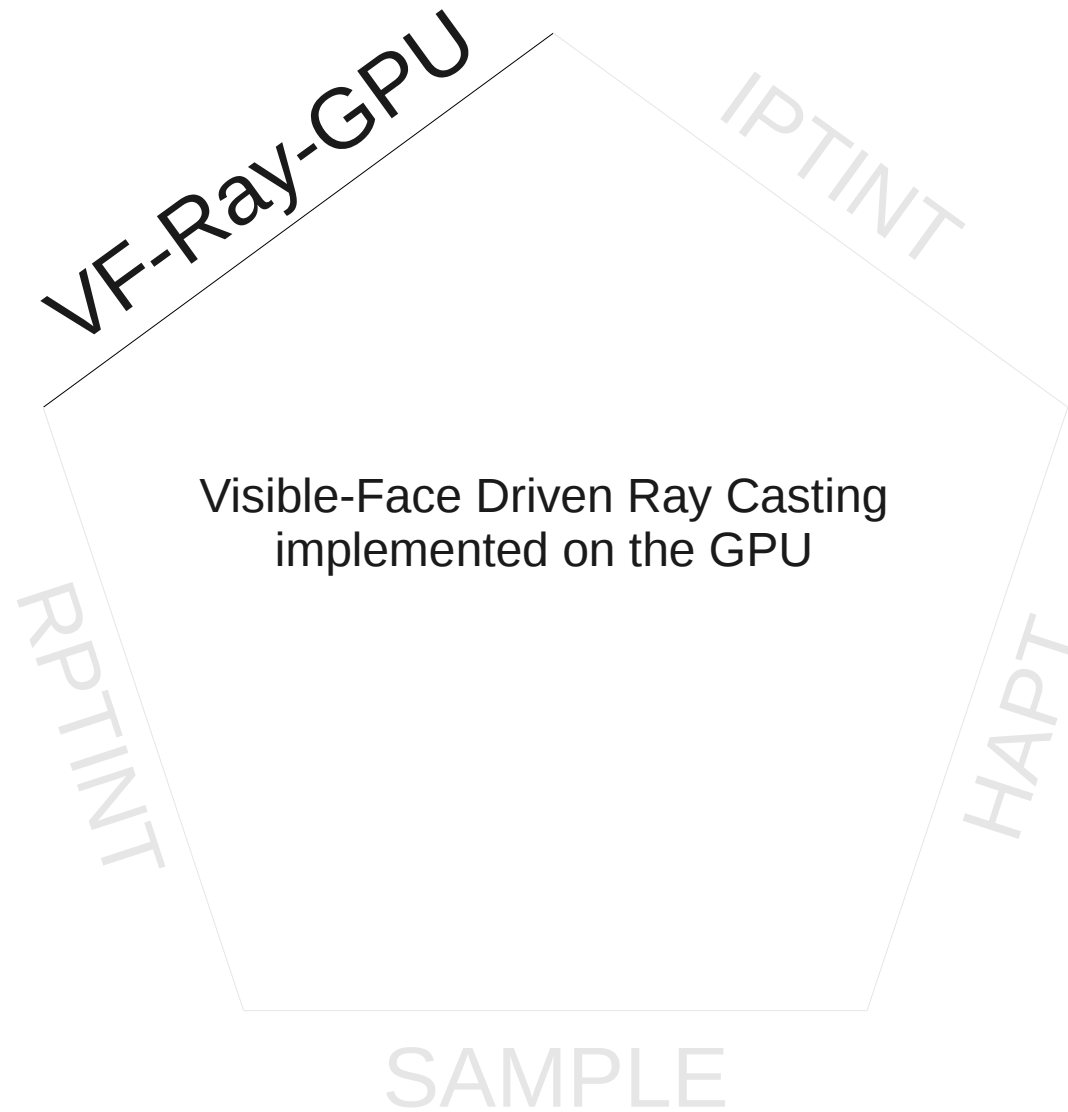
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volume rendering

algorithm I

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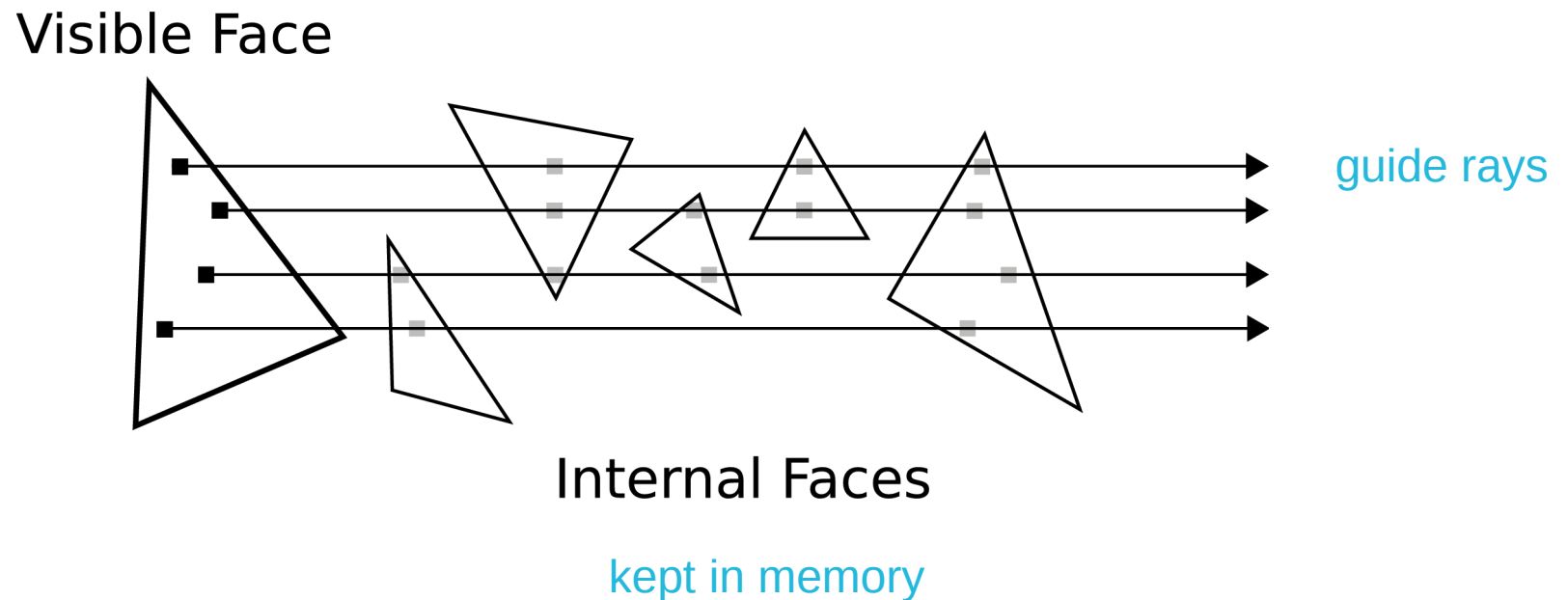


VF-Ray

Visible-Face Driven *
Ray Casting

basic idea

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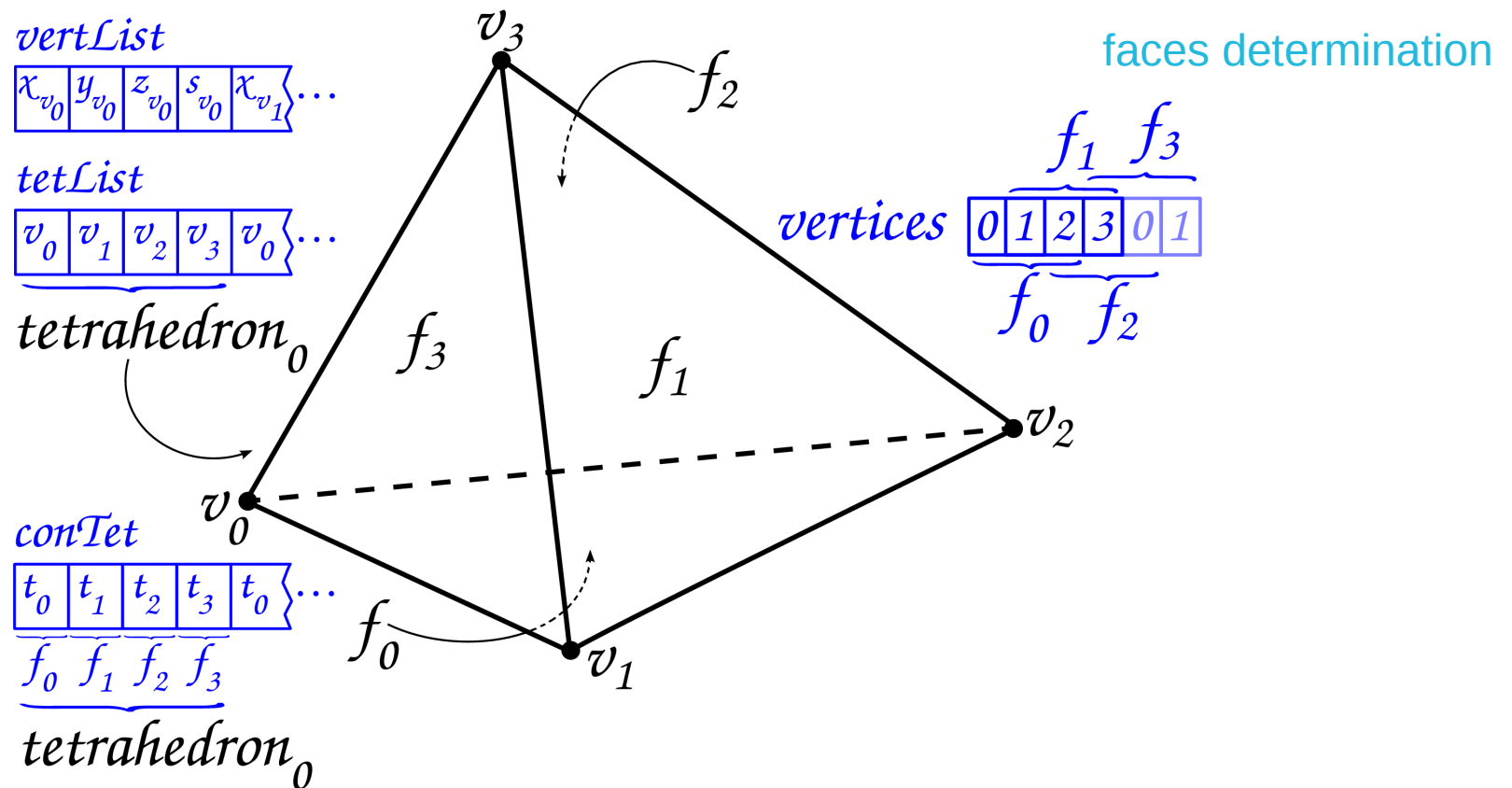


* RIBEIRO, S., MAXIMO, A., BENTES, C., OLIVEIRA, A., FARIAS, R. “Memory-Aware and Efficient Ray-Casting Algorithm”, in Proceedings of *SIBGRAPI (IEEE Computer Society)*, pp. 147-154, Belo Horizonte, Minas Gerais, Brazil, 2007.

VF-Ray-GPU

basic data structures

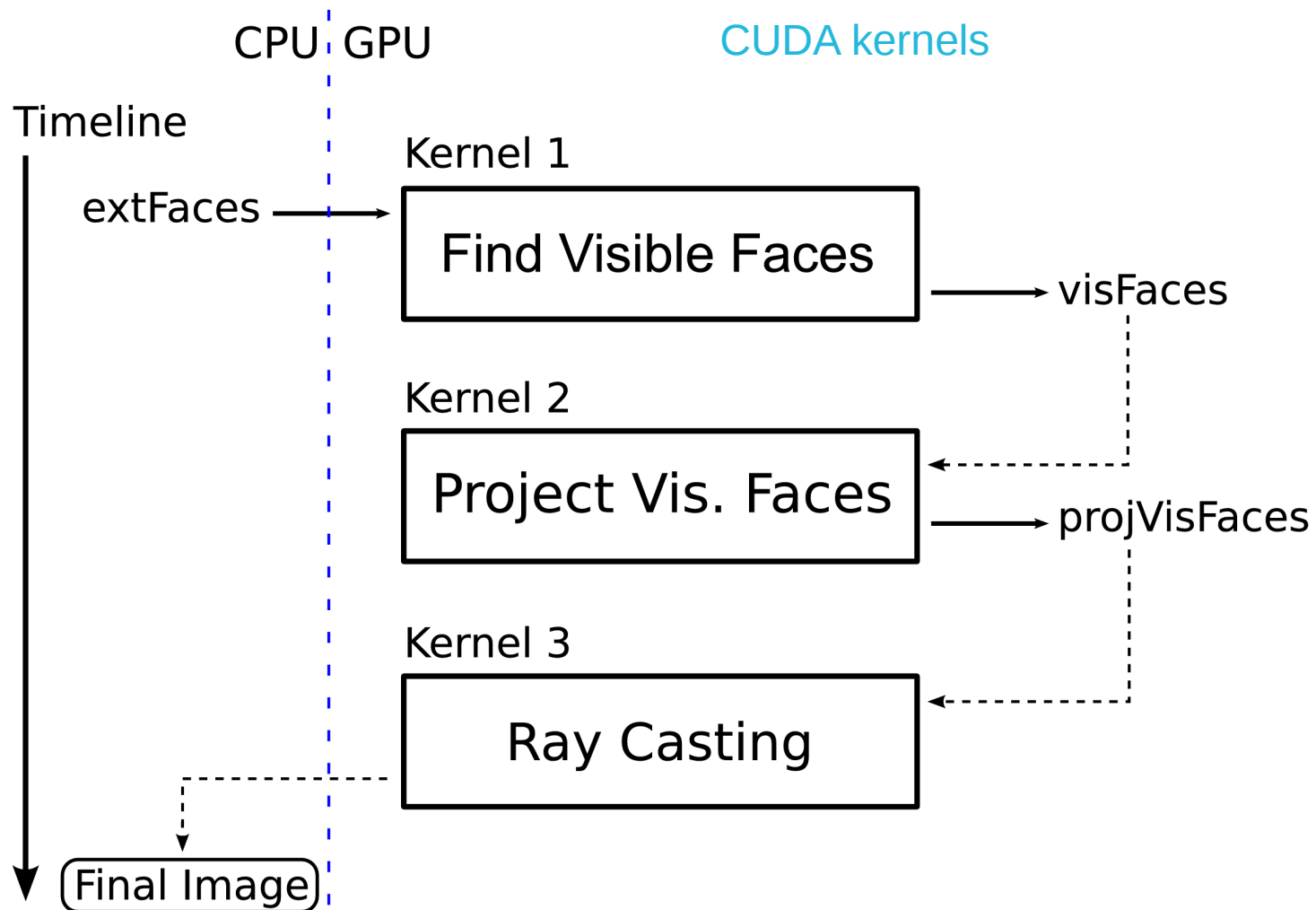
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VF-Ray-GPU

overview

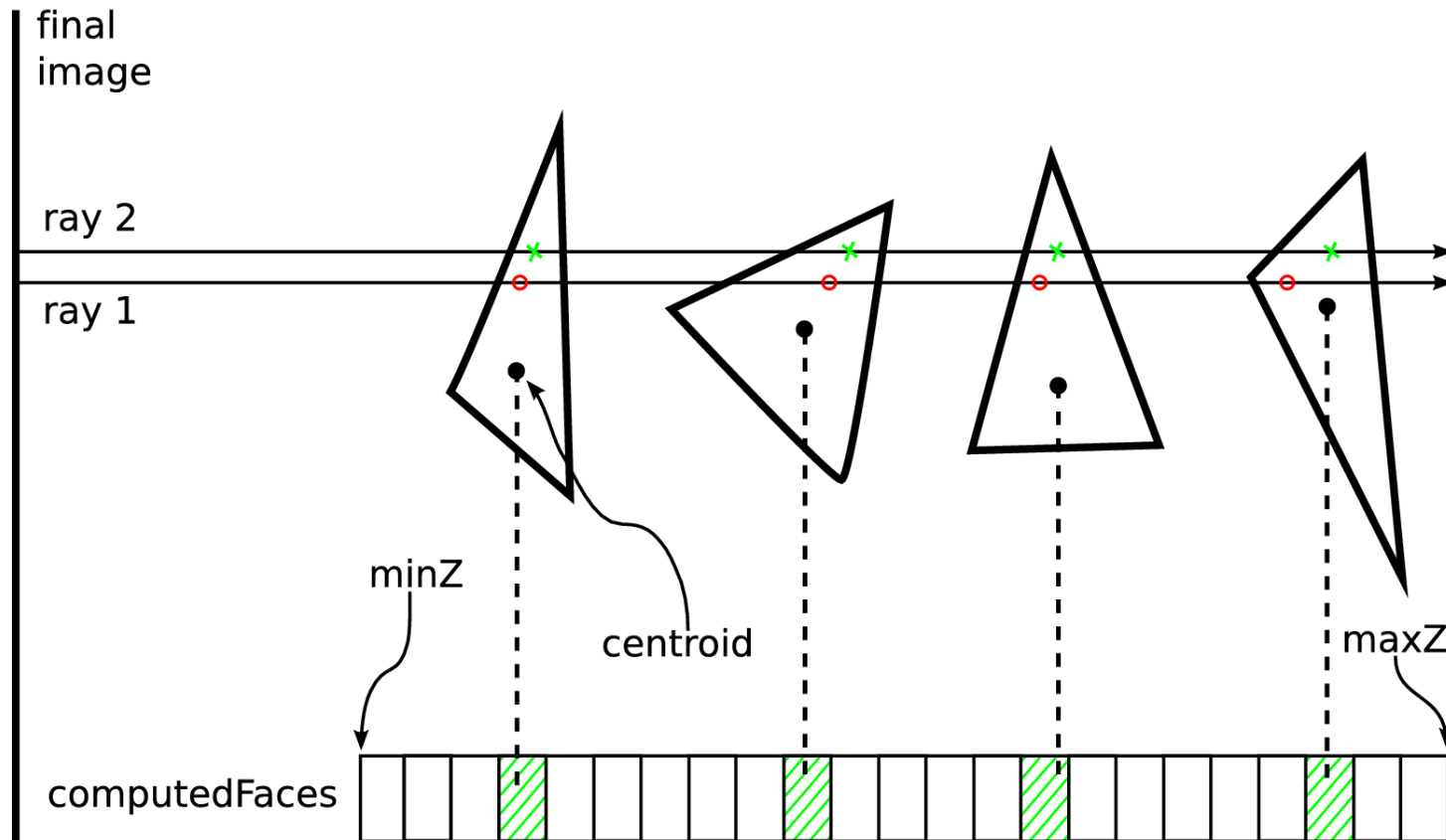
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VF-Ray-GPU

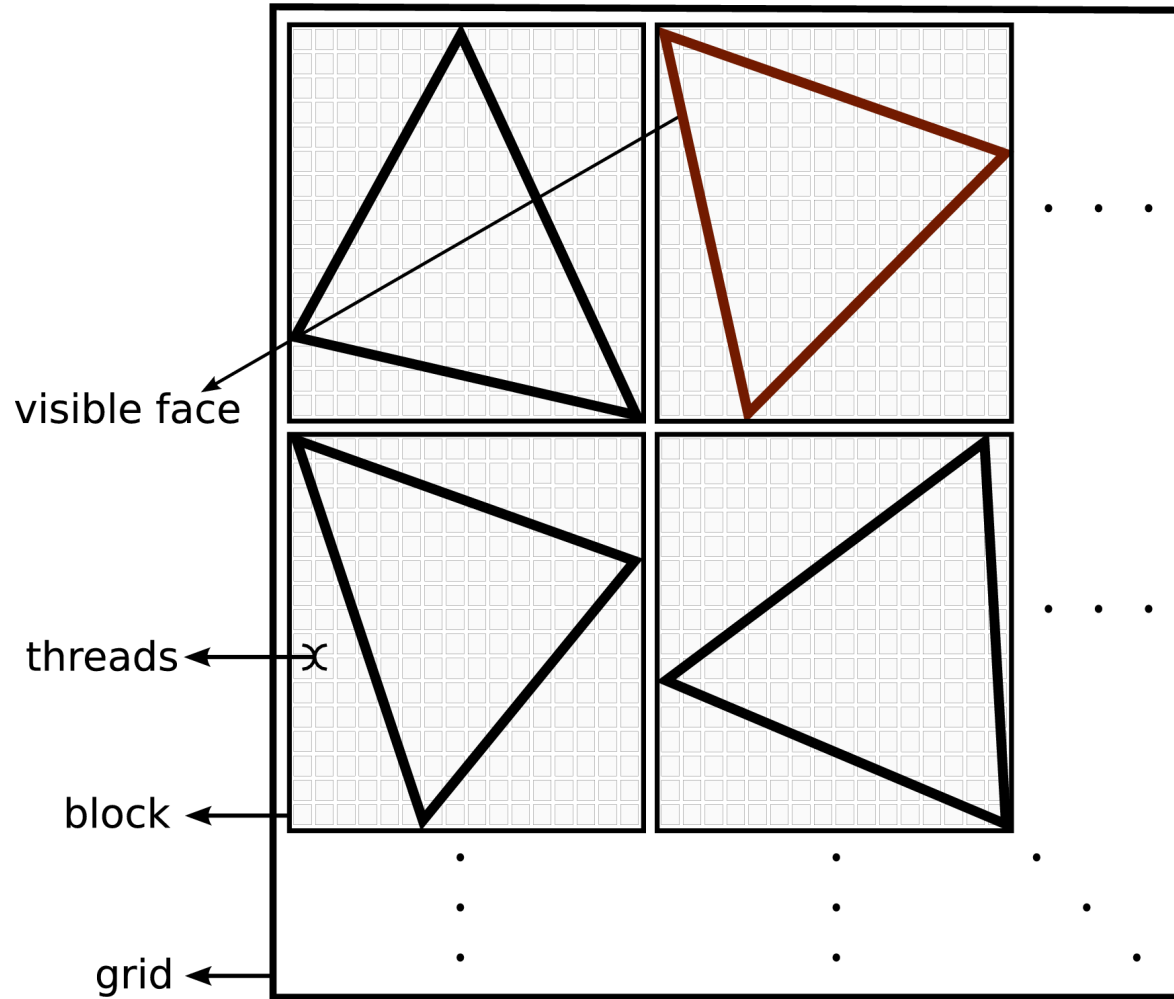
hashed buffer

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VF-Ray-GPU

threads scheme



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VF-Ray-GPU

results

1/3

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Memory aspects

<i>Algorithm</i>	<i>Bytes/Tet</i>	<i>Bytes/Pixel</i>	<i>Pre-Int</i>
VICP	456	—	16
HARC	160	96	16
HARC (INT)	96	96	1
VF-Ray-GPU	38	—	—

less than **half**
memory consumption

MB

VF-Ray-GPU

results

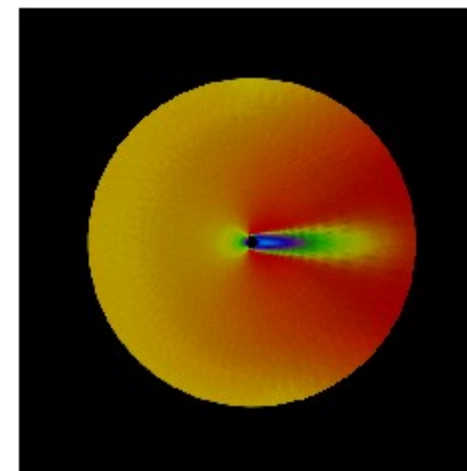
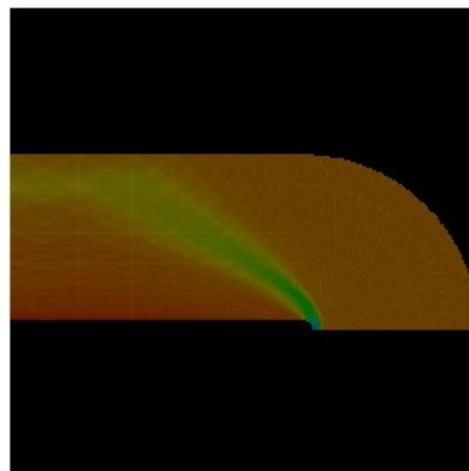
2/3

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Memory/Timing comparisons

<i>Algorithm</i>	blunt		post	
	<i>Memory (KB)</i>	<i>Time (ms)</i>	<i>Memory (KB)</i>	<i>Time (ms)</i>
VICP	118,524	190	249,928	546
HARC	72,267	18	123,245	33
HARC (INT)	22,636	32	50,248	51
VF-Ray-GPU	7,029	186	19,494	370

~10x less
memory



VF-Ray-GPU

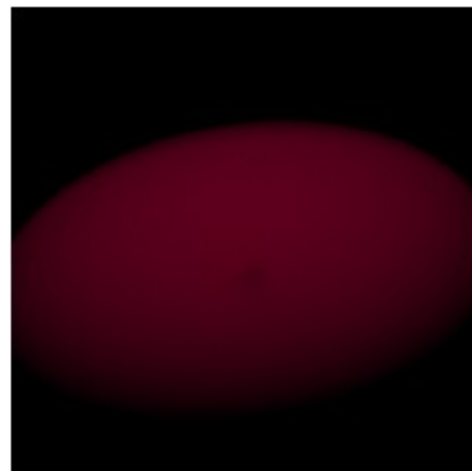
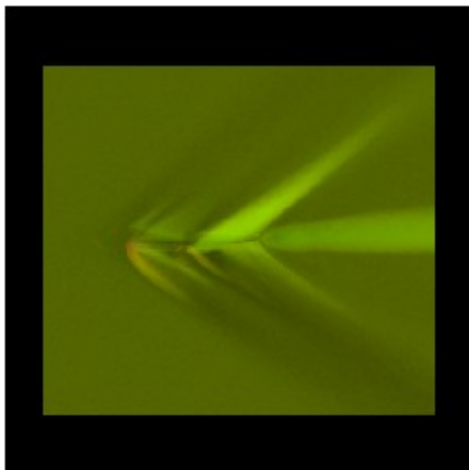
results

3/3

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VF-Ray x VF-Ray-GPU

Dataset	Memory (MB)		Time (ms)	
	CPU	GPU	CPU	GPU
fighter+	876	426	58326	10035
f16	499	239	51235	8815



half memory
consumption

~7x faster

VF-Ray-GPU

Visible-Face Driven Ray Casting
implemented on the GPU *

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code & publication

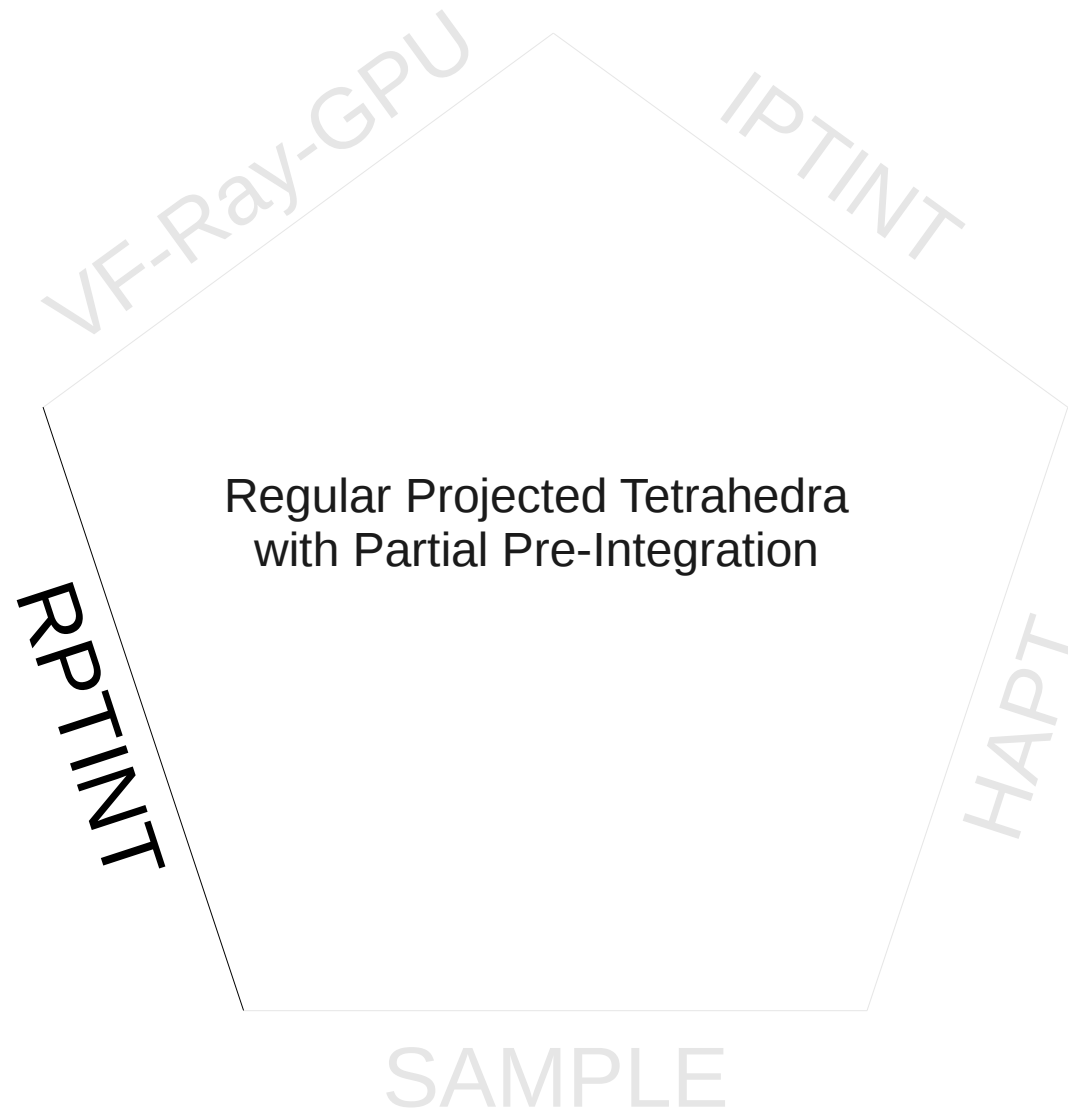
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<http://code.google.com/p/vfray>

- * MAXIMO, A., RIBEIRO, S., BENTES, C., OLIVEIRA, A., FARIAS, R. “**Memory-Efficient GPU-Based Ray Casting for Unstructured Volume Rendering**”, in *Proceedings of VG-PBG (Eurographics Association)*, pp. 155-162, Los Angeles, California, USA, 2008.

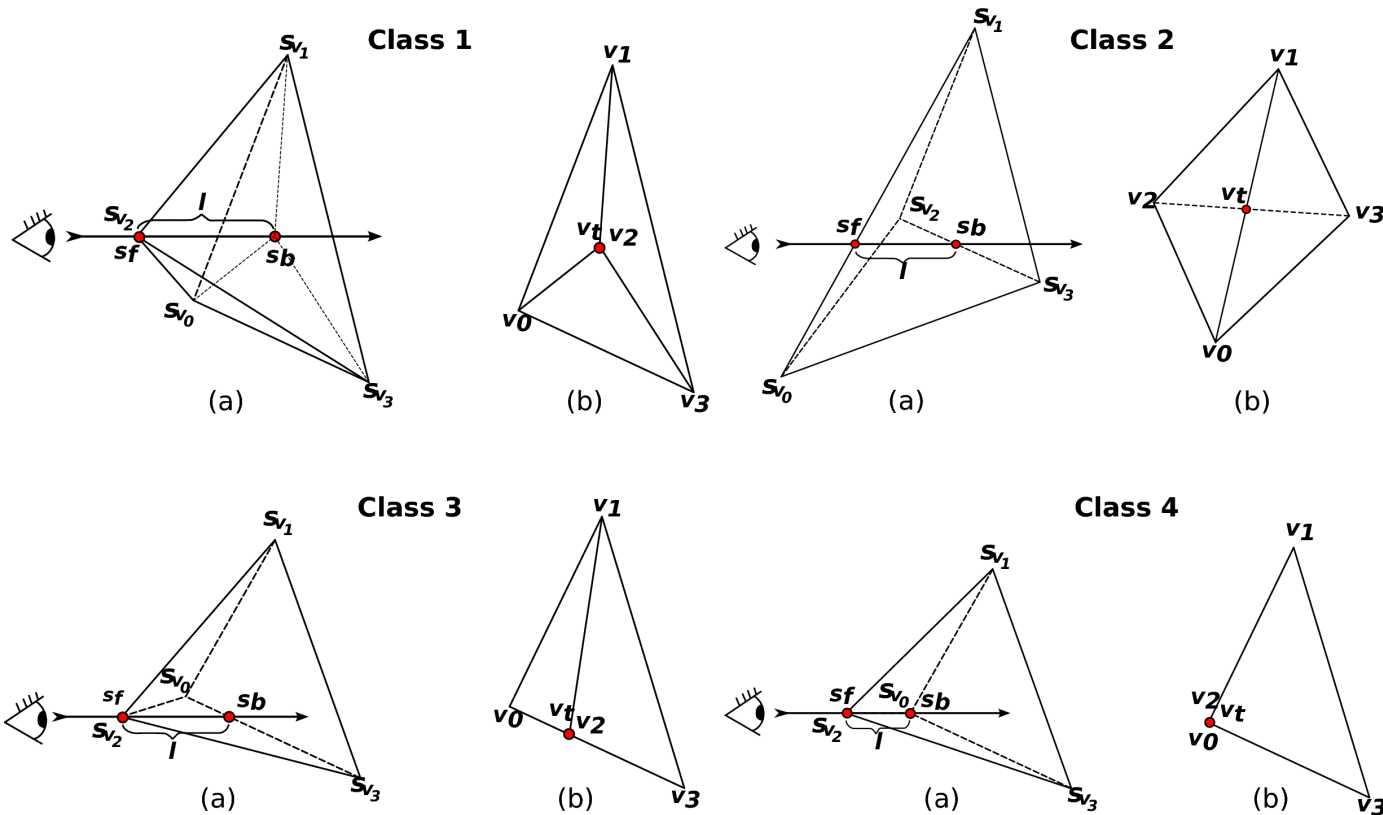
algorithm II

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first algorithm

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*

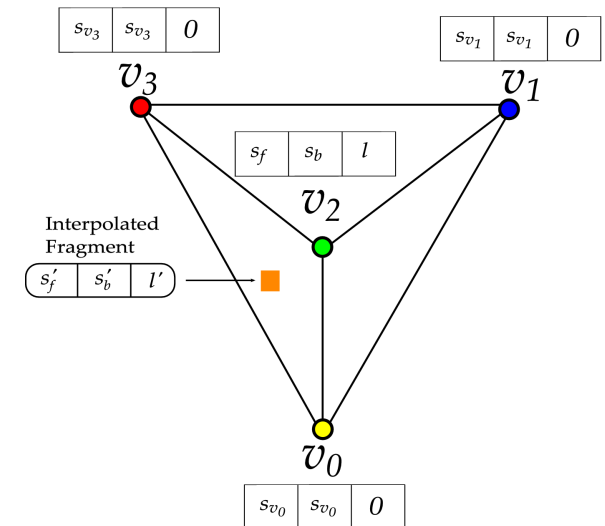
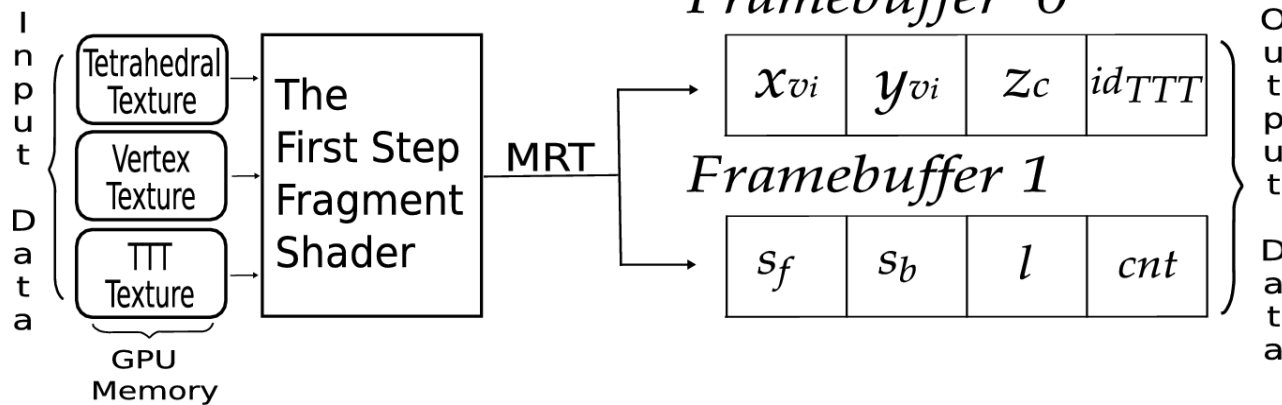
SHIRLEY, P., TUCHMAN, A. "A Polygonal Approximation to Direct Scalar Volume Rendering", in *Proceedings of SIGGRAPH*, v. 24, n. 5, pp. 63-70, 1990.

PTINT

Projected Tetrahedra with Partial Pre-Integration *

a two-step approach

introduction
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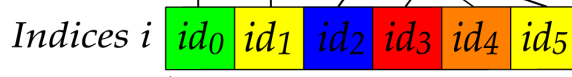
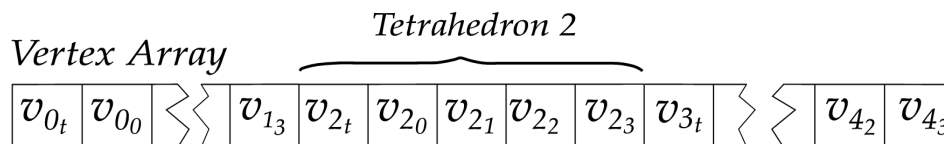
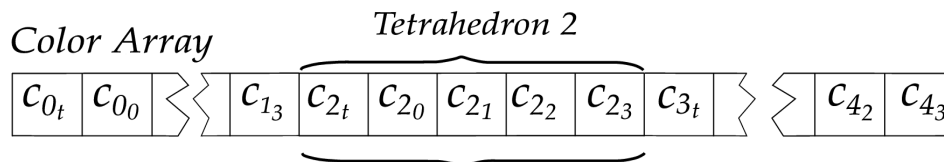
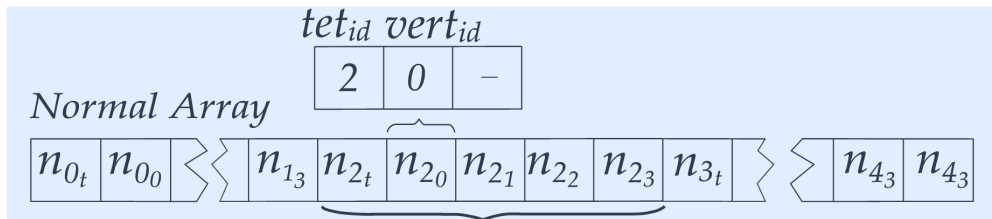
*

MARROQUIM, R., MAXIMO, A., FARIAS, R., ESPERANÇA, C.
“GPU-Based Cell Projection for Interactive Volume Rendering”,
in Proceedings of SIBGRAPI (IEEE Computer Society), pp. 147-154, Manaus, Amazonas, 2006. *Best Paper.*

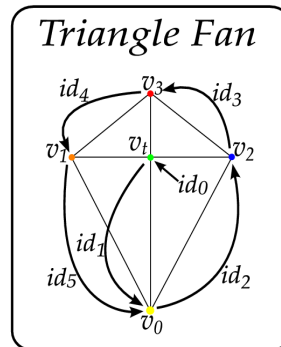
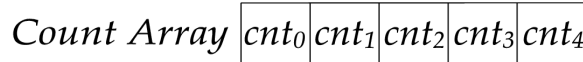
RPTINT

data structures

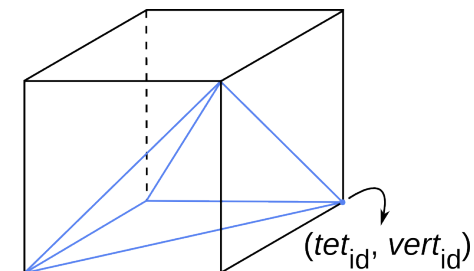
+



Count₂ = 6



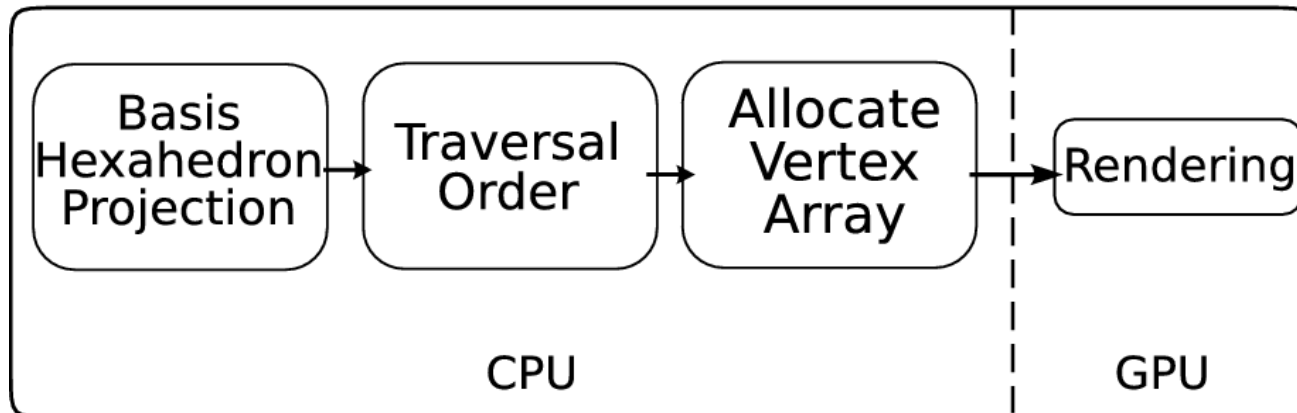
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RPTINT

overview

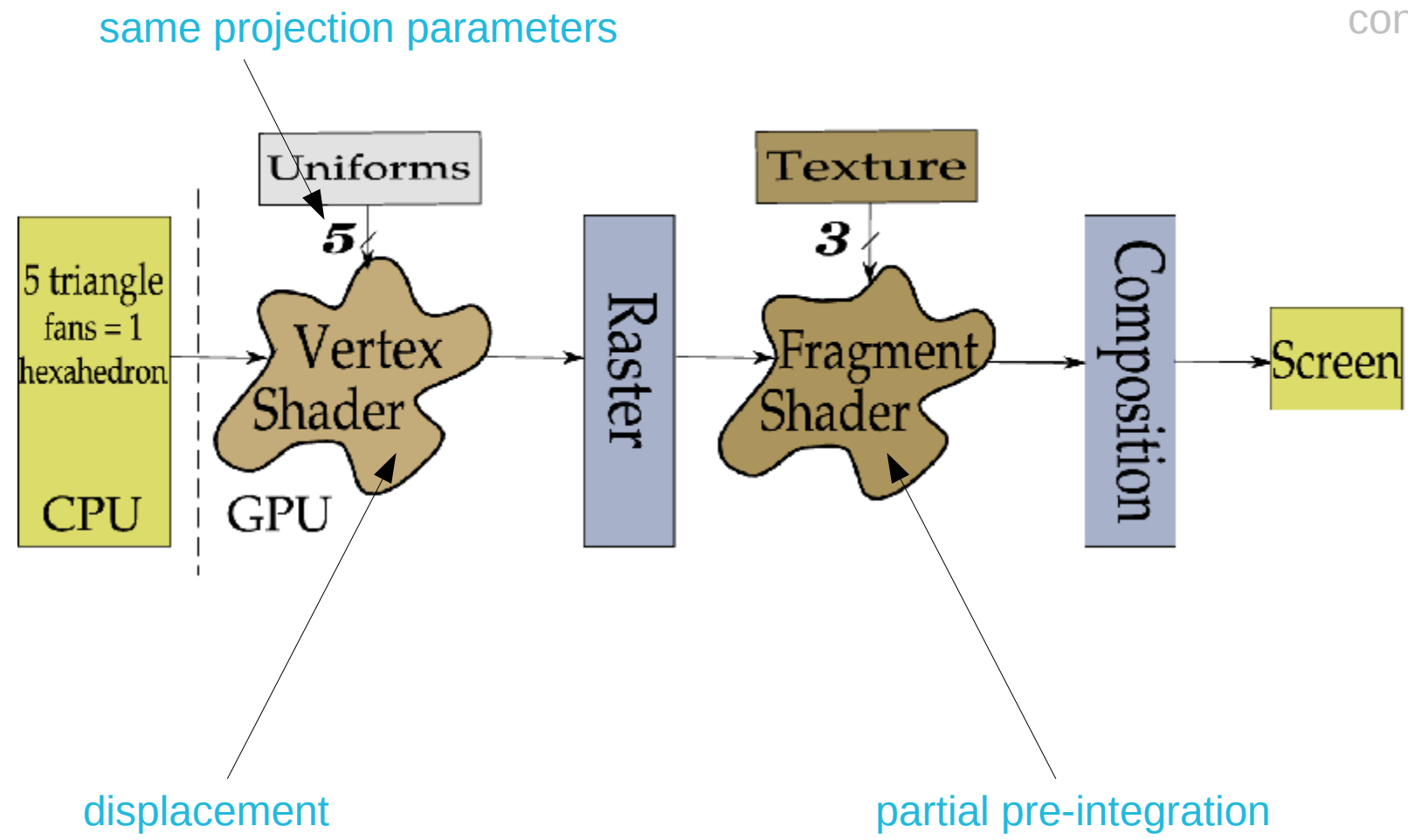
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RPTINT

4th step in GPU :: rendering pipeline

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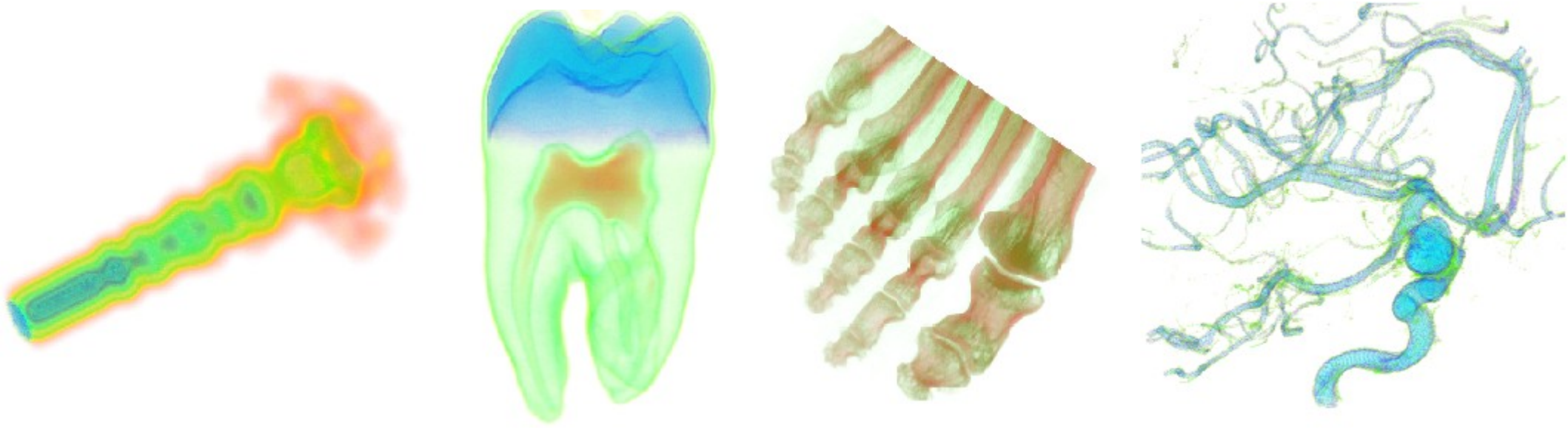
RPTINT

results :: performance measures

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Dataset	# Verts	# Tet	<i>fps</i>	<i>M Tet/s</i>
fuel	262 K	1.2 M	70.78	88.5 (5.99)
tooth—	1 M	5 M	1.22	13.1 (6.30)
tooth	10 M	52 M	0.24	12.7 (6.61)
foot	16 M	83 M	0.81	67.7 (6.23)
skull	16 M	83 M	0.61	51.7 (6.25)
aneurysm	16 M	83 M	2.42	201 (5.35)

256x256x256



RPTINT

results :: setup x render

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Dataset	Setup	Render	% Total
fuel	0.005 s	0.009 s	64.28 %
tooth	1.377 s	6.484 s	82.47 %
foot	4.556 s	9.074 s	66.57 %
skull	4.606 s	8.593 s	65.10 %
aneurysm	0.199 s	0.210 s	51.34 %

1st – 3rd steps (setup)
x
4th step (rendering)

theoretical limit

RPTINT

Regular Projected Tetrahedra
with Partial Pre-Integration *

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code & publication

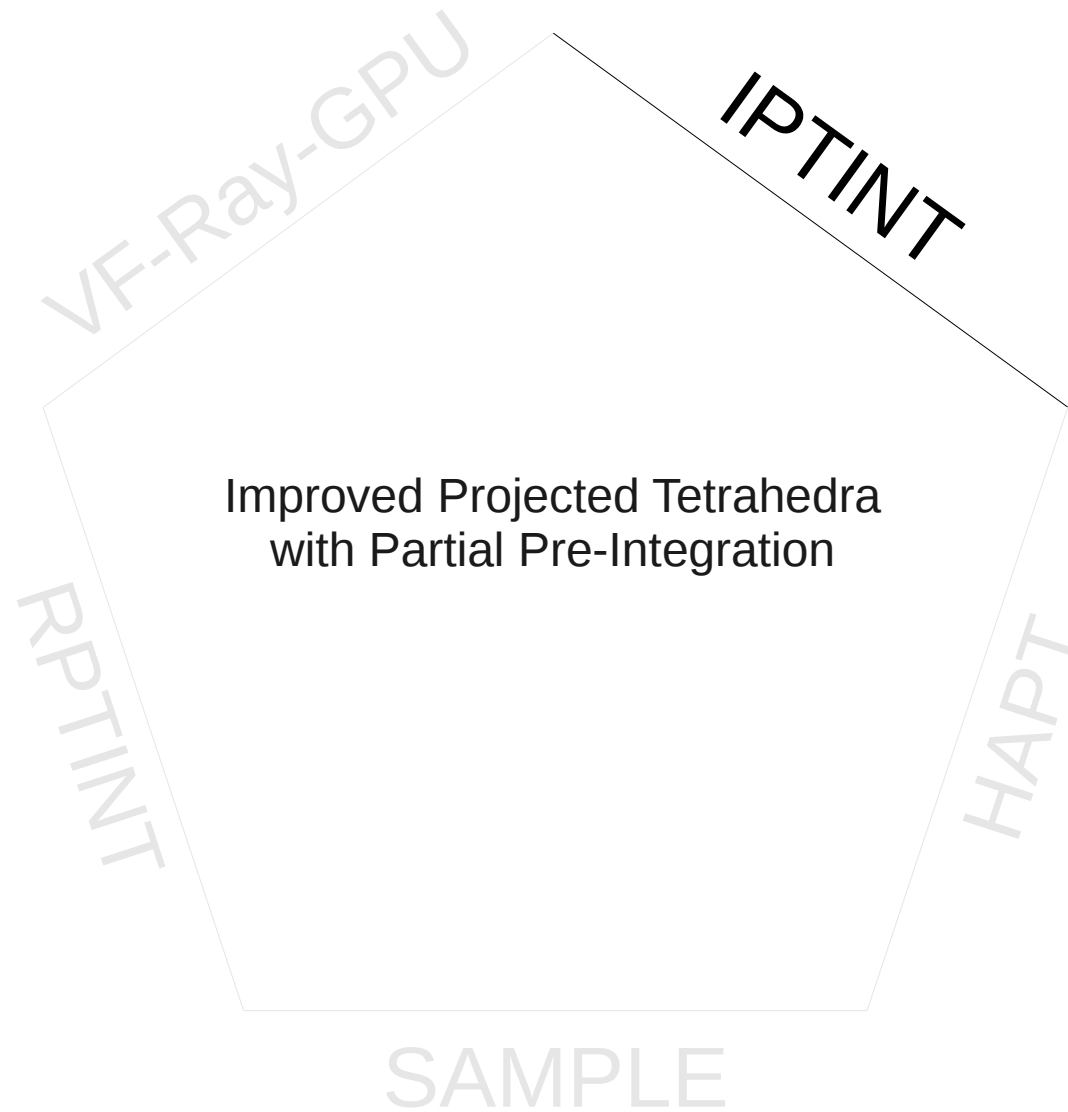
introduction
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<http://code.google.com/p/rptint>

* MAXIMO, A., MARROQUIM, R., FARIAS, R., ESPERANÇA, C.
“**GPU-Based Cell Projection for Large Structured Datasets**”, in
Proceedings of GRAPP (INSTICC), pp. 312-322, Barcelona, Spain,
2007.

algorithm III

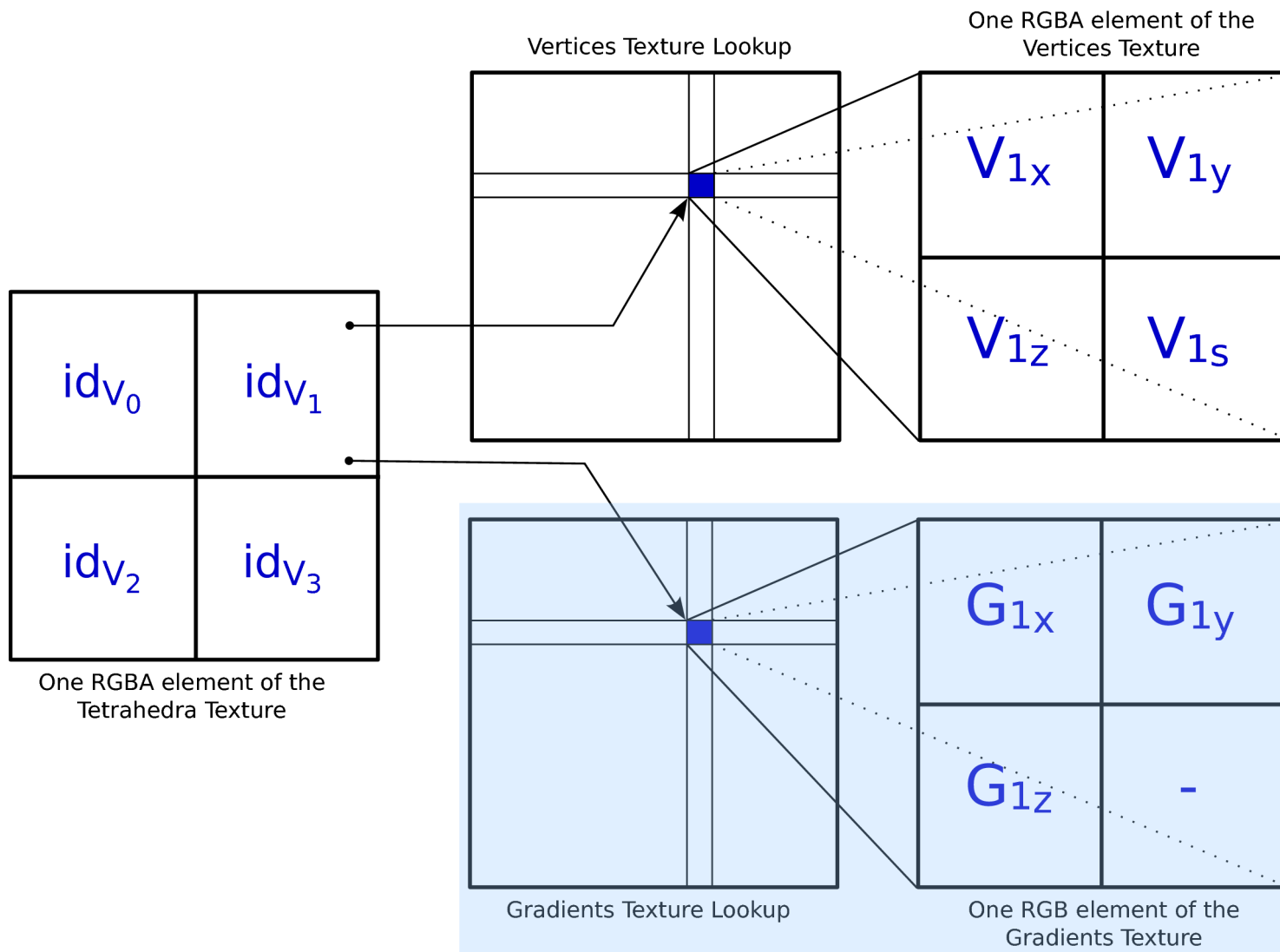
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IPTINT

data structures

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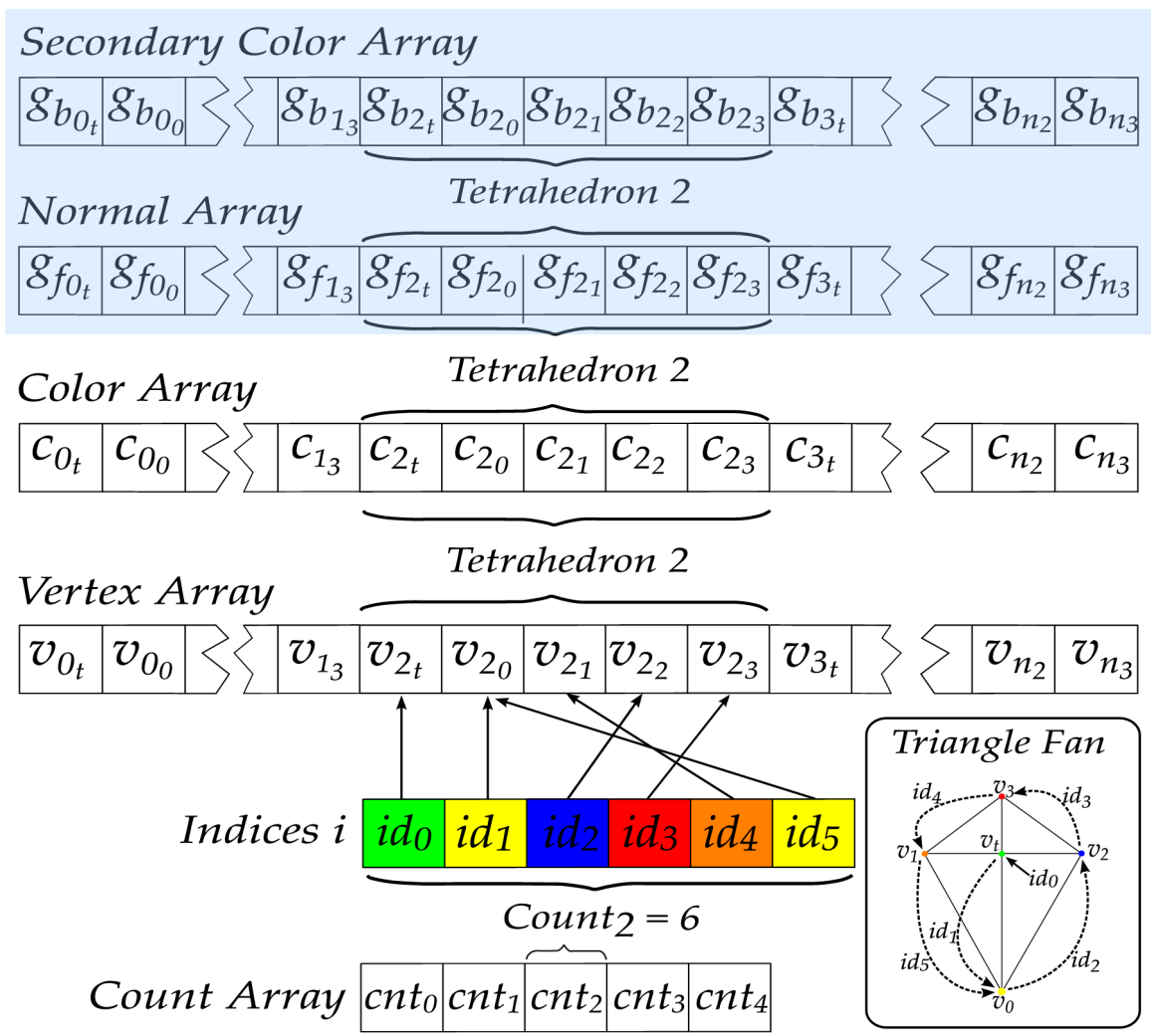


IPTINT

data structures

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 conclusion

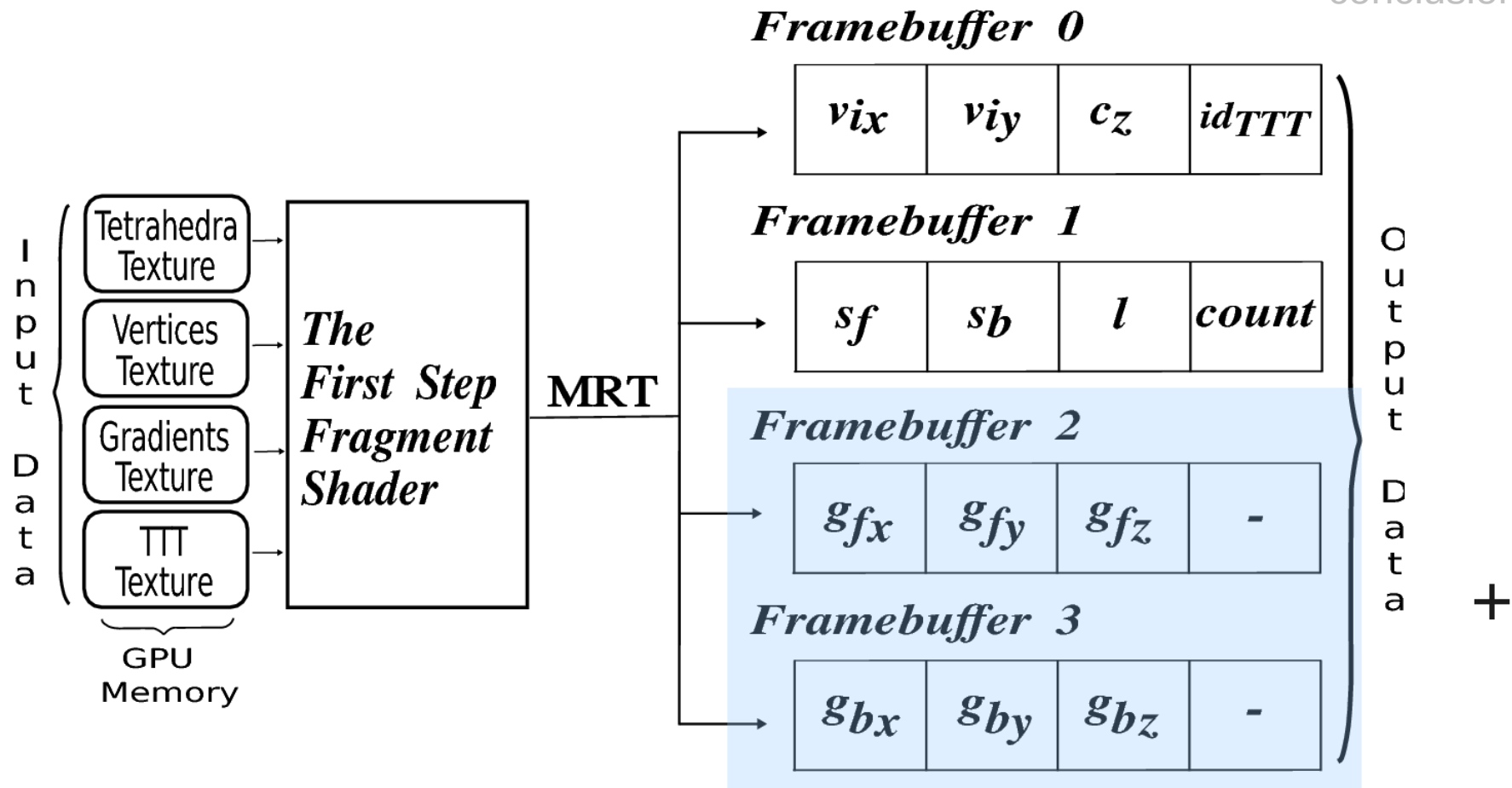
+



IPTINT

first step

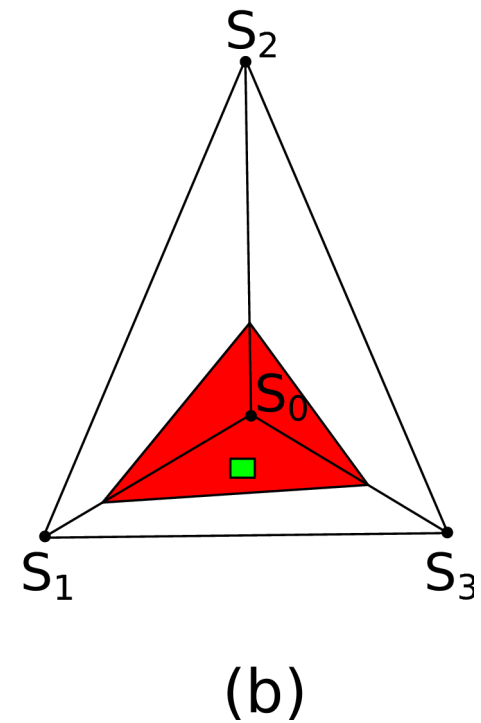
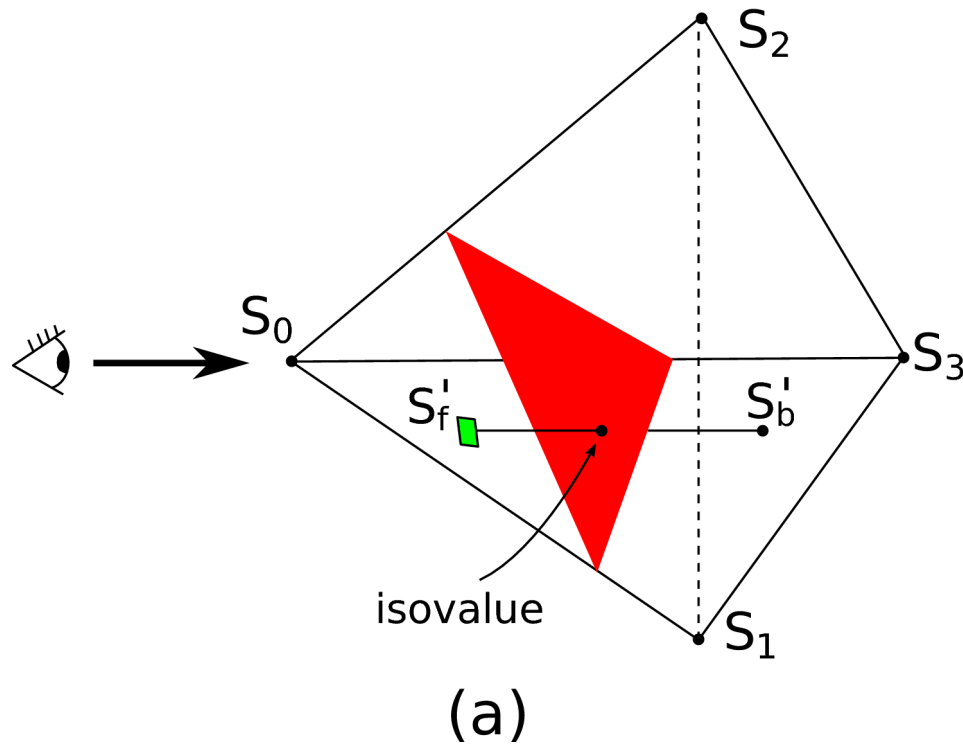
introduction
volume rendering
mesh processing
conclusion



IPTINT

iso-surface rendering

introduction
volume rendering
mesh processing
conclusion



normal ~ interpolated
gradient

IPTINT

results :: timing comparisons

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<i>Algorithm</i>	blunt	post
PTINT	10.76 <i>fps</i>	4.35 <i>fps</i>
IPTINT	4.97 <i>fps</i>	2.09 <i>fps</i>
GATOR	4.07 <i>fps</i>	1.51 <i>fps</i>
VICP (GPU)	5.20 <i>fps</i>	1.93 <i>fps</i>
VICP (CPU)	1.82 <i>fps</i>	0.57 <i>fps</i>
VICP (Balanced)	4.10 <i>fps</i>	1.11 <i>fps</i>
HARC	4.47 <i>fps</i>	8.63 <i>fps</i>
HARC (INT)	4.94 <i>fps</i>	5.93 <i>fps</i>
HAVIS	2.36 <i>fps</i>	0.79 <i>fps</i>
HAVS (k=2)	6.09 <i>fps</i>	3.09 <i>fps</i>
HAVS (k=6)	3.45 <i>fps</i>	2.09 <i>fps</i>

50% slower than original PTINT

GPU hybrid rendering

~2x faster

IPTINT

results :: types of rendering

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Dataset	Size		<i>Basic</i>		<i>+INT</i>		<i>+ISO</i>	
	# Verts	# Tet	<i>fps</i>	<i>M Tet/s</i>	<i>fps</i>	<i>M Tet/s</i>	<i>fps</i>	<i>M Tet/s</i>
blunt	40 K	187 K	12.75	2.38	10.76	2.01	4.97	0.93
comb	47 K	215 K	11.12	2.38	8.98	1.92	3.71	0.79
post	110 K	513 K	4.91	2.51	4.35	2.23	2.09	1.07
spx+	150 K	828 K	4.68	2.55	4.52	2.47	1.23	1.02
fuel	262 K	1.25 M	26.01	2.10	22.99	1.86	9.95	0.80
neghip	262 K	1.25 M	3.59	2.34	3.11	2.03	1.27	0.83

Original **PT**
 in GPU

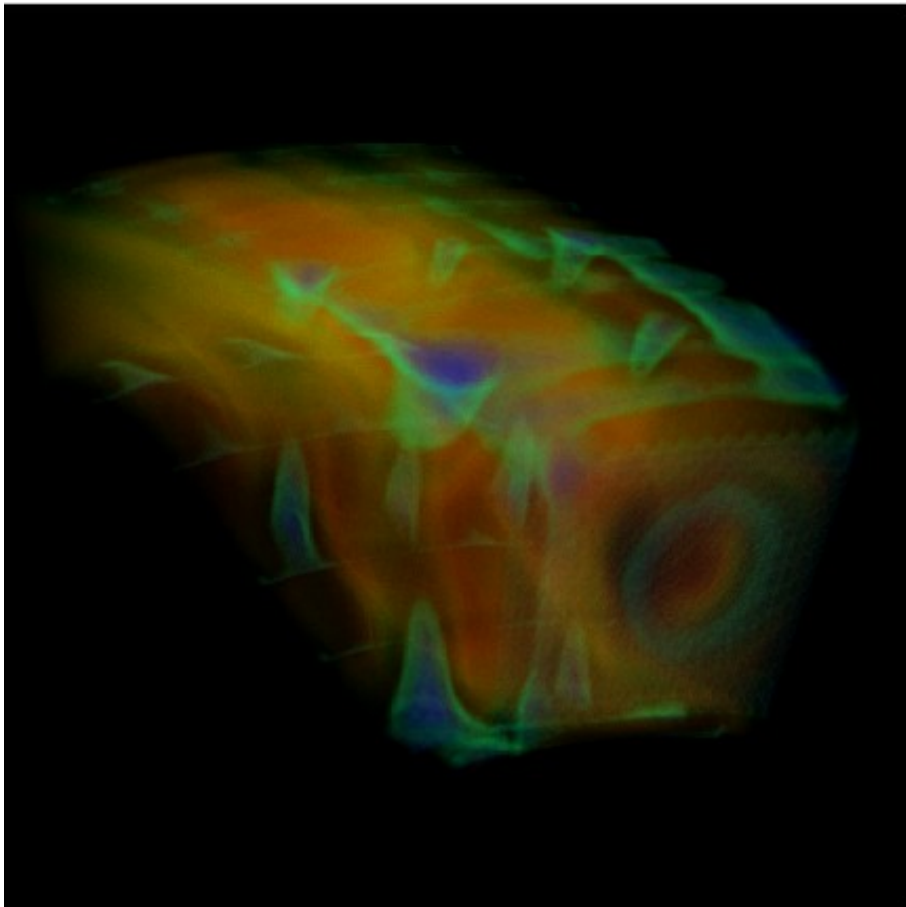
Original
PTINT

IPTINT

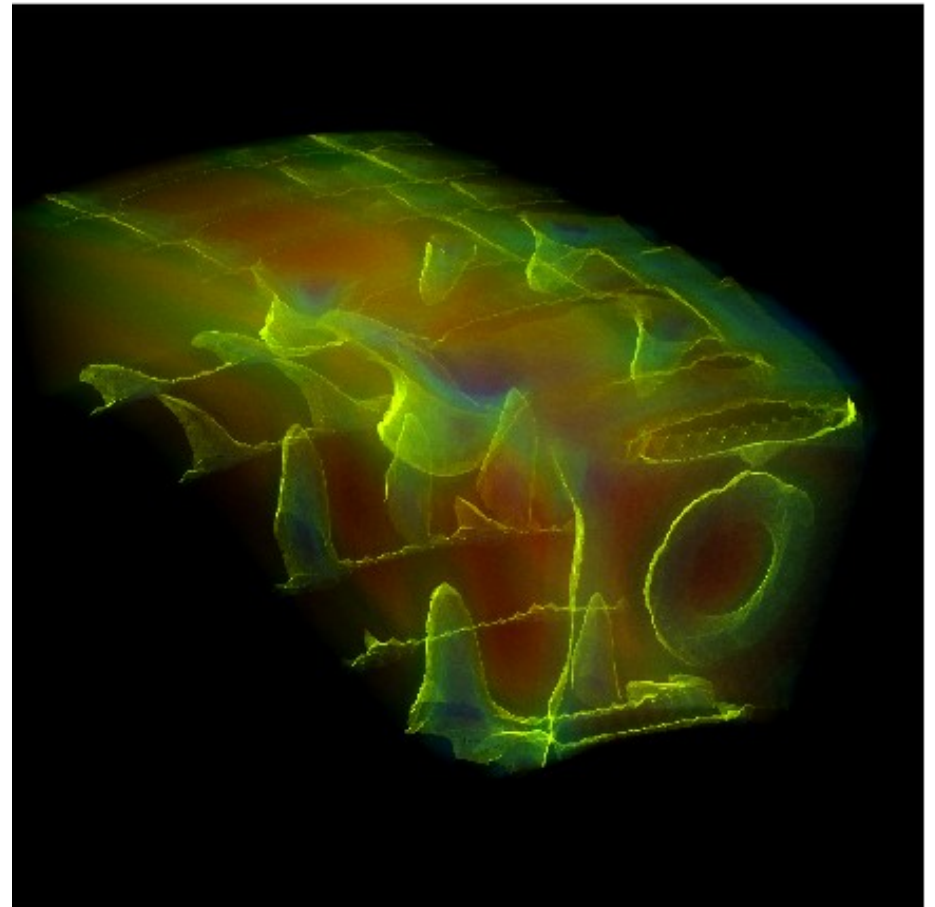
IPTINT

results :: renderings

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comb (215 K Tets)
+int @8.98 fps

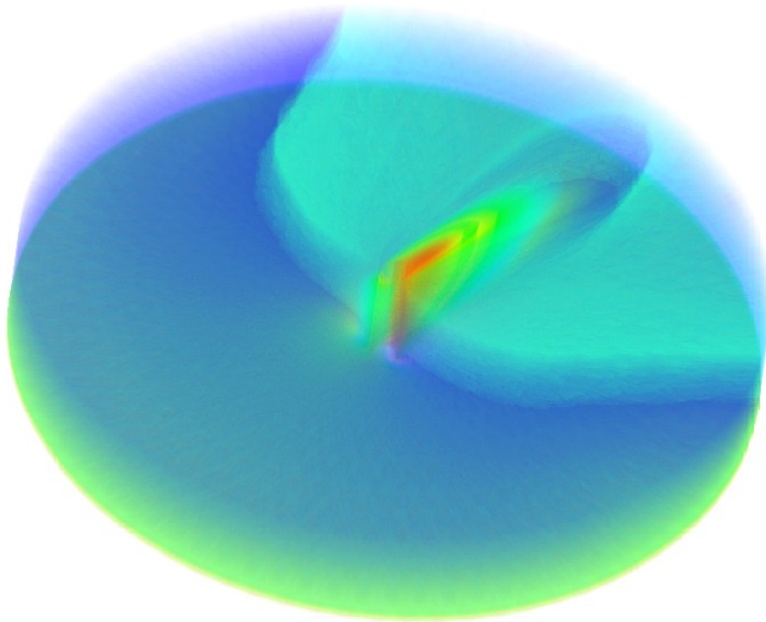


comb (215 K Tets)
+int +iso @3.71 fps

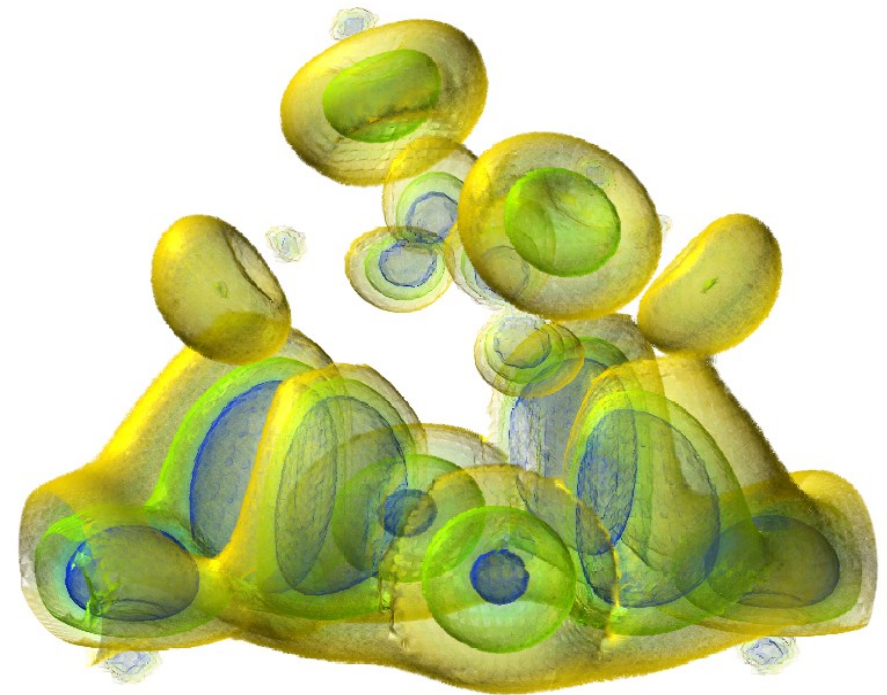
IPTINT

results :: renderings

introduction
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post (513 K Tets)
+int @4.35 fps



neghip (1.25 M Tets)
+int +iso @1.27 fps

IPTINT

Improved Projected Tetrahedra
with Partial Pre-Integration *

July, 2010
André Maximo

code & publication

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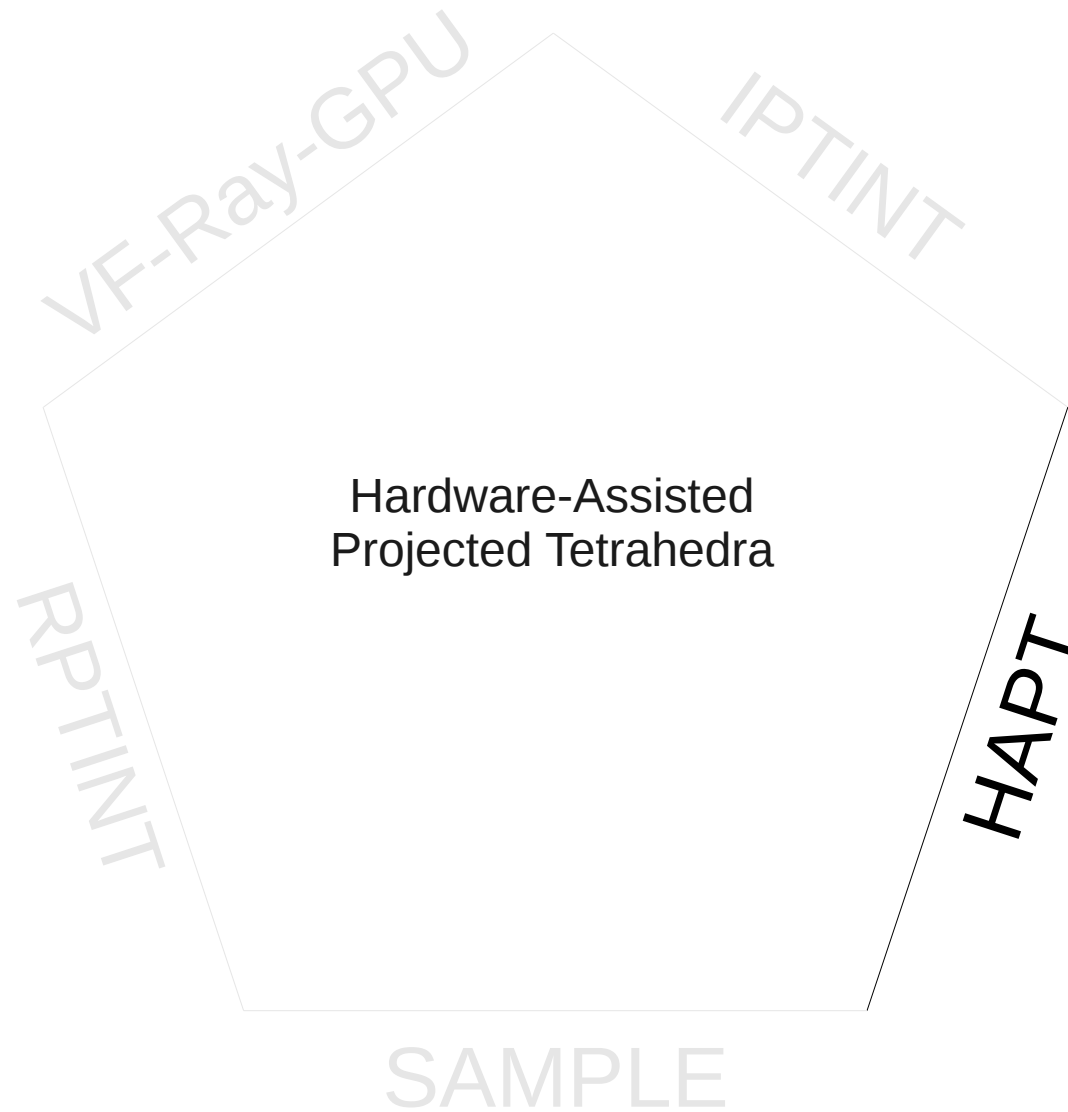
<http://code.google.com/p/ptint>

*

MARROQUIM, R., MAXIMO, A., FARIAS, R., ESPERANÇA, C.
“**Volume and Isosurface Rendering with GPU-Accelerated Cell
Projection**”, *Computer Graphics Forum (Best Paper selection of
SIBGRAPI 2006)*, v. 27, pp. 24-35, 2008.

algorithm IV

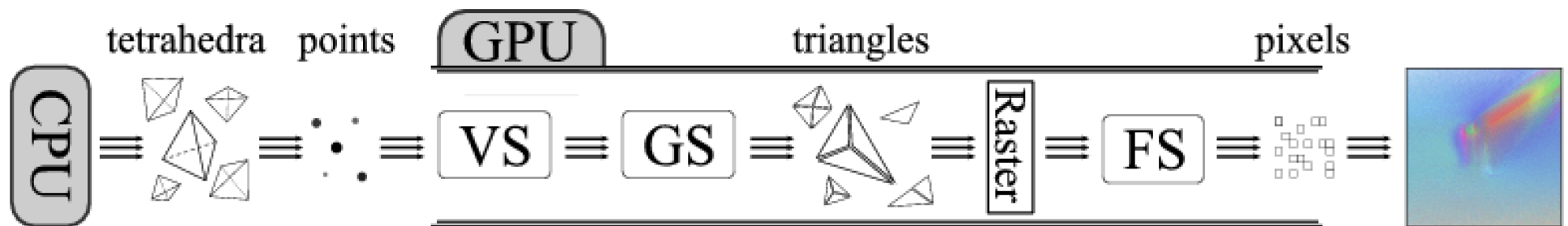
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HAPT

pipeline

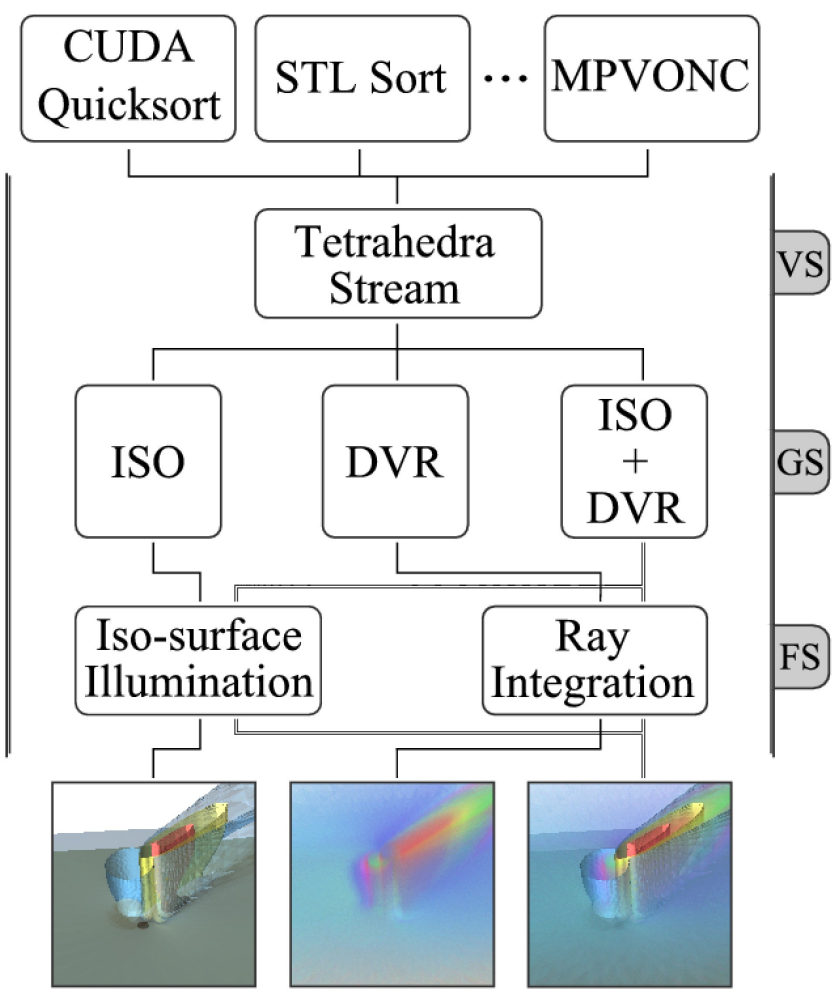
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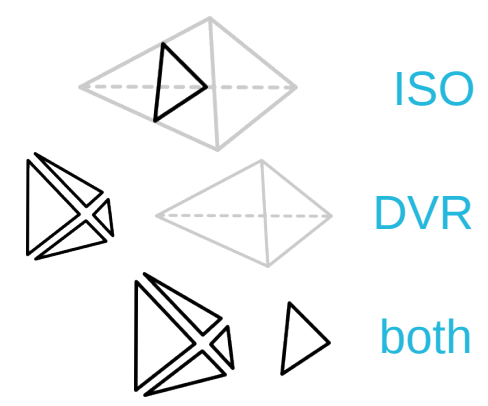
HAPT

framework

easy change of
its **modules**



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HAPT

results :: performance measures

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Dataset	Size		<i>DVR</i>		<i>ISO</i>		<i>DVR + ISO</i>	
	# Verts	# Tet	<i>fps</i>	<i>M Tet/s</i>	<i>fps</i>	<i>M Tet/s</i>	<i>fps</i>	<i>M Tet/s</i>
blunt	40 K	187 K	19.2	3.59	25.5	4.78	7.7	1.44
post	110 K	513 K	8.1	4.15	11.9	6.10	3.0	1.51
spx+	150 K	828 K	7.4	6.11	8.2	6.76	1.9	1.57
delta	211 K	1 M	4.5	4.52	6.0	6.01	1.5	1.51
torso	168 K	1.08 M	5.6	6.08	7.2	7.78	1.7	1.82
fighter	256 K	1.40 M	4.2	5.83	5.0	7.06	1.1	1.60
turbjet	212 K	1.01 M	17.5	17.67	n/a	n/a	n/a	n/a

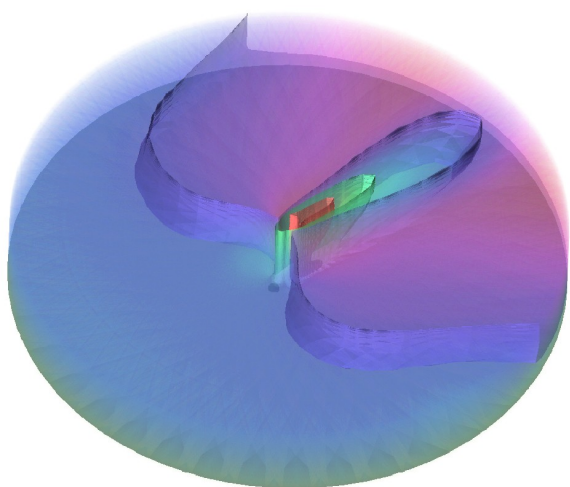
good frame rates
 1 M cells dataset

HAPT

results :: sorting

introduction
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Dataset	Maximum Error	Average Error	Different Pixels
blunt	1.961%	0.4069%	6.04%
post	2.353%	0.4245%	33.13%
spx+	1.569%	0.3985%	8.13%
delta	5.098%	0.5895%	14.25%
torso	1.176%	0.3933%	1.51%
fighter	1.569%	0.3943%	2.02%



Centroid
x
MPVONC

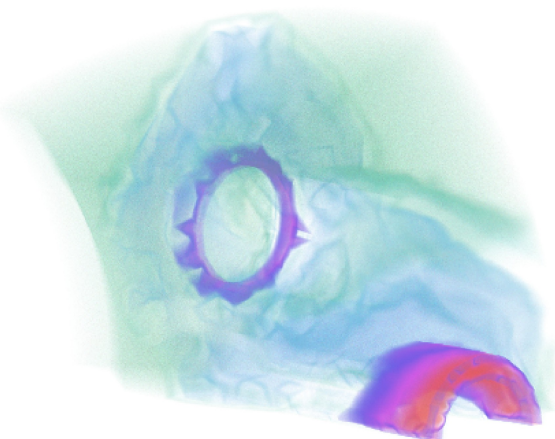
1/3 of the
pixels

0.4% ~ 1 unit
[0, 255]

HAPT

results :: timing comparisons

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spx (828 K Tets)
 partial pre-integration

<i>Algorithm</i>	<i>Sort</i>	<i>Draw</i>	<i>fps</i>	<i>M Tet/s</i>
HAPT ^Q	0.03 s	0.09 s	7.4	6.11
HAPT ^B	0.04 s	0.09 s	6.9	5.73
HAPT ^S	0.08 s	0.09 s	5.4	4.50
HAPT ^M	0.13 s	0.09 s	4.4	3.61
HAVS ²	0.09 s	0.11 s	5.0	4.14
HAVS ⁶	0.09 s	0.12 s	4.7	3.94
PTINT	0.19 s	0.20 s	2.4	2.06
GATOR	0.08 s	0.83 s	1.1	0.93
HARC	n/a	0.22 s	4.6	3.82
HARC (INT)	n/a	0.28 s	3.5	2.90

50% faster

HAPT

results :: timing comparisons

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<i>Algorithm</i>	“torso” 1082 K Tet		“fighter” 1403 K Tet	
	<i>fps</i>	<i>M Tet/s</i>	<i>fps</i>	<i>M Tet/s</i>
	HAPT ^Q	5.6	6.08	4.2
HAPT ^B	4.3	4.68	3.6	5.09
HAPT ^S	3.9	4.25	2.9	4.10
HAPT ^M	1.6	1.73	1.2	1.62
HAVS ²	3.7	4.01	2.9	4.12
HAVS ⁶	3.3	3.60	2.7	3.89
PTINT	1.3	1.47	0.9	1.31
GATOR	0.7	0.76	0.4	0.56
HARC	4.8	5.19	3.8	5.33
HARC (INT)	3.9	4.22	3.0	4.21

PT in GPU
 adaptations

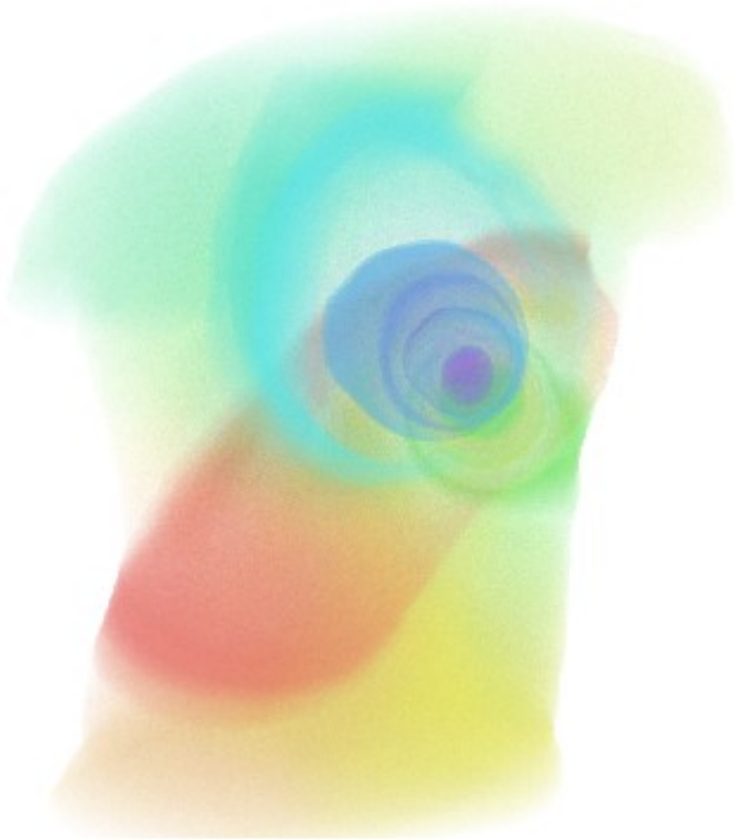
faster even with
 exact sorting

HAPT

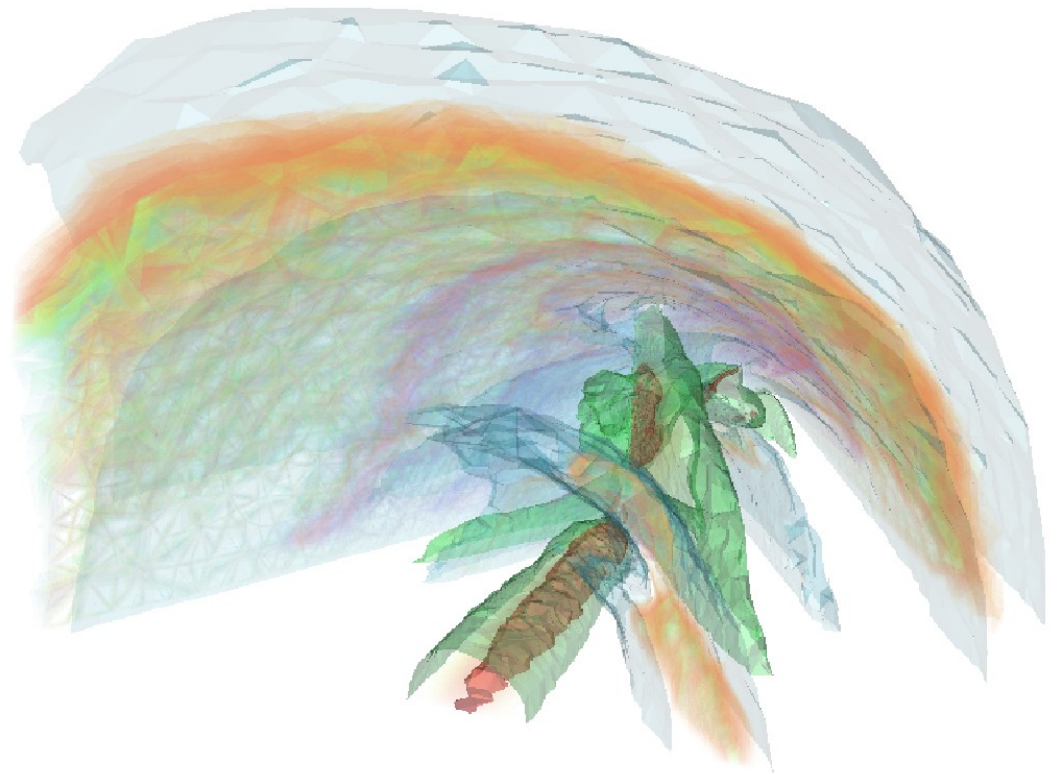
results :: renderings

1/3

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torso (1.08 M Tets)
DVR @5.6 fps



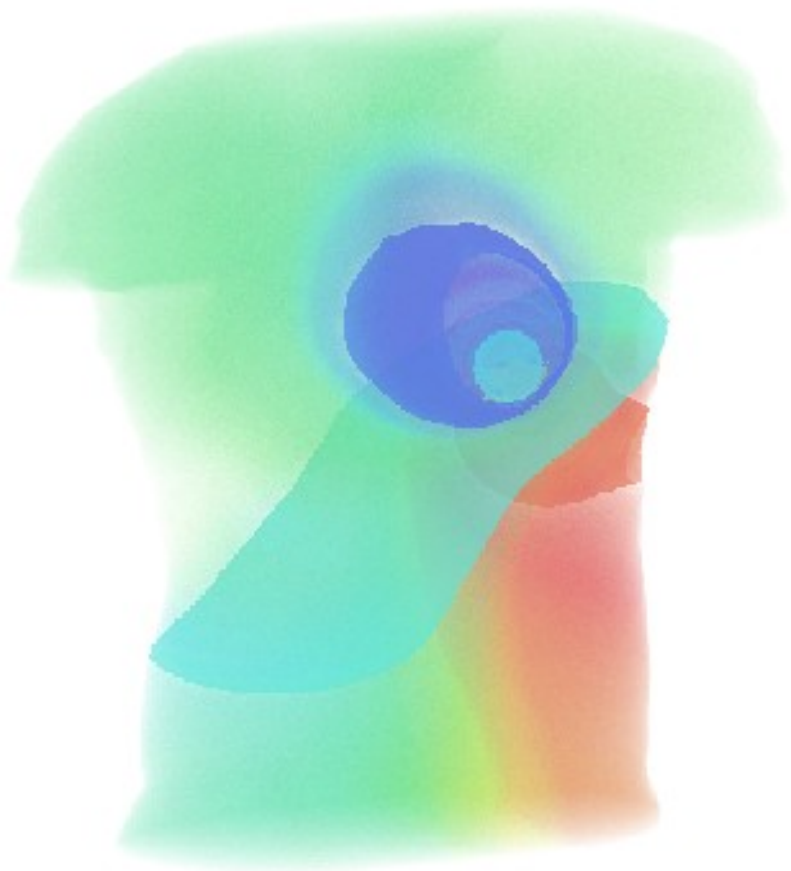
fighter (1.4 M Tets)
DVR+ISO @1.1 fps

HAPT

results :: renderings

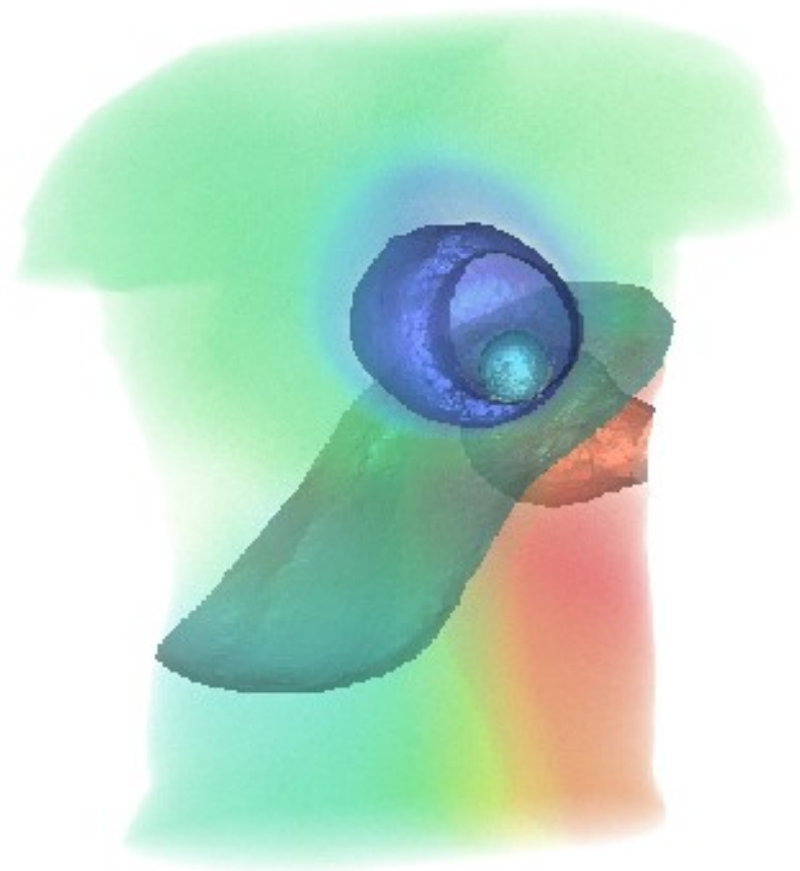
2/3

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DVR+ISO
without lighting

torso (1.08 M Tets)



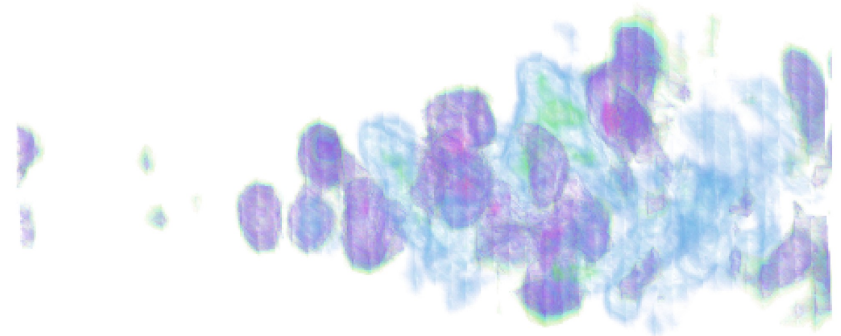
DVR+ISO
with lighting

HAPT

results :: renderings

3/3

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turbjet (1 M Tet per frame)
150 frames @17.5 fps

HAPT

Hardware-Assisted
Projected Tetrahedra *

July, 2010
André Maximo

code & publication

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<http://code.google.com/p/hapt>

* MAXIMO, A., MARROQUIM, R., FARIAS, R. “**Hardware-Assisted Projected Tetrahedra**”, in *Proceedings of Eurographics/IEEE Symposium on Visualization (Computer Graphics Forum special issue)*, v. 29, pp. 903-912, Bordeaux, France, 2010.

mesh processing

basis

symmetry

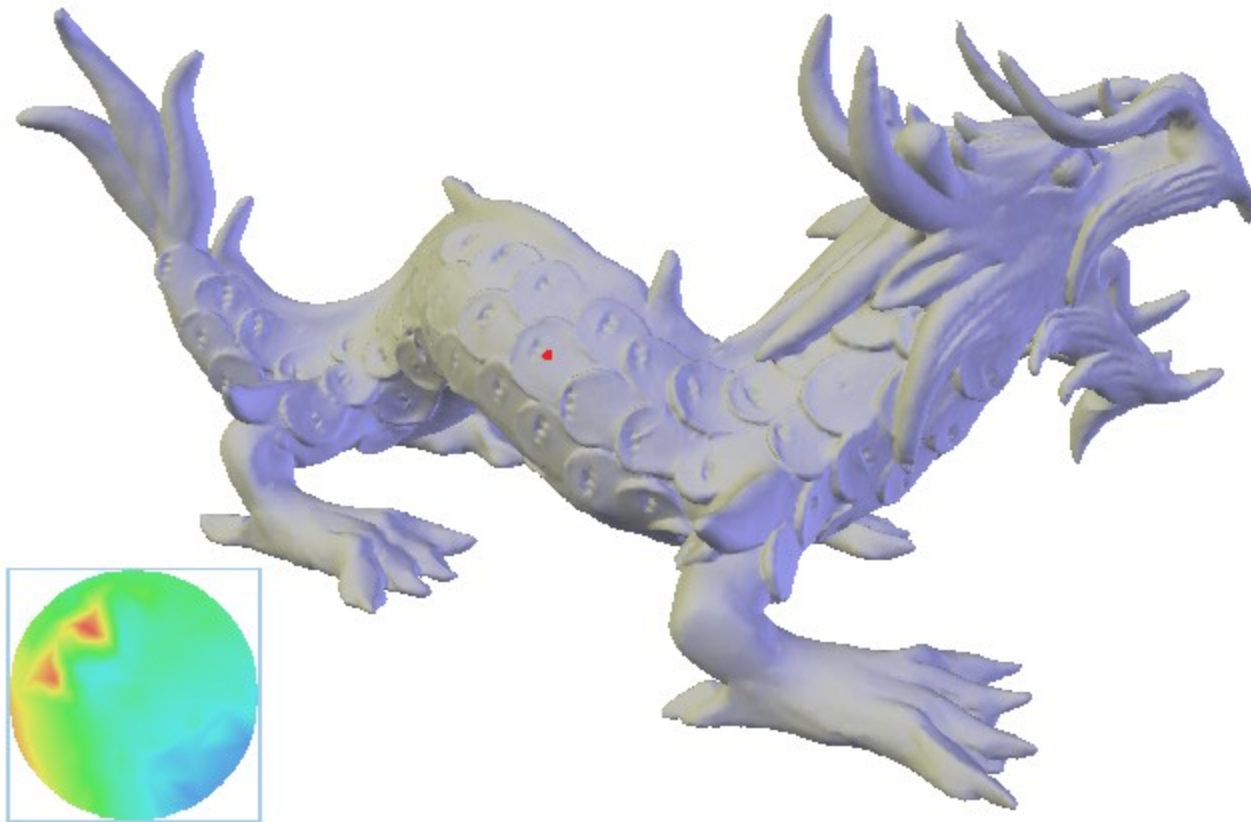
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basis

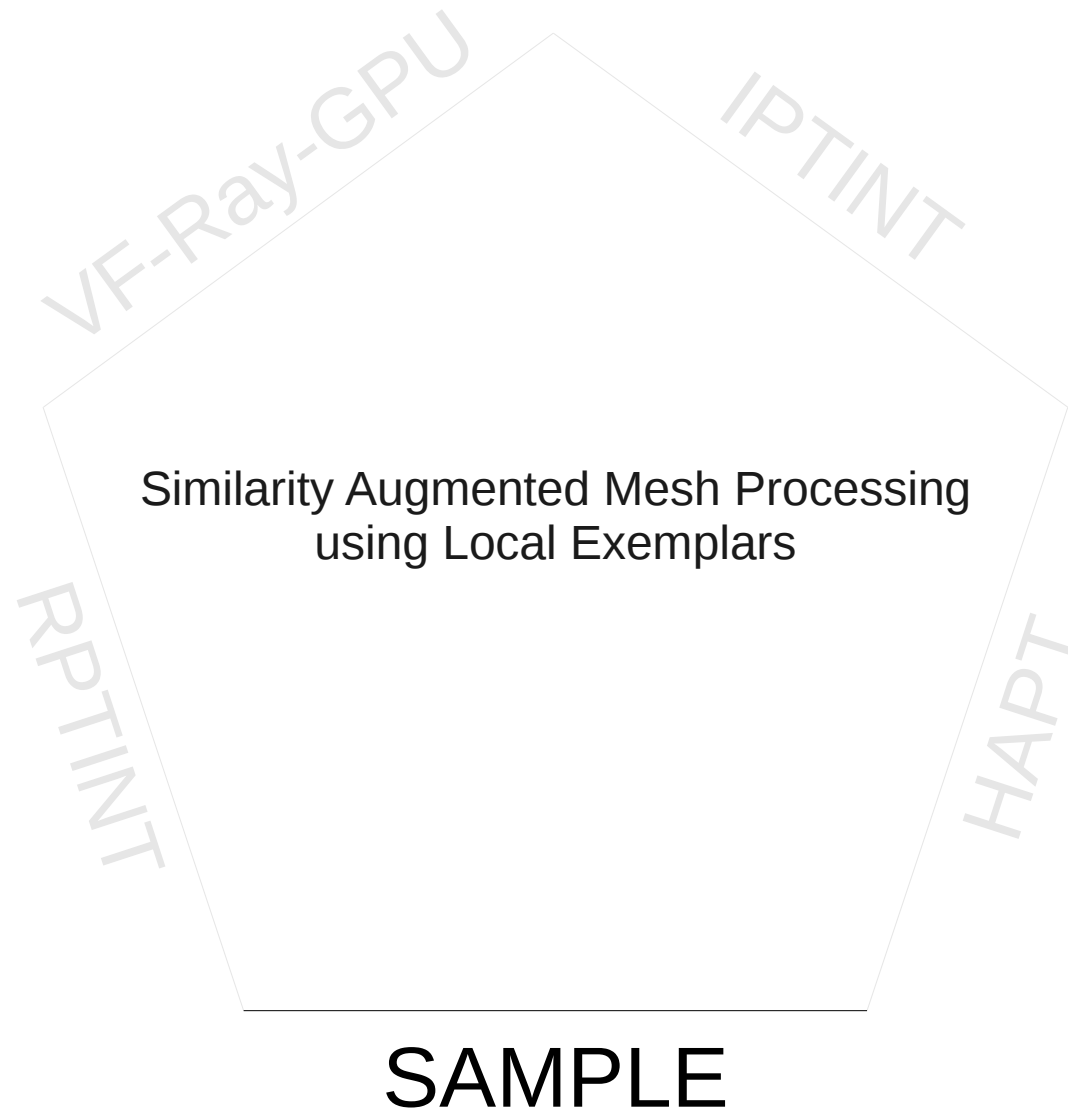
similarity descriptor

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algorithm V

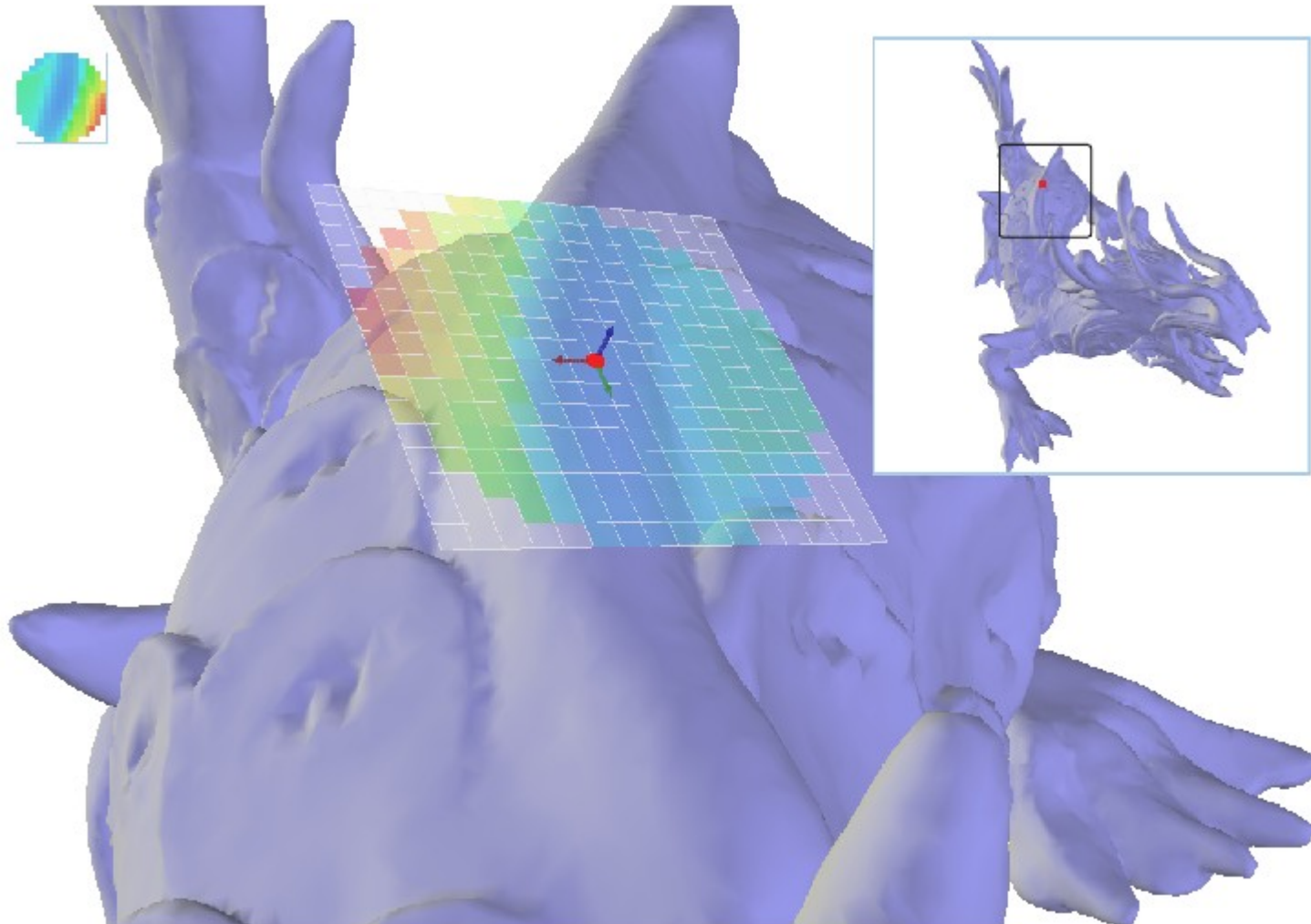
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local heightmap descriptor

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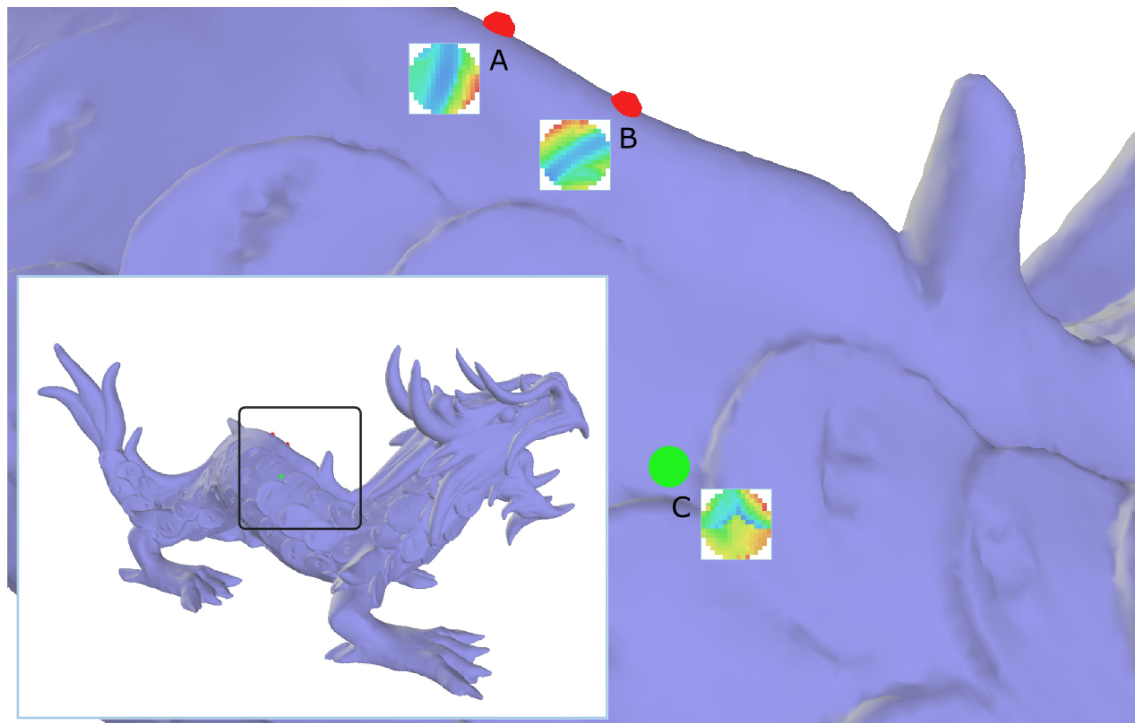


SAMPLE

Heightmaps

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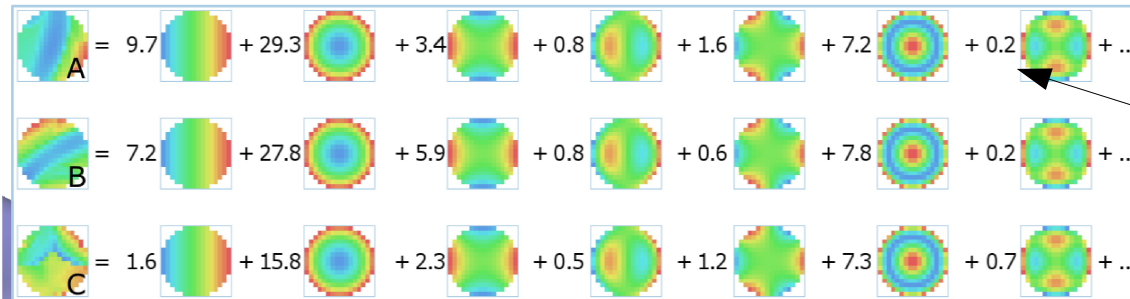
A and B
not similar



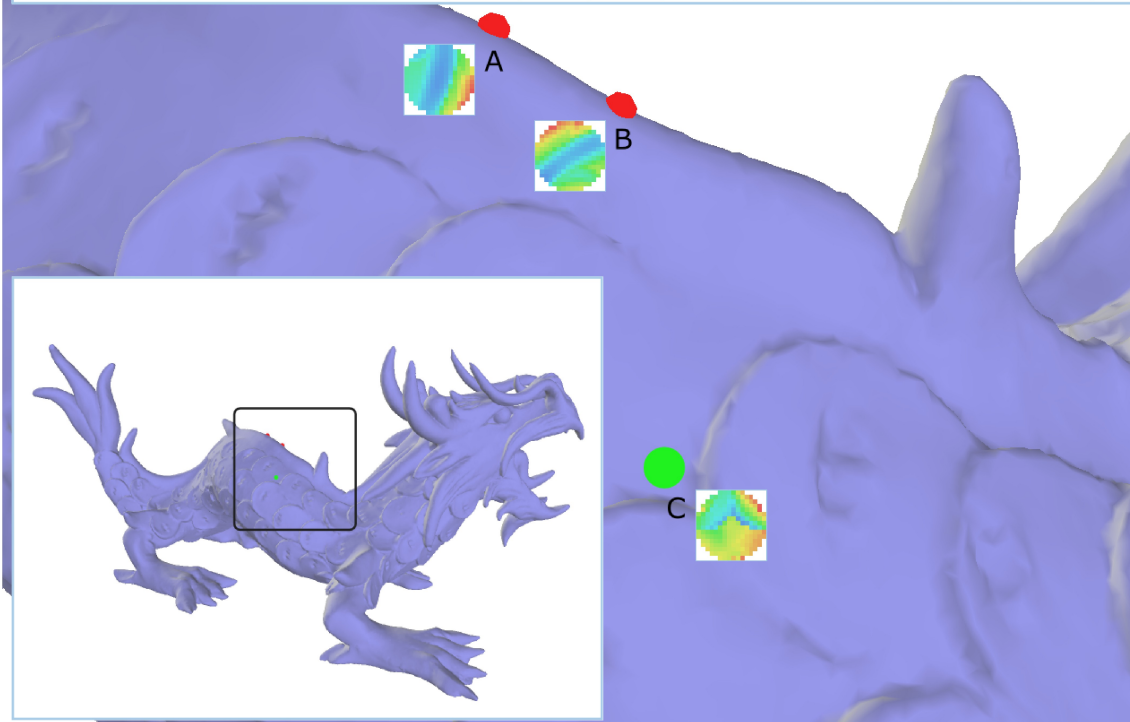
SAMPLE

Zernike expansion

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Zernike
coefficients



A and B
similar

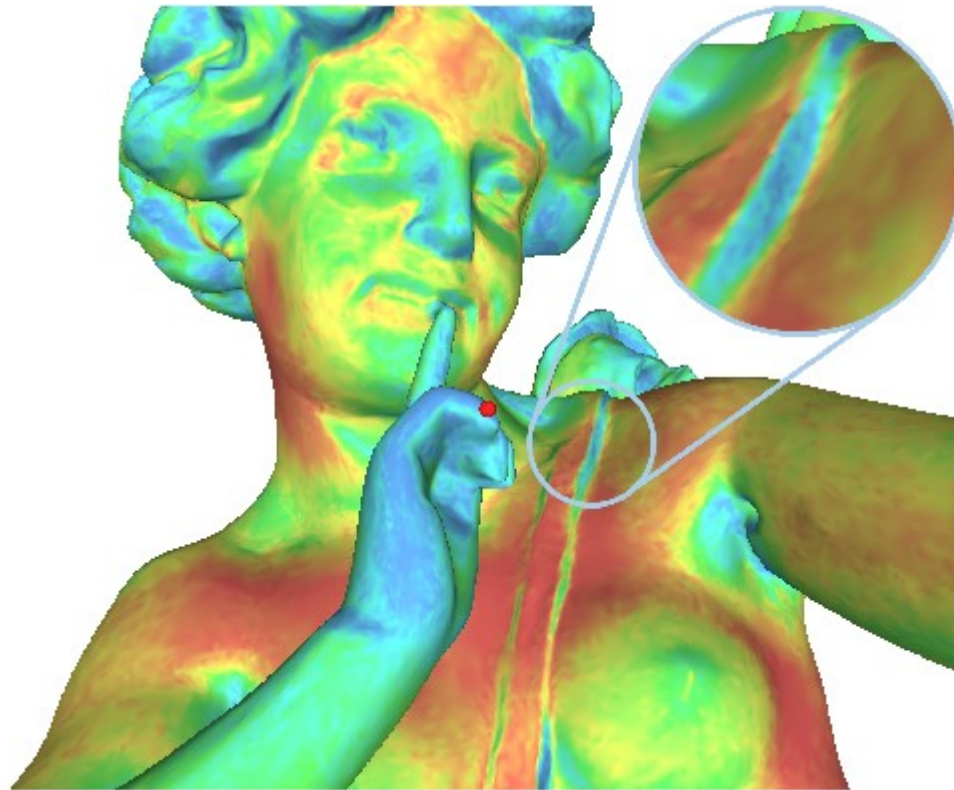
C not similar

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vertex-based similarity

heightmaps / Zernike coefficients

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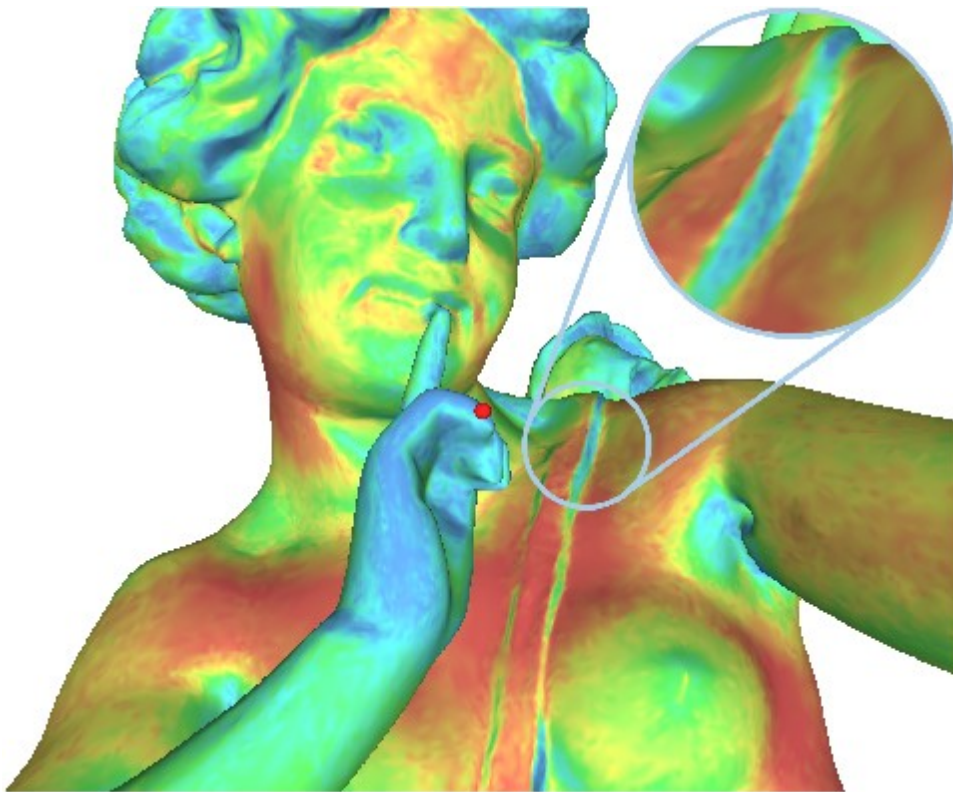
vertex-based descriptor

SAMPLE

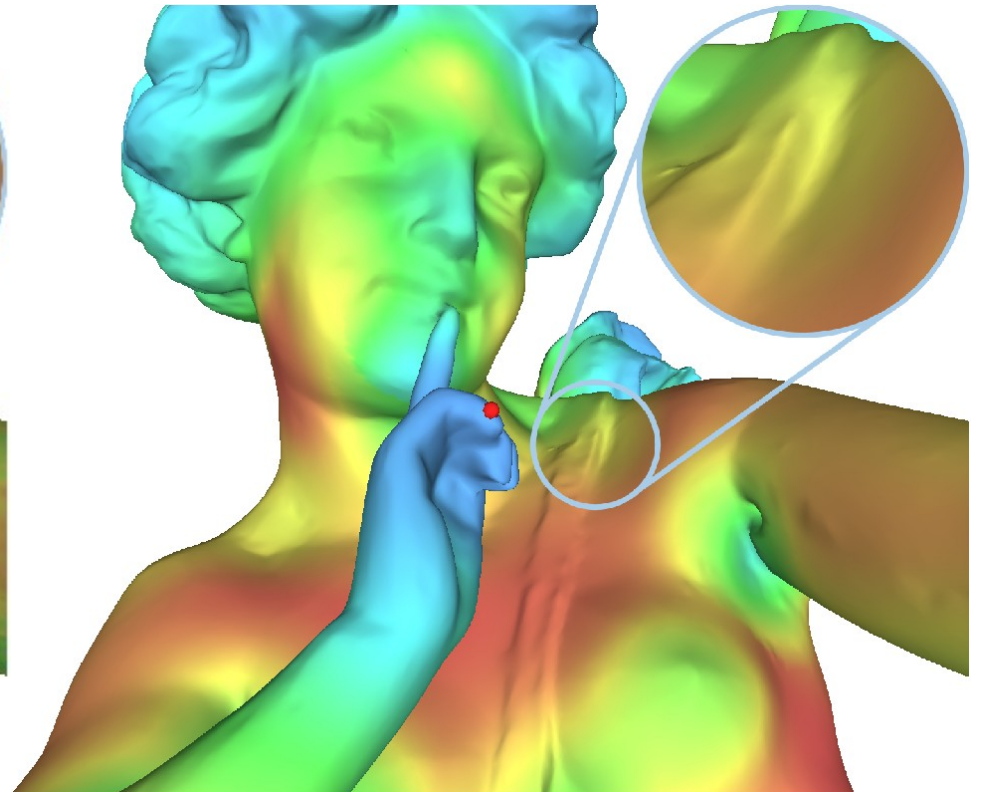
region-based similarity

heightmaps / Zernike coefficients / Gaussian weights

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vertex-based descriptor

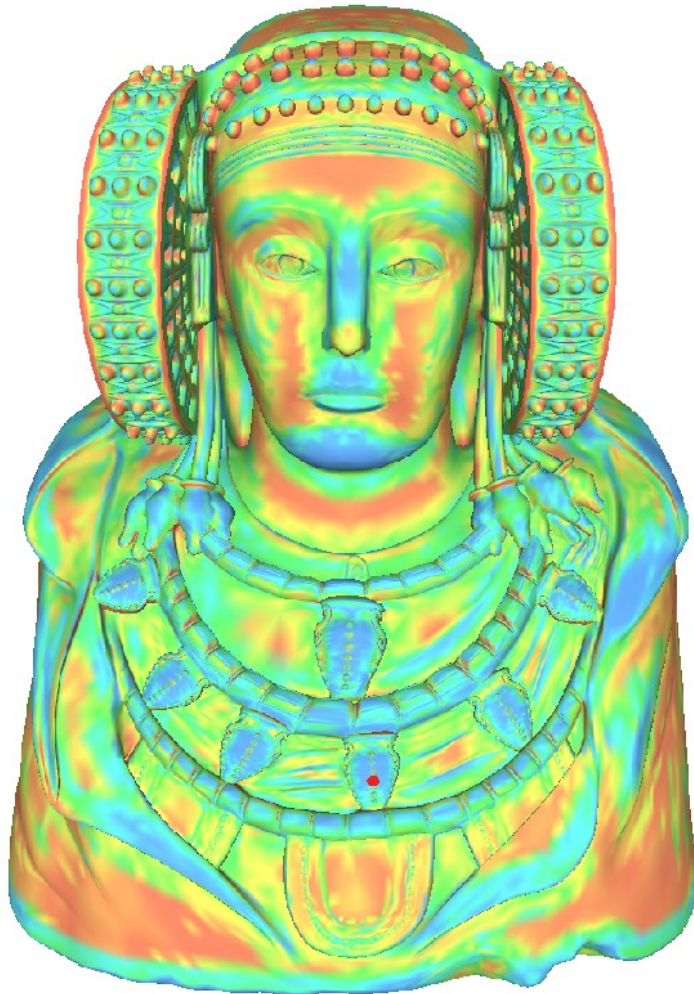


region-based descriptor

SAMPLE

region-based similarity

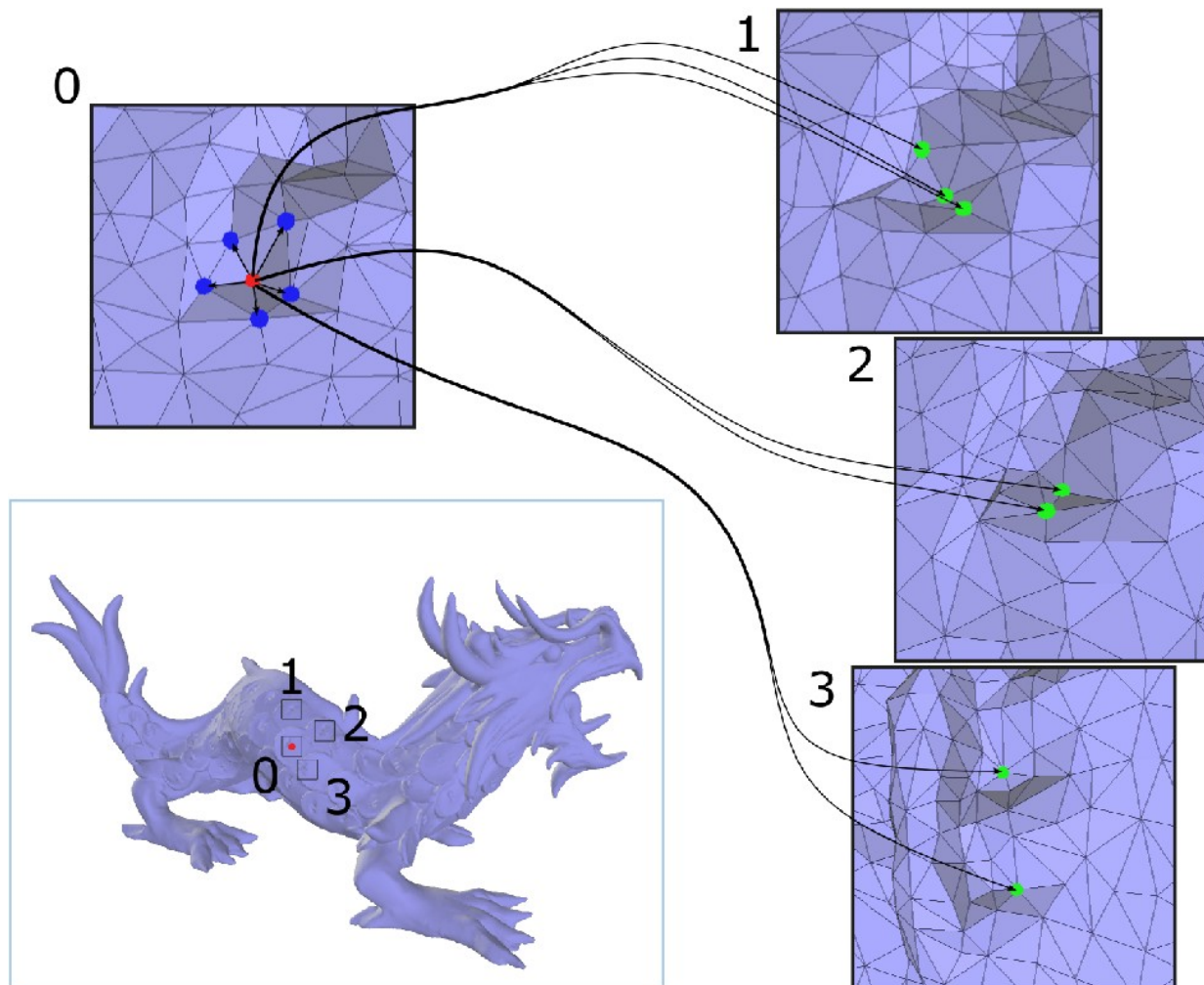
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propagating mesh processing

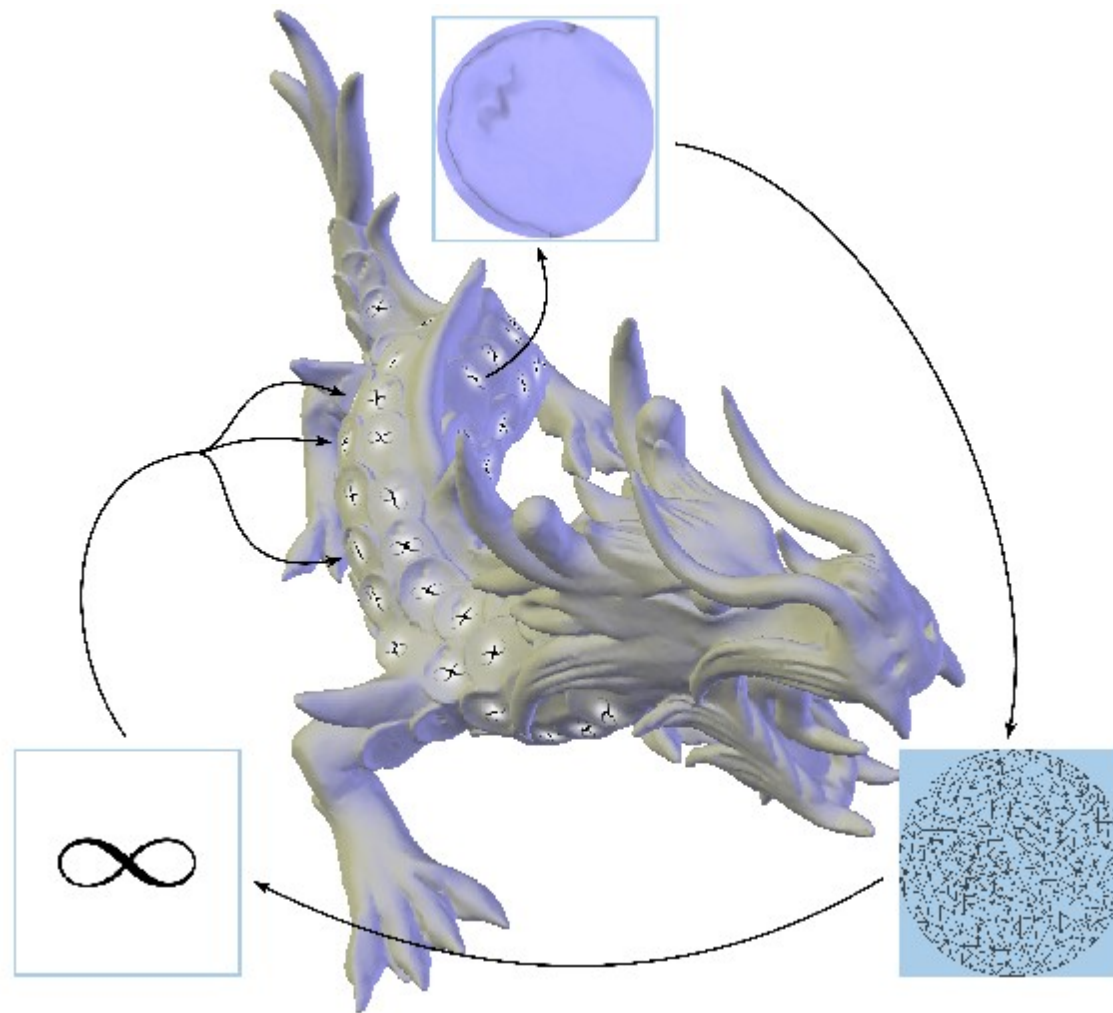
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application :: mesh parameterization

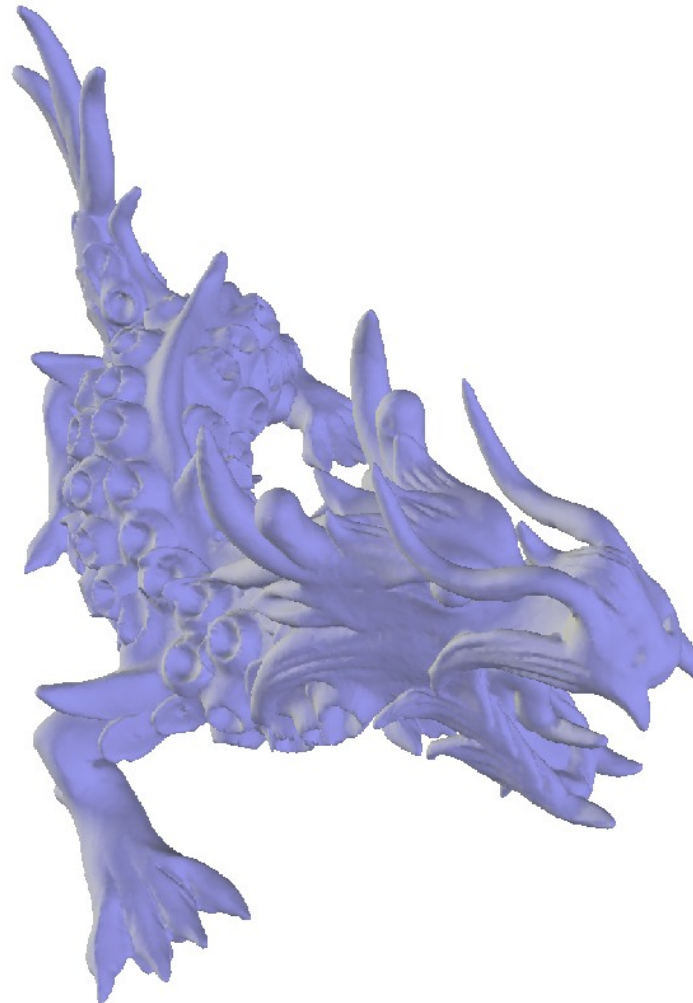
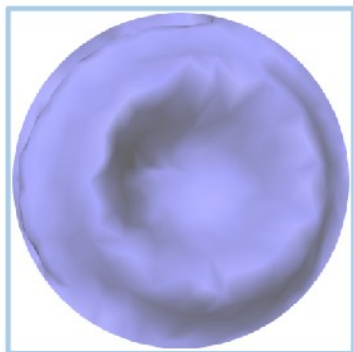
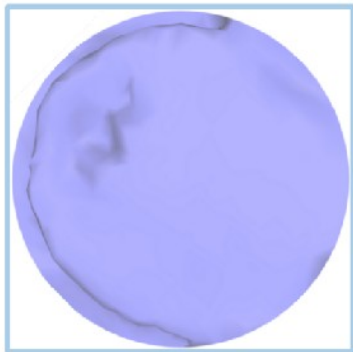
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application :: detail transfer

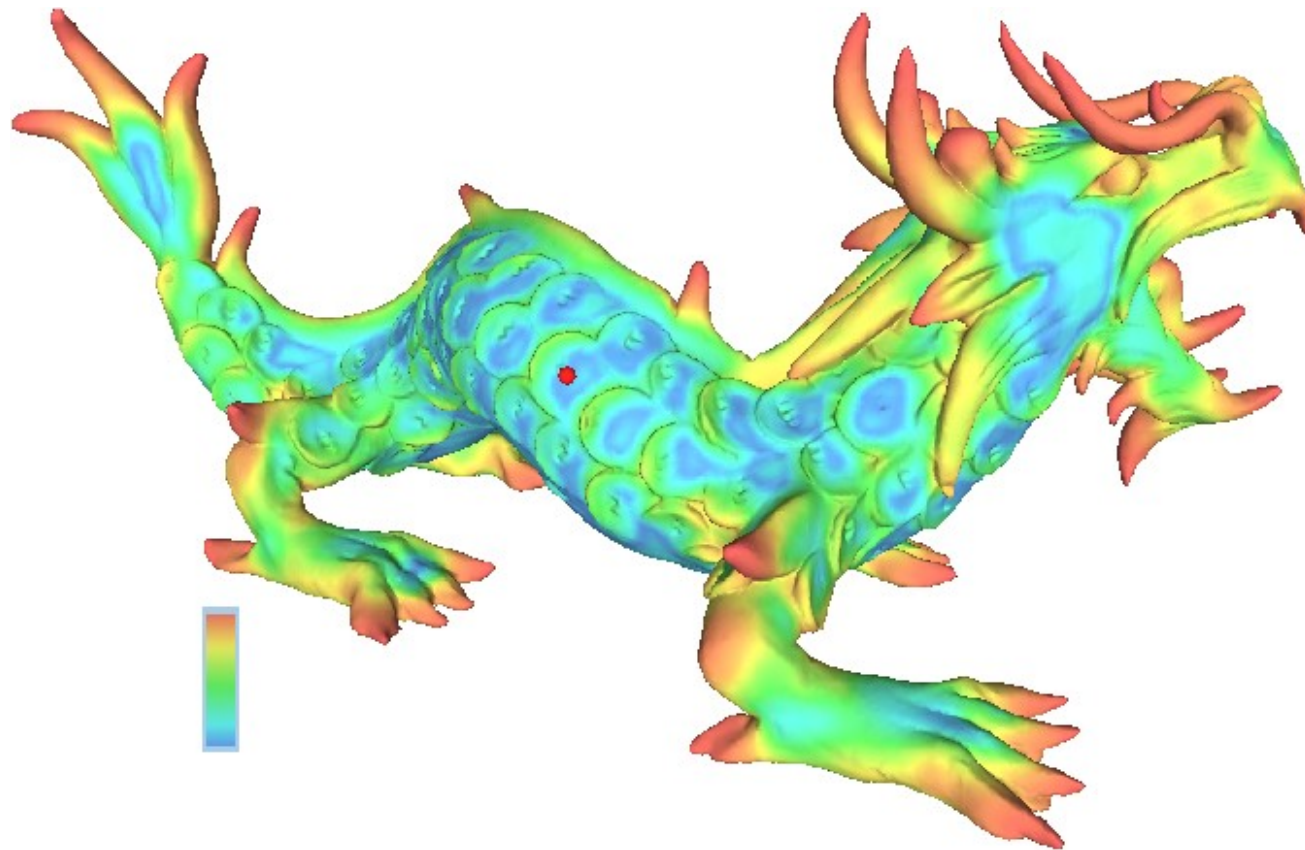
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results :: dual space

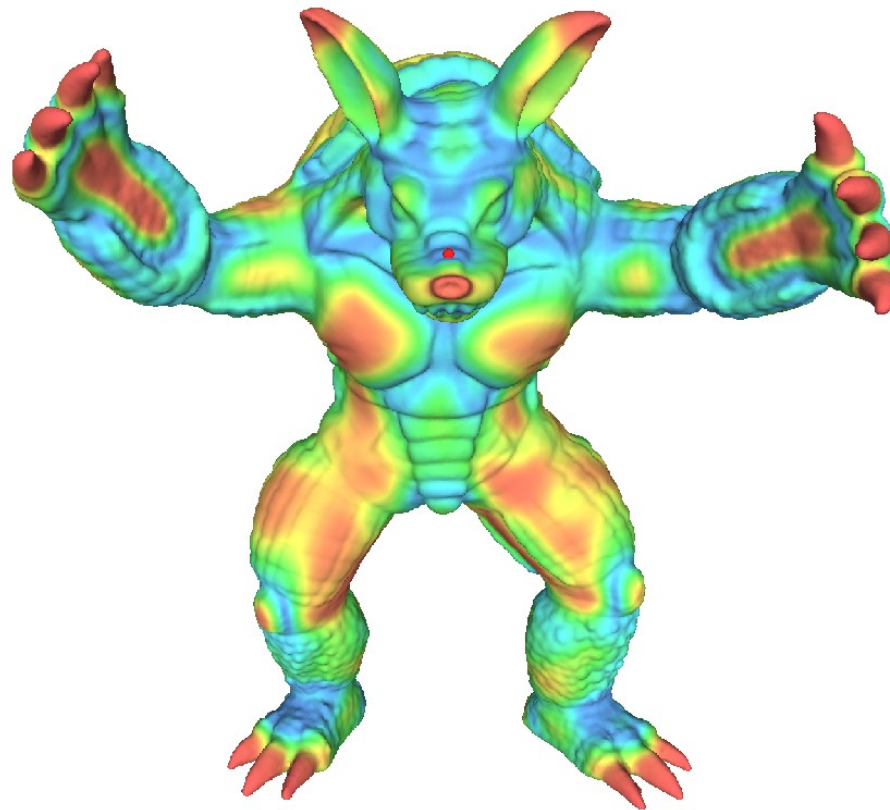
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results :: reflective symmetry

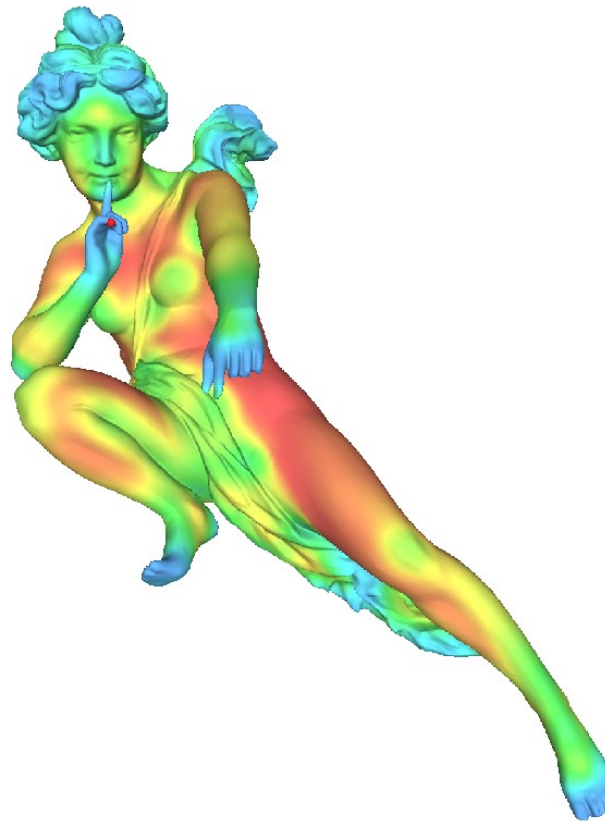
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results :: symmetries

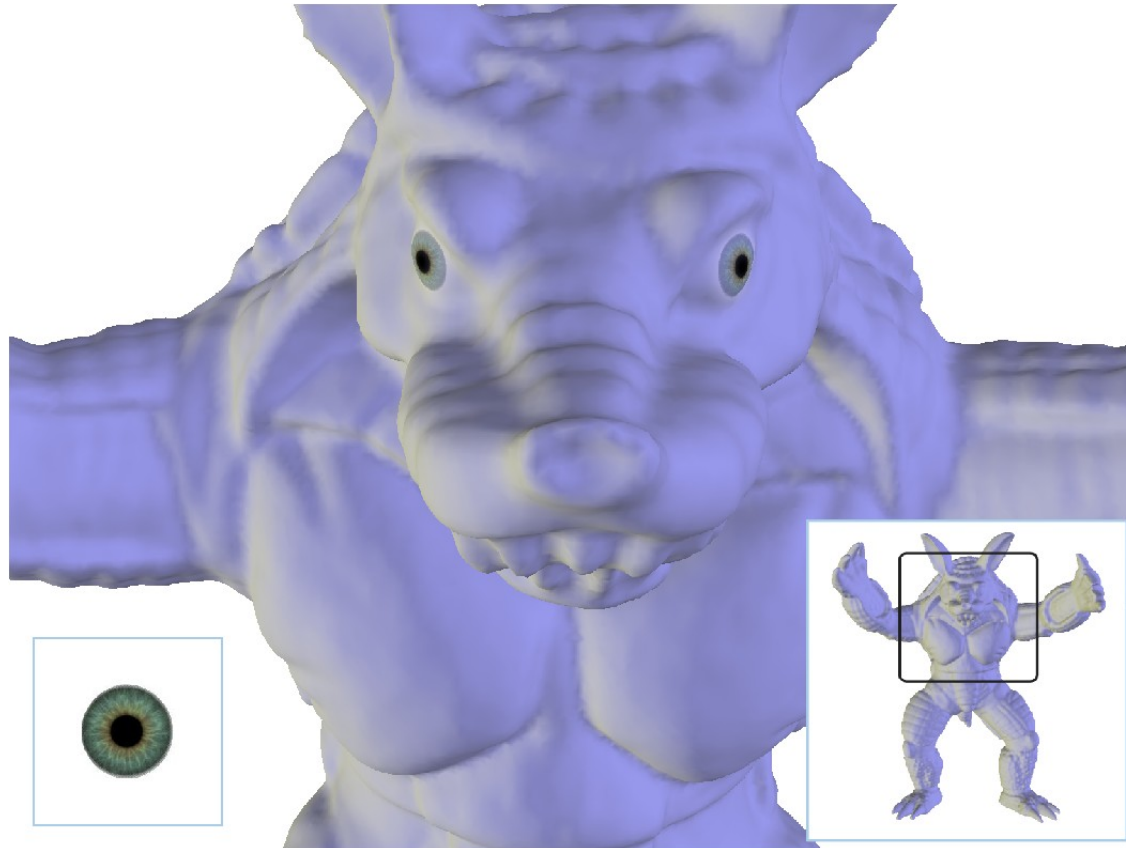
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results :: immediate neighbor

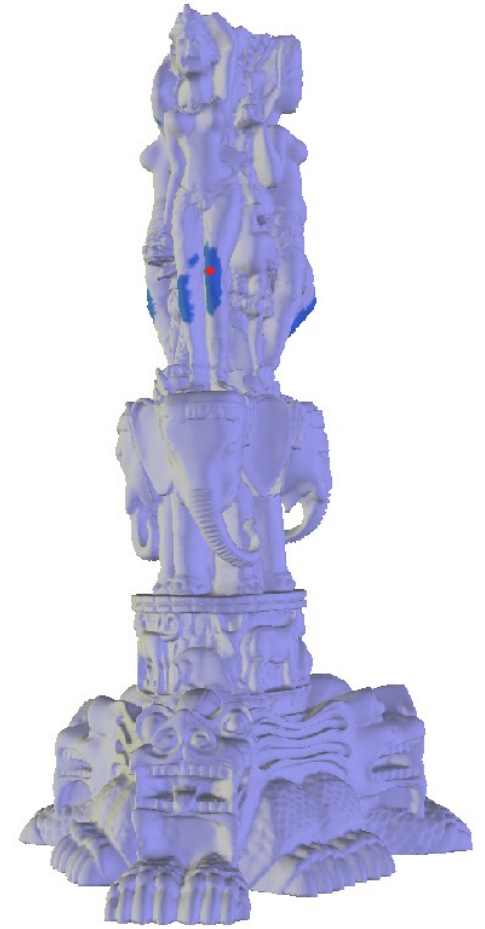
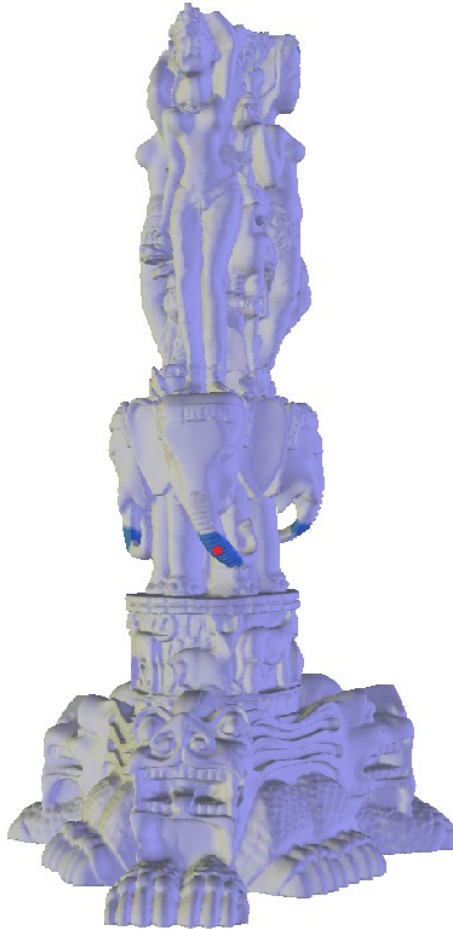
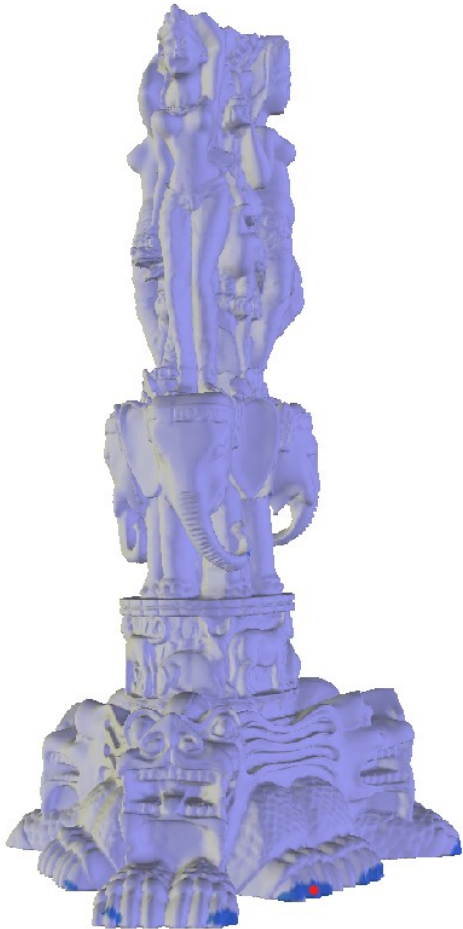
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results :: neighbors

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results :: timings

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Model	# Verts	# Faces	Heightmap	Zernike	Gaussian
Dama	106 K	207 K	3.20 min	5.53 sec	2.47 min
Asian Dragon	108 K	216 K	2.56 min	5.54 sec	1.83 min
Thai Statue	125 K	250 K	2.98 min	6.58 sec	2.07 min
Armadillo	172 K	345 K	6.12 min	9.01 sec	5.34 min
Angel	237 K	474 K	17.76 min	12.15 sec	18.45 min

~ linear #vertices
pre-computation time

less than one second
running time

SAMPLE

Similarity Augmented Mesh Processing * using Local Exemplars

publication :: submitted

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code not available yet

*

MAXIMO, A., PATRO, R., VARSHNEY, A., FARIAS, R. “A Robust and Rotationally Invariant Local Surface Descriptor with Applications to Non-local Mesh Processing”, *submitted to Graphical Models*, May, 2010.

conclusion

contributions

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Volume Rendering

Memory-Efficient Ray Casting

Regular Data Specialization

Efficient Cell Projection

Flexible Framework

Using the GPU

Mesh Processing

Local Heightmap Descriptor

Rotationally Invariant

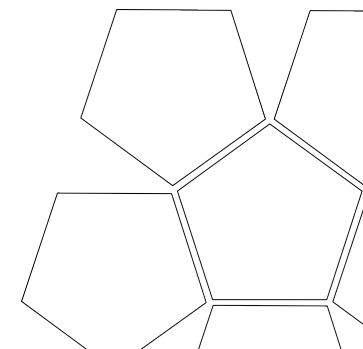
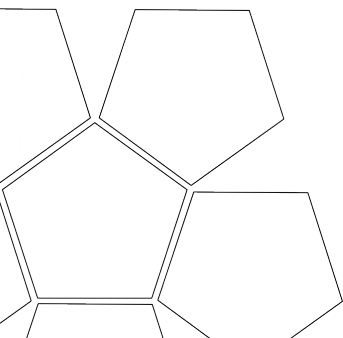
Region-based Comparison

Dual-Space Concept

Processing Propagation

reproducible research

<http://code.google.com/u/andmax>



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MAXIMO, A., RIBEIRO, S., BENTES, C., OLIVEIRA, A., FARIAS, R.
“Memory-Efficient GPU-Based Ray Casting for Unstructured Volume Rendering”, in *Proceedings of VG-PBG (Eurographics Association)*, pp. 155-162, Los Angeles, California, USA, 2008.

VF-Ray-GPU

RIBEIRO, S., MAXIMO, A., BENTES, C., OLIVEIRA, A., FARIAS, R.
“Memory-Aware and Efficient Ray-Casting Algorithm”, in *Proceedings of SIBGRAPI (IEEE Computer Society)*, pp. 147-154, Belo Horizonte, Minas Gerais, Brazil, 2007.

VF-Ray

MAXIMO, A., MARROQUIM, R., FARIAS, R., ESPERANÇA, C.
“GPU-Based Cell Projection for Large Structured Datasets”, in *Proceedings of GRAPP (INSTICC)*, pp. 312-322, Barcelona, Spain, 2007.

RPTINT

MARROQUIM, R., MAXIMO, A., FARIAS, R., ESPERANÇA, C.
“GPU-Based Cell Projection for Interactive Volume Rendering”, in *Proceedings of SIBGRAPI (IEEE Computer Society)*, pp. 147-154, Manaus, Amazonas, 2006. *Best Paper*.

PTINT

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MARROQUIM, R., MAXIMO, A., FARIAS, R., ESPERANÇA, C. **“Volume and Isosurface Rendering with GPU-Accelerated Cell Projection”**, *Computer Graphics Forum (Best Paper selection of SIBGRAPI 2006)*, v. 27, pp. 24-35, 2008.

IPTINT

MAXIMO, A., MARROQUIM, R., FARIAS, R. **“Hardware-Assisted Projected Tetrahedra”**, in *Proceedings of Eurographics/IEEE Symposium on Visualization (Computer Graphics Forum special issue)*, v. 29, pp. 903-912, Bordeaux, France, 2010.

HAPT

MAXIMO, A., PATRO, R., VARSHNEY, A., FARIAS, R. **“A Robust and Rotationally Invariant Local Surface Descriptor with Applications to Non-local Mesh Processing”**, *submitted to Graphical Models*, May, 2010.

SAMPLE

Thank You!

André Maximo



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(CNPq Sandwich) Advisor: Amitabh Varshney



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